# Trajectory attractors for 2D Navier-Stokes system and some generalizations 

Vladimir V. Chepyzhov and Mark I. Vishik

| Max-Planck-Arbeitsgruppe | Max-Planck-Institut <br> "Partielle Differentialgleichungen und <br> komplexe Analysis" |
| :--- | :--- |
| Universität Potsdam | Gottfried-Claren-Str. 26 |
| Am Neuen Palais 10 | 53225 Bonn |
| 14469 Potsdam | Germany |
| Germany |  |
|  |  |
| Institut for Information Transmission |  |
| Problems |  |
| Russian Academy of Sciences |  |
| str. Ermolovoy 19, Moscow 101447 |  |
| GSP-4 |  |
| Russia |  |

# Trajectory attractors for 2D Navier-Stokes system and some generalizations. 

Vladimir V.Chepyzhov* Mark I.Vishik *

## Introduction

We are dealing with the non-autonomous 2D Navier-Stokes system

$$
\begin{equation*}
\partial_{t} u+\nu L u+B(u)=g(x, t),(\nabla, u)=0,\left.u\right|_{\partial \Omega}=0 \tag{1}
\end{equation*}
$$

$x \in \Omega \subset \subset \mathbf{R}^{2}, t \geq 0, u=u(x, t)=\left(u^{1}, u^{2}\right) \equiv u(t), g=g(x, t)=\left(g^{1}, g^{2}\right) \equiv g(t)$. Here $L u=-P \Delta u$ is the Stokes operator, $\nu>0, B(u)=P \sum_{i=1}^{2} u_{i} \partial_{x_{i}} u ; P$ is the orthogonal projector onto the space of divergence-free vector fields (see section 1).

Consider the autonomous case: $g(x, t) \equiv g(x), g(x) \in H$ to begin with. Let for $t=0$ we be given the initial condition:

$$
\begin{equation*}
\left.u\right|_{t=0}=u_{0}(x), u_{0}(x) \in H . \tag{2}
\end{equation*}
$$

The problem (1), (2) has a unique solution $u(t), t \geq 0$, which can be represented in the form: $u(t)=S(t) u_{0}$. The family of mappings $\{S(t), t \geq 0\}$ forms a semigroup: $S\left(t_{1}\right) S\left(t_{2}\right)=S\left(t_{1}+t_{2}\right) \forall t_{1}, t_{2} \geq 0, S(0)=I d$. A set $\mathbf{A} \subset H$ is said to be an attractor of this semigroup $\{S(t)\}$ (or an attractor of the equation (1)) if $\mathbf{A}$ is compact in $H$, $\mathbf{A}$ is strictly invariant with respect to $\{S(t)\}: S(t) \mathbf{A}=\mathbf{A} \forall t \geq 0$, and $\mathbf{A}$ attracts any bounded set $B$ in $H$ :

$$
\operatorname{dist}_{H}(S(t) B, \mathbf{A}) \rightarrow 0(t \rightarrow+\infty)
$$

(see, for example, [13], [20], [2], and the references cited there).
Non-autonomous equation (1) is less studied. Let an external force $g_{0}(x, t) \equiv$ $g_{0}(t)$ in (1) depend on $t, t \geq 0$. Assume the function $g_{0}(t)$ is translation-compact in $L_{2}^{\text {loc }}\left(\mathbf{R}_{+} ; H\right) \equiv L_{2}^{\text {loc }}$ (or $g_{0}(t)$ is translation-compact in $L_{2, w}^{\text {loc }}\left(\mathbf{R}_{+} ; H\right) \equiv L_{2, w}^{\text {loc }}$ ). "This means that the family of translations $\left\{g_{0}(t+h) \mid h \geq 0\right\}$ forms a precompact set in $L_{2}^{\text {loc }}$ (respectively, in $L_{2, w}^{\text {loc }}$ ). It is easy to formulate the translation-compact criterions

[^0](see section 1). For example, a function $g_{0}(t)$ is translation-compact in $L_{2, \psi}^{\text {loc }}$ if and only if the following norm is bounded:
\[

$$
\begin{equation*}
\left\|g_{0}\right\|_{a}^{2}=\sup _{t \geq 0} \int_{t}^{t+1}\left|g_{0}(s)\right|^{2} d s<+\infty \tag{3}
\end{equation*}
$$

\]

By $\mathcal{H}_{+}\left(g_{0}\right)$ denote a hull of the function $g_{0}$ in the space $L_{2, \omega}^{\text {loc }}$, i.e.

$$
\mathcal{H}_{+}\left(g_{0}\right)=[\{g(t+h) \mid h \geq 0\}]_{L_{2, \omega}^{L \infty}}
$$

where $[.]_{X}$ means the closure in a topological space $X$.
Consider the family of equations (1) with external forces $g(t) \in \mathcal{H}_{+}\left(g_{0}\right) \equiv \Sigma$. Let $\left\{U_{g}(t, \tau) \mid t \geq \tau \geq 0\right\}$ be the family of operators (called a process in $H$ ) such that $U_{g}(t, \tau) u_{\tau}=u_{g}(t), t \geq \tau \geq 0$, where $u_{g}(t)$ is a solution of equation (1) with the external force $g(t)$ and with the initial condition $\left.u\right|_{t=\tau}=u_{\tau}(x), u_{\tau}(x) \in H$. Evidently, $U_{g}(t, \tau): E \rightarrow E, U_{g}(t, \theta) U_{g}(\theta, \tau)=U_{g}(t, \tau), U_{g}(\tau, \tau)=I d \forall t \geq \theta \geq$ $\tau \geq 0$. Consider the family of processes $\left\{U_{g}(t, \tau) \mid g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$ corresponding to the family of equations (1) with external forces $g \in \mathcal{H}_{+}\left(g_{0}\right)$. (To compare with autonomous case, $g_{0}(t) \equiv g_{0}, \mathcal{H}_{+}\left(g_{0}\right)=\left\{g_{0}\right\}, U_{g}(t, \tau)=S(t-\tau)$ ). It was proved that the family of processes $\left\{U_{g}(t, \tau) \mid g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$ possesses a uniform (w.r.t. $g \in \Sigma$ ) attractor $\mathbf{A}_{\boldsymbol{\Sigma}}$ in $H$. More precisely, the set $\mathbf{A}_{\boldsymbol{\Sigma}}$ is compact in $H, \mathbf{A}_{\boldsymbol{\Sigma}}$ attracts any bounded set $B$ in $H$ uniformly w.r.t. $g \in \Sigma$ :

$$
\sup _{g \in \Sigma} \operatorname{dist}_{H}\left(U_{g}(t, \tau) B, \mathbf{A}_{\Sigma}\right) \rightarrow 0(t \rightarrow+\infty) \forall \tau \geq 0
$$

and $\mathbf{A}_{\boldsymbol{\Sigma}}$ is a minimal compact, uniformly attracting set (see [9], [6], and [4] dealing with more restrictive case). In [6], [4] the structure and the properties of the uniform attractor for (1) was also studied.

In the present work we introduce and we study a trajectory attractor $\mathcal{A}_{\Sigma}$ for equation (1). We point out at once that a trajectory attractor $\mathcal{A}_{\Sigma}$ is a compact set in the corresponding trajectory space of equations (1) that consists of their solutions $u_{g}(t), t \geq 0$, considering as a whole as functions of $t$ with values in $H$. In the previous considerations, an attractor $\mathbf{A}_{\Sigma}$ was a compact subset of points in $H$.

Consider as before a fixed external force $g_{0}(t)$ being a translation-compact function in $L_{2}^{\text {loc }}$ (or in $L_{2, w}^{\text {loc }}$ ) and let $\mathcal{H}_{+}\left(g_{0}\right) \equiv \Sigma$ be a hull of $g_{0}$ in $L_{2}^{\text {loc. }}$. (The case when $g_{0}(t)$ is translation-compact in $L_{2, w}^{\text {loc }}$ is studied in section 1). Let $H^{\mathrm{r}}\left(Q_{t_{1}, t_{2}}\right), \mathrm{r}=$ $(2,2,1)$ be the Nicolskiy space in $\left.Q_{t_{1}, t_{2}}=\Omega \times\right] t_{1}, t_{2}$ [(see [3]) of functions $\varphi(x, t)=$ $\left.\varphi(t)=\left(\varphi^{1} \varphi^{2}\right) \in H, t \in\right] t_{1}, t_{2}[$ with a finite norm

$$
\|\varphi\|_{H}^{2} \mathbf{r}_{\left(Q_{t_{1}, t_{2}}\right)}=\int_{Q_{t_{1}, t_{2}}}\left(\sum_{|\alpha| \leq 2}\left|\partial_{x}^{\alpha} \varphi(x, t)\right|^{2}+\left|\partial_{t} \varphi(x, t)\right|^{2}\right) d x d t,\left.\varphi\right|_{\partial \Omega}=0 .
$$

To any external force $g(t) \in \mathcal{H}_{+}\left(g_{0}\right)$ there corresponds the trajectory space $\mathcal{K}_{g}^{+}$. The space $\mathcal{K}_{g}^{+}$is the union of all solutions $u(t)=u_{g}(t), t \geq 0$, of equation (1)
in the space $\left.H^{\mathbf{r}, l o c}\left(Q_{+}\right) \equiv H^{\mathbf{r}, l o c}, Q_{+}=\Omega \times\right] 0,+\infty$ [, (i.e. $u(t) \in H^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right)$ for any $] t_{1}, t_{2}\left[\subset \mathbf{R}_{+}\right)$. Let $\mathcal{K}^{+}=\bigcup_{g \in \mathcal{H}_{+}(g o)} \mathcal{K}_{g}^{+}$be a union of all $\mathcal{K}_{g}^{+}$. The translation semigroup $\{T(h) \mid h \geq 0\}$ acts on $H^{\mathrm{r}}$,loc :

$$
T(h) \varphi(t)=\varphi(t+h), h \geq 0
$$

Evidently, $T(h) u_{g}(t)=u_{g}(t+h)=u_{T(h) g}(t) \in \mathcal{K}_{T(h) g}^{+}$. Therefore,

$$
\begin{equation*}
T(h) \mathcal{K}^{+} \subseteq \mathcal{K}^{+} \forall h \geq 0 \tag{4}
\end{equation*}
$$

(the inclusion may be strict, see section 1). It is proved that $\mathcal{K}^{+}$is closed in $H^{\mathbf{r}, l o c}$. It is clear that the semigroup $\{T(h)\}$ is continuous on $H^{\mathbf{r}, l o c}$. Denote by $H^{\mathbf{r}, a}\left(Q_{+}\right) \equiv$ $H^{\mathbf{r}, a}$ a subset of $H^{\mathbf{r}, l o c}$ of functions $\varphi(t), t \geq 0$, having a finite norm

$$
\|\varphi\|_{H}^{2} \mathrm{r.a}=\sum_{|\alpha| \leq 2}\left\|\partial_{x}^{\alpha} \varphi\right\|_{a}^{2}+\left\|\partial_{t} \varphi\right\|_{a}^{2}<+\infty,
$$

where $\|\cdot\|_{a}^{2}$ is defined in (3).
A trajectory attractor of the translation semigroup $\{T(h)\}$ acting on $\mathcal{K}^{+}$is a set $\mathcal{A}_{\Sigma} \subseteq \mathcal{K}^{+}$such that $\mathcal{A}_{\Sigma}$ is a set, compact in $H^{\mathbf{r}, l o c}$, bounded in $H^{\mathbf{r}, a}$, invariant with respect to $\{T(h)\}: T(h) \mathcal{A}_{\Sigma}=\mathcal{A}_{\Sigma} \forall h \geq 0$, and satisfying the following attracting property: for any set $B \subset \mathcal{K}^{+}$, bounded in $H^{\mathbf{r}, a}$, and for any $\left[t_{1}, t_{2}\right] \subset \mathbf{R}_{+}$the set $T(h) B$ tends to $\mathcal{A}_{\Sigma}$ in the strong topology of the space $H^{\mathbf{r}}\left(Q_{t_{1}, t_{z}}\right)$ i.e.

$$
\begin{equation*}
\operatorname{dist}_{H} \mathbf{r}\left(Q_{1_{1}, t_{2}}\right)\left(T(h) B, \mathcal{A}_{\mathbf{\Sigma}}\right) \rightarrow 0(h \rightarrow+\infty) . \tag{5}
\end{equation*}
$$

In section 2 , we construct the trajectory attractor $\mathcal{A}_{\boldsymbol{\Sigma}}$ of the translation semigroup $\{T(h)\}$ acting on $\mathcal{K}^{+}$. Section 1 deals with the trajectory attractor $\mathcal{A}_{\Sigma}$ in "weak" topology $H_{w}^{\text {r,loc }}\left(Q_{+}\right)$under the assumption that $g_{0}(t)$ is translation-compact in $L_{2, w}^{\text {loc }}$ only. In this case $T(h) B$ tends to $\mathcal{A}_{\Sigma}$ in the weak topology of the space $H^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right)$ for any $\left[t_{1}, t_{2}\right] \subset \mathbf{R}_{+}$. In section 3 , the structure of the trajectory attractor $\mathcal{A}_{\Sigma}$ is described.

Trajectory attractors have been constructed for various equations and systems of PDE for which the corresponding Cauchy problem has non-unique solution or for which the uniqueness theorem is not proved yet (see [7], [8], [9], [10], and [5]).

In section 4 we construct the trajectory attractor for 3D Navier-Stokes system; the structure and some properties of the trajectory attractor are given as well. In particular, the trajectory attractor $\mathcal{A}_{\Sigma}$ is stable with respect to a small perturbation of the external force $g_{0}(x, t)$; the trajectory attractor $\mathcal{A}_{\Sigma}^{(N)}$ of the Faedo-Galerkin approximation system of order $N$ tends to $\mathcal{A}_{\Sigma}$ as $N \rightarrow+\infty$ in the corresponding topology. Some of other properties turns out to be unexpected.

## 1 Trajectory attractor for 2D N.-S. system with translation-compact external force in $L_{2, w}^{l o c}$.

We consider the Navier-Stokes system in a bounded domain $\Omega \subset \subset \mathbf{R}^{2}$. Excluding the pressure, the system can be written in the form:

$$
\begin{equation*}
\partial_{t} u+\nu L u+B(u)=g(x, t),(\nabla, u)=0,\left.u\right|_{\partial \Omega}=0, x \in \Omega, t \geq 0 \tag{1.1}
\end{equation*}
$$

where, $x=\left(x_{1}, x_{2}\right), u=u(x, t)=\left(u^{1}, u^{2}\right), g=g(x, t)=\left(g^{1}, g^{2}\right) . L$ is the Stokes operator: $L u=-P \Delta u ; B(u)=B(u, u), B(u, v)=P(u, \nabla) v=P \sum_{i=1}^{2} u_{i} \partial_{x_{i}} v, \nu>0$ (see [16], [15], [19], [21]). By $H, V$, and $H_{2}$ denote respectively the closure in $\left(L_{2}(\Omega)\right)^{2},\left(H^{1}(\Omega)\right)^{2}$, and $\left(H^{2}(\Omega)\right)^{2}$ of the set $\mathcal{V}_{0}=\left\{v \mid v \in\left(C_{0}^{\infty}(\Omega)\right)^{2},(\nabla, v)=\right.$ $0\}$. $P$ denotes the orthogonal projector in $\left(L_{2}(\Omega)\right)^{2}$ onto the Hilbert space $H$. The scalar products in $H$ and in $V$ are $(u, v)=\int_{\Omega}(u(x), v(x)) d x$ and $((u, v))=$ $\langle L u, v\rangle=\int_{\Omega}(\nabla u(x), \nabla v(x)) d x$ and the norms are respectively $|u|=(u, u)^{1 / 2}$ and $\|u\|=\langle L u, u\rangle^{1 / 2}$. The norm in $H_{2}$ is $\|\cdot\|_{2}$.

To describe an external force $g(x, s)$ in (1.1) consider the topological space $L_{2, w}^{l o c}\left(\mathbf{R}_{+}, H\right)$. By the definition, the space $L_{2, w}^{l o c}\left(\mathbf{R}_{+}, H\right)=L_{2, w}^{l o c}$ is $L_{2}^{\text {loc }}\left(\mathbf{R}_{+}, H\right)=L_{2}^{\text {loc }}$ endowed with the following local weak convergence topology. The sequence $\left\{g_{n}(s)\right\}$ converges to $g(s)$ as $n \rightarrow \infty$ in $L_{2, w}^{\text {loc }}$ whenever $\int_{t_{1}}^{t_{2}}\left(g_{n}(s)-g(s), v(s)\right) d s \rightarrow 0(n \rightarrow$ $\infty$ ) for any $\left[t_{1}, t_{2}\right] \subseteq \mathbf{R}_{+}$and any $v(s) \in L_{2}\left(t_{1}, t_{2} ; H\right)$.

Let we are given some fixed external force $g_{0}(s) \in L_{2}^{\text {loc }}$. Assume $g_{0}(s)$ is translationcompact (tr.-c.) in $L_{2, w}^{\text {loc }}$, i.e. the set $\left\{g_{0}(s+h) \mid h \in \mathbf{R}_{+}\right\}$is precompact in $L_{2, w}^{\text {loc }}$. This condition is valid if and only if

$$
\begin{equation*}
\left\|g_{0}\right\|_{L_{2}^{2}\left(\mathbf{R}_{+} ; H\right)}^{2}=\left\|g_{0}\right\|_{a}^{2}=\sup _{t \geq 0} \int_{t}^{t+1}\left|g_{0}(s)\right|^{2} d s<+\infty \tag{1.2}
\end{equation*}
$$

(see $[6]$ ). By $\mathcal{H}_{+}\left(g_{0}\right)$ denote the hull of a function $g_{0}(s)$ in $L_{2, w}^{\text {loc }}: \mathcal{H}_{+}\left(g_{0}\right)=\left[\left\{g_{0}(s+\right.\right.$ $\left.\left.h) \mid h \in \mathbf{R}_{+}\right\}\right\}_{L_{2, w}^{l o s}}$. Here $[.\}_{L_{2, w}^{l o c}}$ means the closure in $L_{2, w}^{\text {loc }}$. It can be shown that the set $\mathcal{H}_{+}\left(g_{0}\right)$ being a topological subspace of $L_{2, \omega}^{l o c}$ is metrizable and the corresponding metric space is complete. Moreower, any function $g(s) \in \mathcal{H}_{+}\left(g_{0}\right)$ is tr.-c. in $L_{2, w}^{l o c}$, $\mathcal{H}_{+}(g) \subseteq \mathcal{H}_{+}\left(g_{0}\right)$, and $\|g\|_{a} \leq\left\|g_{0}\right\|_{a}$.

The translation semigroup $\{T(t) \mid t \geq 0\}=\{T(t)\}$ acts on $\mathcal{H}_{+}\left(g_{0}\right): T(t) g(s)=$ $g(s+t)$. Evidently, $T(t)$ is continuous in $L_{2, w}^{l o c}$ and $T(t) \mathcal{H}_{+}\left(g_{0}\right) \subseteq \mathcal{H}_{+}\left(g_{0}\right) \forall t \geq 0$.

We shall study the family of equations (1.1) with various external forces $g(., s) \in$ $\mathcal{H}_{+}\left(g_{0}\right)$

By $Q_{t_{1}, t_{2}}$ denote the cylinder $\Omega \times\left[t_{1}, t_{2}\right]$, where $\left[t_{1}, t_{2}\right] \subset \mathbf{R}_{+}$.
Consider the space $H^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right), \mathbf{r}=(2,2,1)$ (see [3]), $H^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right)=L_{2}\left(t_{1}, t_{2} ; H_{2}\right) \cap$ $\left\{\partial_{t} v \in L_{2}\left(t_{1}, t_{2} ; H\right)\right\}$. The norm in $H^{\mathrm{r}}\left(Q_{t_{1}, t_{2}}\right)$ is

$$
\begin{equation*}
\|v\|_{H\left(Q_{t_{1}, t_{2}}\right)}^{2}=\int_{t_{1}}^{t_{2}}\left(\|v(s)\|_{2}^{2}+\left|\partial_{t} v(s)\right|^{2}\right) d s \tag{1.3}
\end{equation*}
$$

Let us recall the existence and uniqueness theorem.

Theorem 1.1 Let $g(s) \in L_{2}\left(t_{1}, t_{2} ; H\right)$ and $u_{0} \in V$. Then there exists a unique solution $u(s)$ of equation (1.1) belonging to the space $H^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right)$ such that $u\left(t_{1}\right)=u_{0}$. Moreover, $u(s) \in C\left(\left[t_{1}, t_{2}\right], V\right)$.

This theorem is a variant of the classical result (see [14], [15], [16], [19], [2]). The proof uses the Faedo-Galerkin approximations method.

We shall study equation (1.1) in the semicylinder $Q_{+}=\Omega \times \mathbf{R}_{+}$, where $g(., s) \in$ $\mathcal{H}_{+}\left(g_{0}\right)$.

Consider the space $H^{\mathrm{r}, l o c}\left(Q_{+}\right)=L_{2}^{l o c}\left(\mathbf{R}_{+} ; H_{2}\right) \cap\left\{\partial_{t} v \in L_{2}^{\text {loc }}\left(\mathbf{R}_{+} ; H\right)\right\}$, i.e. $v(s) \in$ $H^{\mathbf{r}, l o c}\left(Q_{+}\right)$if $\left\|\Pi_{t_{1}, t_{2}} v\right\|_{H^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right)}^{2}<+\infty$ for any $\left[t_{1}, t_{2}\right] \subset \mathbf{R}_{+}$, where $\Pi_{t_{1}, t_{2}}$ is the restriction operator onto the segment $\left[t_{1}, t_{2}\right]$. We introduce two different topological spaces $H_{s}^{\text {r loc }}\left(Q_{+}\right)$and $H_{w}^{\text {r,loc }}\left(Q_{+}\right)$, ("strong" and "weak"). The space $H_{s}^{\text {r,loc }}\left(Q_{+}\right)$ $\left(H_{w}^{\mathbf{r}, l o c}\left(Q_{+}\right)\right)$is $H^{r, l o c}\left(Q_{+}\right)$with the following convergence topology. By the definition, $v_{n}(s) \rightarrow v(s)(n \rightarrow \infty)$ in $H_{s}^{\mathbf{r}, l o c}\left(Q_{+}\right)$(in $H_{w}^{\mathbf{r}, l o c}\left(Q_{+}\right)$) if $\Pi_{t_{1}, t_{2}} v_{n}(s) \rightarrow$ $\Pi_{t_{1}, t_{2}} v(s)(n \rightarrow \infty)$ strongly in $H^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right)$ (respectively, $\Pi_{t_{1}, t_{2}} v_{n}(s) \rightarrow \Pi_{t_{1}, t_{2}} v(s)(n \rightarrow$ $\infty$ ) weakly in $H^{\mathrm{r}}\left(Q_{t_{1}, t_{2}}\right)$ ) for any $\left[t_{1}, t_{2}\right] \subset \mathbf{R}_{+}$. It is easy to prove that the linear topological space $H_{z}^{r, l o c}\left(Q_{+}\right)$is metrizable, for example, by means of the Fréchet metric generated by the seminorms $\left\|\Pi_{n, n+1} v\right\|_{H^{r}\left(Q_{n, n+1}\right)}, n=0,1,2, \ldots$ The space $H_{w}^{\text {r, }, l o c}\left(Q_{+}\right)$is not metrizable, but it is a Hausdorff and Fréchet-Uryson space with a countable topology base.

We shall use also the space $H^{\mathbf{r}, a}\left(Q_{+}\right)$that is a subspace of $H^{\mathbf{r}, l o c}\left(Q_{+}\right)$. By the definition, $v(s) \in H^{\mathbf{r}, a}\left(Q_{+}\right)$, if the following norm is finite

$$
\begin{equation*}
\|v\|_{H}^{2} \mathbf{r}, \mathbf{a}\left(Q_{+}\right)=\|v\|_{\mathbf{r}, a}^{2}=\sup _{t \geq 0}\left\|\Pi_{t, t+1} v\right\|_{H}^{2} \mathbf{r}_{\left(Q_{1, t+1}\right)} \tag{1.4}
\end{equation*}
$$

Evidently, $H^{r, a}\left(Q_{+}\right)$with the norm (1.4) is a Banach space. We shall not use the topology generated by the norm (1.4). We need the Banach space $H^{\mathbf{r}, a}\left(Q_{+}\right)$to define bounded sets in $H^{\mathrm{r}, l o c}\left(Q_{+}\right)$only.

We put into correspondence to any external force $g(., s) \in \mathcal{H}_{+}\left(g_{0}\right)$ the trajectory space $\mathcal{K}_{g}^{+}$that is the union of all solutions $u(s), s \geq 0$, of equation (1.1) in the space $H^{\mathbf{r}, l o c}\left(Q_{+}\right)$. Notice that $|B(v)| \leq C|v|^{1 / 2}\|v\|^{2}\|v\|_{2}^{1 / 2}$; therefore any solution $u(s) \in \mathcal{K}_{g}^{+}$satisfies (1.1) in the strong sence of the space $L_{2}^{\text {loc }}\left(\mathbf{R}_{+}, H\right)$. By Theorem 1.1, the trajectory space $\mathcal{K}_{g}^{+}$is wide enough for any $g \in \mathcal{H}_{+}\left(g_{0}\right)$. Denote, $\mathcal{K}^{+}=$ $\mathcal{K}_{\mathcal{H}_{+}\left(g_{0}\right)}^{+}=\cup_{g \in \mathcal{H}_{+}\left(g_{0}\right)} \mathcal{K}_{g}^{+}$.
Lemma 1.1 If $g_{0}(s) \in L_{2}^{\text {loc }}\left(\mathbf{R}_{+}, H\right)$ satisfies (1.2) then $\mathcal{K}^{+} \subset H^{\mathbf{r}, a}\left(Q_{+}\right)$.
This lemma will be proved later on.
Consider the translation semigroup $\{T(t) \mid t \geq 0\}$ acting on $H^{\text {r,loc }}\left(Q_{+}\right)$by the formula

$$
T(t) v(s)=v(s+t), s \geq 0, v \in H^{\mathbf{r}, l o c}\left(Q_{+}\right)
$$

Obviously, the family of trajectory spaces $\left\{\mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$ corresponding to the equation (1.1) satisfies the embedding:

$$
\begin{equation*}
T(t) \mathcal{K}_{g}^{+} \subseteq \mathcal{K}_{T(t) g}^{+}, \forall t \geq 0 \tag{1.5}
\end{equation*}
$$

In other words, for any $t \geq 0$, a function $u(s+t), s \geq 0$, is a solution of equation (1.1) with a shifted symbol $g(s+t)=T(t) g(s)$ for any solution $u(s) \in \mathcal{K}_{g}^{+}$of equation (1.1) with a symbol $g(s) \in \mathcal{H}_{+}\left(g_{0}\right)$. Hence, the translation semigroup $\{T(t)\}$ takes $\mathcal{K}^{+}=\mathcal{K}_{\mathcal{H}_{+}\left(g_{0}\right)}^{+}$into itself: $T(t) \mathcal{K}^{+} \subseteq \mathcal{K}^{+}, t \geq 0$.

In this section we study the trajectory attractor $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ of the translation semigroup $\{T(t)\}$ acting on $\mathcal{K}^{+}=\mathcal{K}_{\mathcal{H}_{+}\left(g_{0}\right)}^{+}$. The set $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ attracts any set $T(t) B$ as $t \rightarrow+\infty$ in the topology of $\Theta_{+}^{l o c}=H_{w}^{\text {r,loc }}\left(Q_{+}\right)$, where $B \subset \mathcal{K}^{+}$and $B$ is bounded in the Banach space $\mathcal{F}_{+}^{a}=H^{\mathbf{r}, a}\left(Q_{+}\right)$.

Definition 1.1 Let $\Sigma$ be a complete metric space and let $\Theta$ be a topological space. Consider a family of sets $\left\{\mathcal{K}_{\sigma}, \sigma \in \Sigma\right\}, \mathcal{K}_{\sigma} \subset \Theta$, depending on a parameter $\sigma \in \Sigma$. The family $\left\{\mathcal{K}_{\sigma}, \sigma \in \Sigma\right\}$ is said to be $(\Theta, \Sigma)$-closed if the graph set $\cup_{\sigma \in \Sigma} \mathcal{K}_{\sigma} \times\{\sigma\}$ is closed in the topological space $\Theta \times \Sigma$ with a usual product topology.

Proposition 1.1 Let $\Sigma$ be a compact metric space and $\left\{\mathcal{K}_{\sigma}, \sigma \in \Sigma\right\}$ be $(\Theta, \Sigma)$ closed; then the set $\mathcal{K}_{\Sigma}=\cup_{\sigma \in \Sigma} \mathcal{K}_{\sigma}$ is closed in $\Theta$.

Proof. We use the standard reasoning. Let $u \notin \mathcal{K}_{\Sigma}=\cup_{\sigma \in \Sigma} \mathcal{K}_{\sigma}$. Therefore, $(u, \sigma) \notin \cup_{\sigma^{\prime} \in \Sigma} \mathcal{K}_{\sigma^{\prime}} \times\left\{\sigma^{\prime}\right\}$ for any $\sigma \in \Sigma$. The set $\cup_{\sigma^{\prime} \in \Sigma} \mathcal{K}_{\sigma^{\prime}} \times\left\{\sigma^{\prime}\right\}$ is closed in $\Theta \times \Sigma$, so, there is a neighbourhood $\mathcal{W}_{u} \times \mathcal{O}_{\sigma}$ in $\Theta \times \Sigma$ such that $\mathcal{W}_{\sigma} \times \mathcal{O}_{\sigma} \cap\left(\cup_{\sigma^{\prime} \in \Sigma} \mathcal{K}_{\sigma^{\prime}} \times\left\{\sigma^{\prime}\right\}\right)=$ $\emptyset, u \in \mathcal{W}_{\sigma}, \sigma \in \mathcal{O}_{\sigma}$, where $\mathcal{W}_{\sigma}$ and $\mathcal{O}_{\sigma}$ are open sets in $\Theta$ and $\Sigma$ respectively. The family $\left\{\mathcal{O}_{\sigma} \mid \sigma \in \Sigma\right\}$ forms an open covering of $\Sigma$. Since $\Sigma$ is compact, there is a finite subcovering $\left\{\mathcal{O}_{\sigma_{i}} \mid i=1, \ldots, N\right\}$. Put $\mathcal{W}(u)=\bigcap_{i=1}^{N} \mathcal{W}_{\sigma_{i}}$. Evidently, $\mathcal{W}(u) \cap \mathcal{K}_{\Sigma}=0$. Hence, for any $u \notin \mathcal{K}_{\Sigma}$ there is a neighbourhood $\mathcal{W}(u) \cap \mathcal{K}_{\Sigma}=\emptyset$., i.e. $\mathcal{K}_{\Sigma}$ is closed in $\Sigma$.

Lemma 1.2 The family of trajectory spaces $\left\{\mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$ corresponding to the equation (1.1) is $\left(\Theta_{+}^{\text {loc }}, \mathcal{H}_{+}\left(g_{0}\right)\right)$-closed and $\mathcal{K}^{+}=\mathcal{K}_{\mathcal{H}_{+}\left(g_{0}\right)}^{+}$is closed in $\Theta_{+}^{\text {loc }}$.

Proof. Assume that $u_{n}(s) \in \mathcal{K}_{g_{n}}, g_{n} \in \mathcal{H}_{+}\left(g_{0}\right), u_{n}(s) \rightarrow u(s)(n \rightarrow+\infty)$ in $\Theta_{+}^{\text {loc }}$ and $g_{n}(s) \rightarrow g(s)(n \rightarrow+\infty)$ in $L_{2, w}^{\text {loc }}$. We claim that $u \in \mathcal{K}_{g}^{+}$. Indeed, for any fixed $\left[t_{1}, t_{2}\right] \subset \mathbf{R}_{+}$we have: $u_{n}(s) \rightharpoonup u(s)(n \rightarrow+\infty)$ weakly in $H^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right)$. Thus, $\partial_{t} u_{n}(s)-\partial_{t} u(s)(n \rightarrow+\infty)$ weakly in $L_{2}\left(t_{1}, t_{2} ; H\right)$ and $\partial^{\alpha} u(s) \rightarrow \partial^{\alpha} u(s)(n \rightarrow$ $+\infty)$ weakly in $L_{2}\left(t_{1}, t_{2} ; H\right)$ for any $\alpha=\left(\alpha_{1}, \alpha_{2}\right),|\alpha| \leq 2$. In particular, by refining, we may assume that $u_{n}(s) \rightarrow u(s)(n \rightarrow+\infty)$ almost everywhere in $Q_{t_{1}, t_{2}}$ and $B\left(u_{n}(s)\right) \rightharpoonup B(u(s))(n \rightarrow+\infty)$ weakly in $L_{2}\left(t_{1}, t_{2} ; H\right)$ (see compactness theorems in [16], [19]). Therefore we may, in the equation

$$
\partial_{t} u_{n}+\nu L u_{n}+B\left(u_{n}\right)=g_{n}(x, t)
$$

pass to the limit as $n \rightarrow \infty$ weakly in $L_{2}\left(t_{1}, t_{2} ; H\right)$ and get

$$
\partial_{t} u+\nu L u+B(u)=g(x, t),
$$

so that $u(s) \in \mathcal{K}_{g}^{+}$. Finally, it follows from Proposition 1.1 that $\mathcal{K}_{\mathcal{H}_{+}\left(g_{0}\right)}^{+}$is closed in $\Theta_{+}^{l o c}$ since $\Sigma=\mathcal{H}_{+}\left(g_{0}\right)$ is a compact metric space.

Consider the translation semigroup $\{T(t)\}$ acting on the metric space $\mathcal{H}_{+}\left(g_{0}\right)$. Evidently, the semigroup $\{T(t)\}$ is continuous in $\mathcal{H}_{+}\left(g_{0}\right)$.

Definition 1.2 A set $\mathbf{A}$ is said to be a global attractor of a semigroup $\{S(t)\}$ acting on a complete metric space $X$, if (i) $\mathbf{A}$ is compact in $X$ and $\mathbf{A}$ attracts any bounded set $B: \operatorname{dist}_{X}(S(t) B, \mathbf{A}) \rightarrow 0(t \rightarrow \infty) ;(i i) S(t) \mathbf{A}=\mathbf{A}$ for any $t \geq 0$.

For the case $X=\Sigma=\mathcal{H}_{+}\left(g_{0}\right)$ we have
Proposition 1.2 The translation semigroup $\{T(t)\}$ acting on the compact metric space $\Sigma=\mathcal{H}_{+}\left(g_{0}\right)$ possesses a global attractor $\mathbf{A}$ which coincides with the $\omega$-limit set of $\Sigma$ :

$$
\mathbf{A}=\omega(\Sigma)=\bigcap_{t \geq 0}\left[\bigcup_{h \geq t} T(h) \Sigma\right]_{\Sigma}, \omega(\Sigma) \subseteq \Sigma
$$

where $[.]_{\Sigma}$ means the closure in $\Sigma$. Moreower, $T(t) \omega(\Sigma)=\omega(\Sigma) \forall t \geq 0$.
This statement follows from well-known theorems from the theory of attractors of semigroups acting in metric spaces (see, for example, [2], [20], [13]).

Consider more general scheme. Let $\Sigma$ be a complete metric space. Let also $\mathcal{F}$ be a Banach space. Assume $\mathcal{F} \subseteq \Theta$, where $\Theta$ is a Hausdorff topological space. Let a semigroup $\{T(t)\}$ acts on $\Theta: T(t) \Theta \subseteq \Theta, t \geq 0$. Let we be given a family of sets $\left\{\mathcal{K}_{\sigma}, \sigma \in \Sigma\right\}, \mathcal{K}_{\sigma} \subseteq \mathcal{F}$. Put $\mathcal{K}_{\Sigma}=\cup_{\sigma \in \Sigma} \mathcal{K}_{\sigma}$.

Definition 1.3 $A$ set $P \subseteq \Theta$ is said to be a uniformly (w.r.t. $\sigma \in \Sigma$ ) attracting set for the family $\left\{\mathcal{K}_{\sigma}, \sigma \in \Sigma\right\}$ in the topology $\Theta$ if for any bounded set $B$ in $\mathcal{F}$ and $B \subseteq \mathcal{K}_{\Sigma}$, the set $P$ attracts $T(t) B$ as $t \rightarrow+\infty$ in the topology $\Theta$, i.e. for any neighbourhood $\mathcal{O}(P)$ in $\Theta$ there exists $t_{1} \geq 0$ such that $T(t) B \subseteq \mathcal{O}(P)$ for any $t \geq t_{1}$.

Definition 1.4 $A$ set $\mathcal{A}_{\Sigma} \subseteq \Theta$ is said to be a uniform (w.r.t. $\sigma \in \Sigma$ ) attractor of the semigroup $\{T(t)\}$ on $\mathcal{K}_{\Sigma}$ in the topology $\Theta$, if $\mathcal{A}_{\Sigma}$ is compact in $\Theta$ and $\mathcal{A}_{\Sigma}$ is a minimal compact uniformly attracting set of $\left\{\mathcal{K}_{\sigma}, \sigma \in \Sigma\right\}$, i.e. $\mathcal{A}_{\Sigma}$ belongs to any compact uniformly attracting set $P$ of $\left\{\mathcal{K}_{\sigma}, \sigma \in \Sigma\right\}: \mathcal{A}_{\Sigma} \subseteq P$.

Let a semigroup acts on $\Sigma$, which we denote $\{T(t)\}: T(t) \Sigma \subseteq \Sigma, t \geq 0$.
Definition 1.5 The family of trajectory spaces $\left\{\mathcal{K}_{\sigma}, \sigma \in \Sigma\right\}$ is said to be translationcoordinated (tr.-coord.) if for any $\sigma \in \Sigma$ and any $u \in \mathcal{\mathcal { K } _ { \sigma }}$

$$
T(t) u \in \mathcal{K}_{T(t) \sigma} \forall t \geq 0 .
$$

It follows from (1.5) that the family $\left\{\mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$ is tr.-coord. with respect to the translation semigroup $\{T(t)\}$.

Proposition 1.3 Let $\Sigma$ be a compact metric space and let a continuous semigroup $\{T(t)\}$ act on $\Sigma$ and on $\Theta: T(t) \Sigma \subseteq \Sigma, T(t) \Theta \subseteq \Theta, t \geq 0$. Let we be given a family of sets $\left\{\mathcal{K}_{\sigma}, \sigma \in \Sigma\right\}, \mathcal{K}_{\sigma} \subseteq \mathcal{F}$. Assume, the family $\left\{\mathcal{K}_{\sigma}, \sigma \in \Sigma\right\}$ is $(\Theta, \Sigma)$ closed and tr.-coord. Let there exist a uniformly (w.r.t. $\sigma \in \Sigma$ ) attracting set $P$ for $\left\{\mathcal{K}_{\sigma}, \sigma \in \Sigma\right\}$ in $\Theta$, such that $P$ is compact in $\Theta$ and $P$ is bounded in $\mathcal{F}$. Then the semigroup $\{T(t)\}$ acting on $\mathcal{K}_{\Sigma}=\cup_{\sigma \in \Sigma} \mathcal{K}_{\sigma}$ possesses the uniform (w.r.t. $\sigma \in \Sigma$ ) attractor $\mathcal{A}_{\Sigma} \subseteq \mathcal{K}_{\Sigma} \cap P$ in the space $\Theta$,

$$
\begin{equation*}
T(t) \mathcal{A}_{\Sigma}=\mathcal{A}_{\Sigma} \forall t \geq 0 \tag{1.6}
\end{equation*}
$$

Moreover,

$$
\mathcal{A}_{\Sigma}=\mathcal{A}_{\omega(\Sigma)}
$$

where $\mathcal{A}_{\omega(\Sigma)}$ is the uniform (w.r.t. $\sigma \in \omega(\Sigma)$ ) attractor of the family $\left\{\mathcal{K}_{\sigma}, \sigma \in \omega(\Sigma)\right\}$, $\mathcal{A}_{\omega(\Sigma)} \subseteq \mathcal{K}_{\omega(\Sigma)}$. Here $\omega(\Sigma)$ is the attractor of the semigroup $\{T(t)\}$ on $\Sigma, T(t) \omega(\Sigma)=$ $\omega(\Sigma)$. The set $\mathcal{A}_{\Sigma}=\mathcal{A}_{\omega(\Sigma)}$ is compact in $\Theta$ and bounded in $\mathcal{F}$.

The proof of Proposition 1.3 is given in [5], (see also [10]).
In application to the Navier-Stokes system (1.1) in this section, $\Sigma=\mathcal{H}_{+}\left(g_{0}\right), \mathcal{F}=$ $\mathcal{F}_{+}^{a}=H^{\mathbf{r}, a}\left(Q_{+}\right), \quad \Theta=\Theta_{+}^{l o c}=H_{w}^{\mathbf{r}, l o c}\left(Q_{+}\right),\{T(t)\}$ is the translation semigroup, and $\left\{\mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$ is the family of trajectory spaces of equation (1.1). In this case a uniform (w.r.t. $\sigma \in \Sigma$ ) attractor $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ is called a trajectory attractor of the family $\left\{\mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$. In the next section we shall consider the "strong" space $\Theta=\Theta_{+}^{l o c}=H_{s}^{\mathrm{r}, l o c}\left(Q_{+}\right)$.

Let us formulate the main result of this section.
Theorem 1.2 Let $g_{0}(s)$ be tr.-c. in $L_{2, w}^{\text {loc }}\left(\mathbf{R}_{+}, H\right)$ then the translation semigroup $\{T(t)\}$ acting on $\mathcal{K}^{+}=\mathcal{K}_{\mathcal{H}_{+}\left(g_{0}\right)}^{+}$possesses a trajectory attractor $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ in $\Theta_{+}^{\text {loc }}=$ $H_{w}^{\mathbf{r}, l o c}\left(Q_{+}\right)$; the set $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ attracts any set $B \subseteq \mathcal{K}^{+}$, bounded in $\mathcal{F}_{+}^{a}=H^{\mathbf{r}, a}\left(Q_{+}\right)$. The set $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ is bounded in $\mathcal{F}^{+}$, compact in $\Theta_{+}^{\text {loc }}$, and it is invariant with respect to the translation semigroup: $T(t) \mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}=\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ for any $t \geq 0$. Moreower,

$$
\begin{equation*}
. \mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}=\mathcal{A}_{\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)} \tag{1.7}
\end{equation*}
$$

where $\mathcal{A}_{\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)}$ is the trajectory attractor of the family $\left\{\mathcal{K}_{g}, g \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)\right\}$, $\mathcal{A}_{\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)} \subseteq \mathcal{K}_{\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)}$. Any function $u(s) \in \mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ is tr.-c. in $\Theta_{+}^{\text {loc }}$.

Notice that the topology of the space $H_{w}^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right)$ is stronger then the uniform convergence topology of the space $C\left(\left[t_{1}, t_{2}\right] ; H\right), H_{w}^{\Gamma}\left(Q_{t_{1}, t_{2}}\right) \subset C\left(\left[t_{1}, t_{2}\right] ; H\right)$. So, we have

Corollary 1.1 For any set $B \subset \mathcal{K}^{+}$, bounded in $\mathcal{F}^{+}$, one has

$$
\operatorname{dist}_{C\left(\left[t_{1}, t_{2}\right] ; H\right)}\left(\Pi_{0, \Gamma} T(t) B, \Pi_{0, \Gamma} \mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}\right) \rightarrow 0(t \rightarrow \infty) \forall \Gamma \geq 0 .
$$

Similarly, from the embedding $H_{w}^{\mathrm{r}}\left(Q_{t_{1}, t_{2}}\right) \subset C_{w}\left(\left[t_{1}, t_{2}\right] ; V\right)$, it follows

Corollary 1.2 For any set $B \subset \mathcal{K}^{+}$, bounded in $\mathcal{F}^{+}$, and for any $v \in V$, one has

$$
\operatorname{dist}_{C([0, \Gamma])}\left(\Pi_{0, \Gamma} J_{v} T(t) B, \Pi_{0, \Gamma} J_{v} \mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}\right) \rightarrow 0(t \rightarrow \infty) \forall \Gamma \geq 0,
$$

where $J_{v}$ is the mapping from $H_{w}^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right)$ into $C\left(\left[t_{1}, t_{2}\right]\right): J_{v}(u(s))=((u(s), v))$, $((.,)$.$) is the scalar product in V$.

To prove theorem 1.2 we use Proposition 1.3. According to (1.5) and Lemma 1.2 we have only to check that the family of trajectory spaces $\left\{\mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$ corresponding to the equation (1.1) possesses a uniformly (w.r.t. $g \in \mathcal{H}_{+}\left(g_{0}\right)$ ) attracting set $P$ compact in $\Theta_{+}^{l o c}$ and bounded in $\mathcal{F}_{+}^{a}$. This is the most difficult part of the proof. We separate the proof of this fact into a few lemmas.

Lemma 1.3 For any $u \in \mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)$, the following estimates are valid:

$$
\begin{gather*}
|u(\tau+t)|^{2} \leq e^{-\lambda t}|u(\tau)|^{2}+C_{1}\|g\|_{a}^{2}, t, \tau \geq 0,  \tag{1.8}\\
\|T(t) u\|_{L_{\infty}\left(\mathbf{R}_{+} ; H\right)}^{2} \leq e^{-\lambda t}|u(0)|^{2}+C_{1}\|g\|_{a}^{2} \tag{1.9}
\end{gather*}
$$

where $\lambda$ is the first eigenvalue of the operator $\nu L, C_{1}=\lambda^{-1}\left(1-e^{-\lambda}\right)^{-1}$;

$$
\begin{gather*}
\nu \int_{t}^{t+1}\|u(s)\|^{2} d s \leq|u(t)|^{2}+C_{2} \int_{t}^{t+1}|g(s)|^{2} d s  \tag{1.10}\\
\nu\|T(t) u\|_{L_{2}^{\mathrm{a}}\left(\mathrm{R}_{+} ; V\right)}^{2} \leq e^{-\lambda t}|u(0)|^{2}+C_{3}\|g\|_{a}^{2} \tag{1.11}
\end{gather*}
$$

where $C_{2}=\lambda^{-1}, C_{3}=C_{1}+C_{2}, t \geq 0$.
Proof. Taking the scalar product in $H$ of (1.1) with $u$, we get

$$
\begin{equation*}
\frac{d}{d t}|u(t)|^{2}+\lambda|u(t)|^{2} \leq \frac{d}{d t}|u(t)|^{2}+\nu\|u(t)\|^{2} \leq \lambda^{-1}|g(t)|^{2} \tag{1.12}
\end{equation*}
$$

and we obtain after proper integrating from $\tau$ to $\tau+t$

$$
|u(\tau+t)|^{2} \leq e^{-\lambda t}|u(\tau)|^{2}+\lambda^{-1} e^{-\lambda(\tau+t)} \int_{\tau}^{\tau+t}|g(s)|^{2} e^{\lambda s} d s
$$

Estimating the last expression, we get

$$
\begin{aligned}
& \int_{\tau}^{\tau+t}|g(s)|^{2} e^{-\lambda(\tau+t-s)} d s \leq \\
& \int_{\tau+t-1}^{\tau+t}|g(s)|^{2} e^{-\lambda(\tau+t-s)} d s+\int_{\tau+t-2}^{\tau+t-1}|g(s)|^{2} e^{-\lambda(\tau+t-s)} d s+\ldots \leq \\
& \int_{\tau+t-1}^{\tau+t}|g(s)|^{2} d s+e^{-\lambda} \int_{\tau+t-2}^{\tau+t-1}|g(s)|^{2} d s+e^{-2 \lambda} \int_{\tau+t-3}^{\tau+t-2}|g(s)|^{2} d s+\ldots \leq \\
&\|g\|_{a}^{2}\left(1+e^{-\lambda}+e^{-2 \lambda}+\ldots\right)=\|g\|_{a}^{2}\left(1-e^{-\lambda}\right)^{-1} .
\end{aligned}
$$

So, inequality (1.8) is proved. Inequality (1.9) follows directly from (1.8). In the usual way, one derives (1.10) from (1.12). Combining (1.8) and (1.10), we get (1.11).

Lemma 1.4 For any $u \in \mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)$,

$$
\begin{equation*}
\sup _{0 \leq t \leq \Gamma} t\|u(\tau+t)\|^{2} \leq C_{1}\left(\Gamma,|u(\tau)|^{2}, \int_{\tau}^{\tau+\Gamma}|g(s)|^{2} d s\right) ; \Gamma, \tau \geq 0 \tag{1.13}
\end{equation*}
$$

where $C_{1}\left(\eta_{1}, \eta_{2}, \eta_{3}\right)$ is a continuous and increasing function with respect to each $\eta_{i} \geq 0$.

The proof is analogous to one given in [2]. We sketch the main points of it for convenience of readers. For brevity sake, we suppose without lose of generality that $\nu=1$ and $\tau=0$. Multiplying equation (1.1) by $t L u$ we get:

$$
\begin{array}{r}
\frac{1}{2} \frac{d}{d t}\left(t\|u(t)\|^{2}\right)-\frac{1}{2}\|u(t)\|^{2}+t\|u(t)\|_{2}^{2}+t(B(u), L u) \leq  \tag{1.14}\\
t|g(t)|^{2}+\frac{1}{4} t\|u(t)\|_{2}^{2}
\end{array}
$$

Recall that $(u, L u)=\|u\|^{2},(L u, L u)=\|u\|_{2}^{2}$. We have also that

$$
\begin{align*}
(B(u), L u) & \leq|B(u)|\|u\|_{2},  \tag{1.15}\\
|B(u)| & \leq c\left(\int_{\Omega}|u|^{2}|\nabla u|^{2} d x\right)^{1 / 2} \leq c\|u\|_{0,4}\|u\|_{1,4} ;  \tag{1.16}\\
\|u\|_{0,4} & \leq c_{1}\|u\|^{1 / 2}|u|^{1 / 2},\|u\|_{0,4} \leq c_{2}\|u\|_{2}^{1 / 2}\|u\|^{1 / 2} \tag{1.17}
\end{align*}
$$

(see inequalities (1.17) in [15], [21]). It follows from (1.15), (1.16), and (1.17) that

$$
\begin{align*}
|B(u)| & \leq\left. c_{3}\|u\|_{2}^{1 / 2}\|u\| u\right|^{1 / 2}  \tag{1.18}\\
t(B(u), L u) & \leq t c_{3}\|u\|_{2}^{3 / 2}\|u\|\left\|\left.u\right|^{1 / 2} \leq \frac{t}{4}\right\| u\left\|_{2}^{2}+\frac{t c_{4}}{2}\right\| u \|^{4}|u|^{2} . \tag{1.19}
\end{align*}
$$

Using (1.14) and (1.19) we obtain

$$
\begin{equation*}
\frac{d}{d t}\left(t\|u(t)\|^{2}\right)+t\|u(t)\|_{2}^{2} \leq\|u(t)\|^{2}+2 t|g(t)|^{2}+t c_{4}\|u(t)\|^{4}|u(t)|^{2}, \tag{1.20}
\end{equation*}
$$

Denote $z(t)=t\|u(t)\|^{2}$. Consequently,

$$
z^{\prime}(t) \leq b(t)+\gamma(t) z(t), b(t)=\|u(t)\|^{2}+2 t|g(t)|^{2}, \gamma(t)=c_{4}\|u(t)\|^{2}|u(t)|^{2} .
$$

Applying Gronwall inequality, we get:

$$
z(t) \leq \int_{0}^{t} b(s) \exp \left(\int_{s}^{t} \gamma(\theta) d \theta\right) d s \leq\left(\int_{0}^{t} b(s) d s\right) \exp \left(\int_{0}^{t} \gamma(s) d s\right) .
$$

Using (1.12), we have

$$
\begin{equation*}
|u(t)|^{2}+\int_{0}^{t}\|u(s)\|^{2} d s \leq|u(0)|^{2}+\lambda^{-1} \int_{0}^{t}|g(s)|^{2} d s \tag{1.21}
\end{equation*}
$$

Therefore

$$
\begin{array}{r}
t\|u(t)\|^{2} \leq \\
\left(\int_{0}^{t}\left(\|u(s)\|^{2}+2 s|g(s)|^{2}\right) d s\right) \exp \left(\int_{0}^{t} c_{4}\|u(s)\|^{2}|u(s)|^{2} d s\right) \\
\leq \\
\left(|u(0)|^{2}+\left(\lambda^{-1}+2 t\right) \int_{0}^{t}|g(s)|^{2} d s\right) \exp \left(c_{4}\left(|u(0)|^{2}+\lambda^{-1} \int_{0}^{t}|g(s)|^{2} d s\right)^{2}\right)
\end{array}
$$

Finally,

$$
\begin{equation*}
\sup _{0 \leq \leq \leq \Gamma} t\|u(t)\|^{2} \leq C_{1}\left(\Gamma,|u(0)|^{2}, \int_{0}^{\Gamma}|g(s)|^{2} d s\right) \tag{1.22}
\end{equation*}
$$

where $C_{1}\left(\eta_{1}, \eta_{2}, \eta_{3}\right)=\left(\eta_{2}+\left(\lambda^{-1}+2 \eta_{1}\right) \eta_{3}\right) \exp \left(c_{4}\left(\eta_{2}+\lambda^{-1} \eta_{3}\right)^{2}\right)$.
Inequality (1.13) implies that

$$
\begin{equation*}
\|u(t+\tau+1)\|^{2} \leq C_{1}\left(1,|u(t+\tau)|^{2}, \int_{t+\tau}^{t+\tau+1}|g(s)|^{2} d s\right) \tag{1.23}
\end{equation*}
$$

Taking sup in (1.23) with respect to $\tau \geq 0$, we obtain according to (1.9) that $\|T(t+1) u\|_{L_{\infty}\left(\mathbf{R}_{+} ; V\right)}^{2} \leq C_{1}\left(1,\|T(t) u\|_{L_{\infty}\left(\mathbf{R}_{+} ; H\right)}^{2},\|T(t) g\|_{a}^{2}\right) \leq C_{2}\left(e^{-\lambda t}|u(0)|^{2},\|g\|_{a}^{2}\right)$. Hence

Corollary 1.3 For any $u \in \mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)$,

$$
\|T(t+1) u\|_{L_{\infty}\left(\mathbf{R}_{+} ; V\right)}^{2} \leq C_{2}\left(e^{-\lambda t}|u(0)|^{2},\|g\|_{a}^{2}\right), t \geq 0
$$

Lemma 1.5 For any $u \in \mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)$,
$(1.24) \int_{\tau}^{\tau+\Gamma}(s-\tau)\left(\|u(s)\|_{2}^{2}+\left|\partial_{t} u(s)\right|^{2}\right) d s \leq C_{3}\left(\Gamma,|u(\tau)|^{2}, \int_{\tau}^{\tau+\Gamma}|g(s)|^{2} d s\right) ;$

$$
\begin{align*}
\|T(t+1) u\|_{\mathrm{r}, a}^{2}= & \sup _{\tau \geq t+1} \int_{\tau}^{\tau+1}\left(\|u(s)\|_{2}^{2}+\left|\partial_{t} u(s)\right|^{2}\right) d s \leq  \tag{1.25}\\
& C_{4}\left(e^{-\lambda t}|u(0)|^{2},\|g\|_{a}^{2}\right)
\end{align*}
$$

where $\tau, t, \Gamma$ are positive and any.
Proof. It is sufficient to prove (1.24) for $\tau=0$ and $\nu=1$. It follows from (1.20), (1.21), and (1.22) that

$$
\begin{gather*}
\int_{0}^{\Gamma} s\|u(s)\|_{2}^{2} d s \leq \int_{0}^{\Gamma}\|u(s)\|^{2} d s+2 \Gamma \int_{0}^{\Gamma}|g(s)|^{2} d s \\
c_{4}\left(\sup _{0 \leq t \leq \Gamma}|u(t)|^{2}\right)\left(\sup _{0 \leq t \leq \Gamma} t\|u(t)\|^{2}\right) \int_{0}^{\Gamma}\|u(s)\|^{2} d s \leq \\
|u(0)|^{2}+\lambda^{-1} \int_{0}^{\Gamma}|g(s)|^{2} d s+2 \Gamma \int_{0}^{\Gamma}|g(s)|^{2} d s \\
+ \\
c_{4}\left(|u(0)|^{2}+\lambda^{-1} \int_{0}^{\Gamma}|g(s)|^{2} d s\right)^{2} C_{1}\left(\Gamma,|u(0)|^{2}, \int_{0}^{\Gamma}|g(s)|^{2} d s\right)=  \tag{1.26}\\
C_{3}^{\prime}\left(\Gamma,|u(0)|^{2}, \int_{0}^{\Gamma}|g(s)|^{2} d s\right) .
\end{gather*}
$$

Now, equation (1.1) implies directly that

$$
\begin{align*}
\left(\int_{0}^{\Gamma} s\left|\partial_{t} v(s)\right|^{2} d s\right)^{1 / 2} \leq & \left(\int_{0}^{\Gamma} s\|u(s)\|_{2}^{2} d s\right)^{1 / 2}+\left(\int_{0}^{\Gamma} s|B(u)|^{2} d s\right)^{1 / 2}+ \\
\left(\int_{0}^{\Gamma} s|g(s)|^{2} d s\right)^{1 / 2} \leq & C_{3}^{\prime}\left(\Gamma,|u(0)|^{2}, \int_{0}^{\Gamma}|g(s)|^{2} d s\right)+\Gamma^{1 / 2}\left(\int_{0}^{\Gamma}|g(s)|^{2} d s\right)^{1 / 2}+ \\
(1.27) & c_{3}\left(\int_{0}^{\Gamma} s\|u(s)\|_{2}\|u(s)\|^{2}|u(s)| d s\right)^{1 / 2} \tag{1.27}
\end{align*}
$$

We have used inequality (1.18). At the same time by (1.22) and (1.26), we get

$$
\begin{gather*}
\int_{0}^{\Gamma} s\|u(s)\|_{2}\|u(s)\|^{2}|u(s)| d s \leq \int_{0}^{\Gamma} s\|u(s)\|^{4}|u(s)|^{2} d s+\int_{0}^{\Gamma} s\|u(s)\|_{2}^{2} d s \leq \\
\left(\sup _{0 \leq t \leq \Gamma}|u(t)|^{2}\right)\left(\sup _{0 \leq t \leq \Gamma} t\|u(t)\|^{2}\right) \int_{\tau}^{\Gamma}\|u(s)\|^{2} d s+C_{3}^{\prime}\left(\Gamma,|u(0)|^{2}, \int_{0}^{\Gamma}|g(s)|^{2} d s\right) \leq \\
(1.28) \quad\left(|u(0)|^{2}+\lambda^{-1} \int_{0}^{\Gamma}|g(s)|^{2} d s\right)^{2} C_{1}\left(\Gamma,|u(0)|^{2}, \int_{0}^{\Gamma}|g(s)|^{2} d s\right)+C_{3}^{\prime}(.) \tag{1.28}
\end{gather*}
$$

Combining (1.27) and (1.28) we obtain

$$
\begin{equation*}
\int_{0}^{\Gamma} s\left|\partial_{t} u(s)\right|^{2} d s \leq C_{3}^{\prime \prime}\left(\Gamma,|u(0)|^{2}, \int_{0}^{\Gamma}|g(s)|^{2} d s\right) \tag{1.29}
\end{equation*}
$$

Summing (1.26) and (1.29), we derive (1.24). From (1.24) it follows for $\Gamma=2$ that
(1.30) $\int_{t+\tau+1}^{t+\tau+2}\left(\|u(s)\|_{2}^{2}+\left|\partial_{t} u(s)\right|^{2}\right) d s \leq C_{3}\left(2,|u(t+\tau)|^{2}, \int_{t+\tau}^{t+\tau+2}|g(s)|^{2} d s\right)$.

Taking sup in (1.30) with respect to $\tau \geq 0$, we obtain according to (1.9) that

$$
\|T(t+1) u\|_{\mathbf{r}, a}^{2} \leq C_{3}\left(2,\|T(t) u\|_{L_{\infty}\left(\mathbf{R}_{+} ; H\right)}^{2}, 2\|T(t) g\|_{a}^{2}\right) \leq C_{4}\left(e^{-\lambda t}|u(0)|^{2},\|g\|_{a}^{2}\right)
$$

Lemma is proved.
Lemma 1.1 follows from more general
Lemma 1.6 For any $u \in \mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)$,

$$
\begin{gather*}
\int_{\tau}^{\tau+\Gamma}\left(\|v(s)\|_{2}^{2}+\left|\partial_{t} v(s)\right|^{2}\right) d s \leq C_{5}\left(\|u(\tau)\|^{2}, \int_{\tau}^{\tau+\Gamma}|g(s)|^{2} d s\right)  \tag{1.31}\\
\|u\|_{r, a}^{2}=\sup _{\tau \geq 0} \int_{\tau}^{\tau+1}\|u(s)\|_{2}^{2}+\left|\partial_{t} u(s)\right|^{2} d s \leq C_{6}\left(\|u(0)\|^{2},\|g\|_{a}^{2}\right), \tau, \Gamma \geq 0 .
\end{gather*}
$$

Proof. Similarly to (1.20) we get

$$
\begin{aligned}
\frac{d}{d t}\left(\|u(t)\|^{2}\right)+\|u(t)\|_{2}^{2} & \leq 2|g(t)|^{2}+c_{4}\|u(t)\|^{4}|u(t)|^{2} \\
z_{1}^{\prime}(t) & \leq b_{1}(t)+\gamma(t) z_{1}(t), \quad z_{1}(t)=\|u(t)\|^{2}, b_{1}(t)=2|g(t)|^{2} \\
z_{1}(t) & \leq\left(z_{1}(0)+\int_{0}^{t} b_{1}(s) d s\right) \exp \left(\int_{0}^{t} \gamma(s) d s\right)
\end{aligned}
$$

So, using (1.21), we obtain, as above, (1.31). Finally, combinig (1.31) with $\tau \in[0,1]$ and (1.25) with $\tau \in] 1,+\infty$ [we get

$$
\begin{aligned}
\|u\|_{\mathbf{r}, a}^{2}=\sup _{\tau \geq 0} \int_{\tau}^{\tau+1}\left(\|u(s)\|_{2}^{2}+\left|\partial_{t} u(s)\right|^{2}\right) d s & \leq \\
\max \left\{C_{5}\left(\|u(0)\|^{2},\|g\|_{a}^{2}\right), C_{4}\left(|u(0)|^{2},\|g\|_{a}^{2}\right)\right\} & =C_{6}\left(\|u(0)\|^{2},\|g\|_{a}^{2}\right) .
\end{aligned}
$$

Lemma is proved.
Coming back to the proof of Theorem 1.2, we construct the uniformly attracting set $P$ in $\Theta_{+}^{\text {loc }}$ for the translation semigroup $\{T(t)\}$ acting on $\mathcal{K}^{+}=\mathcal{K}_{\mathcal{H}_{+}\left(g_{0}\right)}^{+}$. From (1.25) it follows that

$$
\begin{equation*}
\|T(t+1) u\|_{\mathbf{r}, a}^{2} \leq C_{4}\left(e^{-\lambda t}\|u\|_{\mathbf{r}, a}^{2},\|g\|_{a}^{2}\right) \leq C_{4}\left(e^{-\lambda t}\|u\|_{\mathbf{r}, a}^{2},\left\|g_{0}\right\|_{a}^{2}\right) \tag{1.32}
\end{equation*}
$$

$\forall u \in \mathcal{K}^{+}$, since $\|g\|_{a} \leq\left\|g_{0}\right\|_{a}$ for any $g \in \mathcal{H}_{+}\left(g_{0}\right)$. Consider the set

$$
P_{0}=\left\{v \in \mathcal{F}_{+}^{a} \mid\|v\|_{\mathbf{r}, a}^{2} \leq C_{4}\left(1,\left\|g_{0}\right\|_{a}^{2}\right)\right\}
$$

Evidently, $P_{0}$ is a desired attracting set. Indeed, if $B \subseteq \mathcal{K}^{+} \cap \mathcal{F}_{+}^{a}$ is a bounded set of trajectories then $e^{-\lambda t}\|u\|_{\mathbf{r}, a}^{2} \leq 1$ for any $u \in B$ when $t \geq t^{\prime} \gg 1$ and therefore, by (1.32) $T(t+1) B \subseteq P_{0}$. Hence $P_{0}$ is even a uniformly absorbing set. Notice that the set $P_{0}$ is bounded in $\mathcal{F}_{+}^{a}$ and compact in $\Theta_{+}^{\text {loc }}=H_{w}^{\text {r.loc }}\left(Q_{+}\right)$. The latter is true since the topology in $H_{w}^{\mathbf{r}, l o c}\left(Q_{+}\right)$is generated by the weak topology of Banach spaces $H^{\mathrm{r}}\left(Q_{t_{1}, t_{2}}\right)=L_{2}\left(t_{1}, t_{2} ; H_{2}\right) \cap\left\{\partial_{\mathrm{t}} v \in L_{2}\left(t_{1}, t_{2} ; H\right)\right\}$. Recall that $u_{n}(s)-$ $u(s)(n \rightarrow+\infty)$ weakly in $H^{\mathrm{r}}\left(Q_{t_{1}, t_{2}}\right)$ whenever $\partial_{t} u_{n}(s) \rightarrow \partial_{t} u(s)(n \rightarrow+\infty)$ weakly in $L_{2}\left(t_{1}, t_{2} ; H\right)$ and $\partial^{\alpha} u(s) \rightarrow \partial^{\alpha} u(s)(n \rightarrow+\infty)$ weakly in $L_{2}\left(t_{1}, t_{2} ; H\right)$ for any $\alpha=\left(\alpha_{1}, \alpha_{2}\right),|\alpha| \leq 2$. That is, a bounded set in $H^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right)$ is weakly compact in $H^{\mathbf{r}}\left(Q_{\mathbf{t}_{1}, t_{2}}\right)$.

Remark 1.1 The set $P_{0}$ being a compact subspace of $H_{w}^{\mathrm{r}, \text { loc }}\left(Q_{+}\right)$is a metrizable space and the corresponding metric space is compact. This proposition follows from the fact that a ball of a separable Banach space endowed with the weak topology of this space is metrizable and compact. The translation semigroup $\{T(t)\}$ is continuous on $P_{0}$ and $T(t)$ takes $P_{0}$ into itself: $T(t) P_{0} \subseteq P_{0}$ for any $t \geq 0$. So the Proposition 1.2 is applicable. In particular the set $\mathbf{A}=\omega\left(P_{0}\right)$ is a global attractor of the semigroup $\{T(t)\}$ acting on $P_{0}$. Moreower, $\mathbf{A}=\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ because $P_{0}$ is a uniformly absorbing set of the family of trajectory spaces $\left\{\mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$. This reasoning proves the first part of Theorem 1.2. To prove property (1.7) we have to use more subtle reasoning (See [5]).

## 2 Trajectory attractor for 2D N.-S. system with translation-compact external force in $L_{2}^{\text {loc }}$.

Now consider the case when the external force $g(x, s)$ in (1.1) is a tr.-c. function in $L_{2}^{\text {loc }}\left(\mathbf{R}_{+} ; H\right)$. The space $L_{2}^{\text {loc }}\left(\mathbf{R}_{+}, H\right)=L_{2}^{\text {loc }}$ is endowed with the following local strong convergence topology. The sequence $\left\{g_{n}(s)\right\}$ converges to $g(s)$ as $n \rightarrow \infty$ in $L_{2}^{\text {loc }}$ whenever $\int_{t_{1}}^{t_{2}}\left|g_{n}(s)-g(s)\right|^{2} d s \rightarrow 0(n \rightarrow \infty)$ for any $\left[t_{1}, t_{2}\right] \subseteq \mathbf{R}_{+}$. The space $L_{2}^{\text {loc }}$ is metrizable and complete. A function $g(s) \in L_{2}^{\text {loc }}$ is tr.-c. in $L_{2}^{l o c}$ whenever the set $\left\{g(s+h) \mid h \in \mathbf{R}_{+}\right\}$is precompact in $L_{2}^{l o c}$. The criterion of functions to be tr.-c. in $L_{2}^{\text {loc }}$ is given in [6]. We recall: a function $g(s) \in L_{2}^{\text {loc }}$ is tr.-c. in $L_{2}^{\text {loc }}$ if and only if
(i) for any $h \geq 0$ the set $\left\{\int_{t}^{t+h} g(s, x) d s \mid t \in \mathbf{R}_{+}\right\}$is precompact in $H$;
(ii) there is a positive function $\beta(s)>0, s>0$, such that $\beta(s) \rightarrow 0+(s \rightarrow 0+)$ and

$$
\int_{t}^{t+1}|g(s)-g(s+l)|^{2} d s \leq \beta(|l|) \forall t \geq 0
$$

Remark 2.1 Let us give a simple sufficient condition. A function $g(s) \in L_{2}^{\text {loc }}$ is tr.-c. in $L_{2}^{\text {loc }}$ if

$$
\left\|\Pi_{0,1} g(., s+t)\right\|_{H^{\delta}\left(Q_{0,1}\right)} \leq M \forall t \geq 0
$$

for some $\delta>0$. Here $H^{\delta}\left(Q_{0,1}\right)=H^{\delta}\left(\Omega \times\left[t_{1}, t_{2}\right]\right)$ is the Sobolev space of order $\delta$.
Let we be given a fixed tr.-c. in $L_{2}^{\text {loc }}$ function $g_{0}(s)$. Evidently, $g_{0}(s)$ is tr.-c. $L_{2, w}^{\text {loc }}$ as well. Consider the set $\left\{g_{0}(s+h) \mid h \in \mathbf{R}_{+}\right\}$. Notice that $\left[\left\{g_{0}(s+h) \mid h \in\right.\right.$ $\left.\left.\mathbf{R}_{+}\right\}\right]_{L_{2, \psi}^{\prime \infty}} \equiv\left[\left\{g_{0}(s+h) \mid h \in \mathbf{R}_{+}\right\}\right]_{L_{2}^{l \infty}}$ and the corresponding topological subspaces of $L_{2, w}^{l o c}$ and $L_{2}^{\text {loc }}$ are homeomorphic. Hence, $\mathcal{H}_{+}\left(g_{0}\right)=\left[\left\{g_{0}(s+h) \mid h \in \mathbf{R}_{+}\right\}\right]_{\Xi}$ does not depend on $\Xi=L_{2, w}^{\text {loc }}$ or $\Xi=L_{2}^{\text {loc }}$. As usually, the topological space $\mathcal{H}_{+}\left(g_{0}\right)$ is compact and any function $g(s) \in \mathcal{H}_{+}\left(g_{0}\right)$ is tr.-c. in $L_{2}^{l o c}, \mathcal{H}_{+}(g) \subseteq \mathcal{H}_{+}\left(g_{0}\right)$, and $\|g\|_{a} \leq\left\|g_{0}\right\|_{a}$.

Now consider the "strong" space $H_{s}^{\text {r,loc }}\left(Q_{+}\right)$introduced in section 1. Recall that $v_{n}(s) \rightarrow v(s)(n \rightarrow \infty)$ in $H_{s}^{\text {r,loc }}\left(Q_{+}\right)$if $\Pi_{t_{1}, t_{2}} v_{n}(s) \rightarrow \Pi_{t_{1}, t_{2}} v(s)(n \rightarrow \infty)$ strongly in
$H^{\mathbf{r}}\left(Q_{t_{1}, t_{2}}\right)$ with respect to the norm (1.3) for any $\left[t_{1}, t_{2}\right] \subseteq \mathbf{R}_{+}$. The linear topological space $H_{s}^{\text {r loc }}\left(Q_{+}\right)$is metrizable and complete.

To any $g \in \mathcal{H}_{+}\left(g_{0}\right)$ there corresponds the trajectory space $\mathcal{K}_{g}^{+}$that is the union of all solutions $u(s), s \geq 0$, of equation (1.1) in the space $H^{\text {r,loc }}\left(Q_{+}\right)$. Consider the family $\left\{\mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$ and the union $\mathcal{K}_{\mathcal{H}_{+}\left(g_{0}\right)}^{+}=\mathcal{U}_{\mathcal{H}_{+}\left(g_{0}\right)} \mathcal{K}_{g}^{+}$.

In this section we study the trajectory attractor $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ of the translation semigroup $\{T(t)\}$ acting on $\mathcal{K}^{+}=\mathcal{K}_{\mathcal{H}_{+}\left(g_{0}\right)}^{+}$in the "strong" topological space $H_{a}^{\mathrm{r}, l o c}\left(Q_{+}\right)$. The set $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ attracts any set $T(t) B$ as $t \rightarrow+\infty$ in the topology of $\Theta_{+}^{\text {loc }}=$ $H_{s}^{\mathbf{r}, l o c}\left(Q_{+}\right)$, where $B \subset \mathcal{K}^{+}$and $B$ is bounded in the Banach space $\mathcal{F}_{+}^{a}=H^{\mathbf{r}, a}\left(Q_{+}\right)$.

Theorem 2.1 Let $g_{0}(s)$ be tr.-c. in $L_{2}^{\text {loc }}$. Then the trajectory attractor $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ in $H_{w}^{\text {r,loc }}\left(Q_{+}\right)$of the translation semigroup $\{T(t)\}$ acting on $\mathcal{K}^{+}$from the Theorem 1.2 serves as the trajectory attractor in $H_{s}^{\mathbf{r}, l o c}\left(Q_{+}\right)$of this semigroup. In particular, for any set $B \subset \mathcal{K}^{+}$

$$
\operatorname{dist}_{H^{\mathrm{r}}\left(Q_{0, \Gamma}\right)}\left(T(t) B, \mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}\right) \rightarrow 0(t \rightarrow \infty) \forall \Gamma>0 .
$$

The set $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ is bounded in $\mathcal{F}^{+}$, compact in $H_{s}^{\text {r,loc }}\left(Q_{+}\right)$. Any function $u(s) \in$ $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ is tr.-c. in $H_{s}^{\text {r }}$,loc $\left(Q_{+}\right)$.

Notice if the trajectory attractor in $H_{s}^{\text {r,loc }}\left(Q_{+}\right)$exists then it coincides with the trajectory attractor $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ in $H_{w}^{\text {r,loc }}\left(Q_{+}\right)$since the embedding $H_{s}^{\text {r,loc }}\left(Q_{+}\right) \subseteq$ $H_{w}^{\text {r }}, l o c\left(Q_{+}\right)$is continuous and the trajectory attractor is the minimal attracting set. So to apply Proposition 1.3 we have to produce an attracting set $P_{1}$ that is compact in $H_{s}^{r, l o c}\left(Q_{+}\right)$and bounded in $\mathcal{F}_{+}^{a}=H^{\mathrm{r}, a}\left(Q_{+}\right)$.

From the continuous embedding $H_{s}^{\mathrm{r}}\left(Q_{t_{1}, t_{2}}\right) \subset C\left(\left[t_{1}, t_{2}\right] ; V\right)$ and from Theorem 2.1, it follows

Corollary 2.1 For any set $B \subset \mathcal{K}^{+}$, bounded in $\mathcal{F}^{+}$, one has

$$
\operatorname{dist}_{C((0, \Gamma) ; V)}\left(\Pi_{0, \Gamma} T(t) B, \Pi_{0, \Gamma} \mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}\right) \rightarrow 0(t \rightarrow \infty) \forall \Gamma \geq 0
$$

Proof of Theorem 2.1. Consider the set $P_{0}^{\prime}=P_{0} \cap \mathcal{K}^{+}$, where $P_{0}$ is the absorbing set constructed in the section 1. Evidently, the set $P_{0}^{\prime}$ is uniformly absorbing for the family $\left\{\mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$. Put

$$
P_{1}=S(1) P_{0}^{\prime}=\left\{\tilde{u}_{g}(s) \equiv u_{g}(s+1), s \geq 0 \mid u_{g}(s) \in \mathcal{K}_{g}^{+} \cap P_{0}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}
$$

The set $P_{1}$ is uniformly absorbing for the family $\left\{\mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$ as well. To complete the proof of Theorem 2.1 we have to establish the following

Lemma 2.1 The set $P_{1}$ is compact in $H_{s}^{\text {r,loc }}\left(Q_{+}\right)$.
It is easy to prove the following statement using the diagonal process.

Proposition 2.1 The set $B$ is compact in $H_{s}^{\mathrm{r}, l o c}\left(Q_{+}\right)$if and only if the set $\Pi_{0, \Gamma} B$ is compact in $H^{\mathrm{r}}\left(Q_{0, \Gamma}\right)$ for any $\Gamma>0$.

Proof of Lemma 2.1. Fix any $\Gamma>0$. Let $\tilde{u}^{n}(s)=T(1) u^{n}(s)=u^{n}(s+1)$ be any sequence from $P_{1}, u^{n}(s) \in \mathcal{K}_{g_{n}}^{+} \cap P_{0}, g_{n} \in \mathcal{H}_{+}\left(g_{0}\right)$. Without lose of generality, we may assume that

$$
\begin{equation*}
\int_{0}^{\Gamma+1}\left|g_{n}(s)-g(s)\right|^{2} d s \rightarrow 0(n \rightarrow \infty) \tag{2.1}
\end{equation*}
$$

for some $g \in \mathcal{H}_{+}\left(g_{0}\right)$. Let us show that the sequence $\left\{\tilde{u}^{n}(s)\right\}$ is precompact in $H^{\mathbf{r}}\left(Q_{0, \Gamma}\right)$. Since $u^{n}(s) \in P_{0}$, we have

$$
\begin{equation*}
\left\|u^{n}(.)\right\|_{H^{\mathbf{r}}\left(Q_{0, \Gamma+1}\right)} \leq M(\Gamma+1) \forall n \in \mathbf{N} \tag{2.2}
\end{equation*}
$$

where the positive function $M(\theta)$ is not decreasing. We can represent the function $u^{n}(s)$ as a sum of two functions:

$$
u^{n}(s)=u_{1}^{n}(s)+u_{2}^{n}(s), s \geq 0
$$

where $u_{1}^{n}(s)$ and $u_{2}^{n}(s)$ are solutions of the following problems:

$$
\begin{align*}
\partial_{t} u_{1}^{n}(t)+L u_{1}^{n}(t) & =0, t \geq 0,  \tag{2.3}\\
u_{1}^{n}(0) & =u_{1}^{n}(0),\left.u_{1}^{n}\right|_{\partial \Omega}=0,\left\|u_{1}^{n}(0)\right\| \leq M_{1}  \tag{2.4}\\
\partial_{t} u_{2}^{n}(t)+L u_{2}^{n}(t) & =-B\left(u^{n}(t)\right)+g_{n}(t), t \geq 0,  \tag{2.5}\\
u_{2}^{n}(0) & =0,\left.u_{2}^{n}\right|_{\partial \Omega}=0 . \tag{2.6}
\end{align*}
$$

Respectively, $\tilde{u}^{n}(s)=\tilde{u}_{1}^{n}(s)+\tilde{u}_{2}^{n}(s)$.
Since $u_{1}^{n}$ is a solution of the Stokes problem (2.3), (2.4), we obtain

$$
\begin{equation*}
\int_{0}^{t+1}\left(\left\|u_{1}^{n}(s)\right\|_{2}^{2}+\left|\partial_{t} u_{1}^{n}(s)\right|^{2}\right) d s \leq M_{2}\left(t+1,\left\|u_{1}^{n}(0)\right\|\right)=M_{3}(t+1) \tag{2.7}
\end{equation*}
$$

$0 \leq t \leq \Gamma$. Let $\psi(t)$ be the cutoff function:

$$
\psi(t) \equiv 1, t \geq 1 ; \psi(t) \equiv 0,0 \leq t \leq 1 / 2 ; \psi \in C_{0}^{\infty}(\mathbf{R}), \psi(t) \geq 0
$$

It follows from (2.3) that

$$
\partial_{t}\left(\psi(t) u_{1}^{n}(t)\right)+L\left(\psi(t) u_{1}^{n}(t)\right)=\psi^{\prime}(t) u_{1}^{n}(t)
$$

Differentiating this equation in $t$ and denoting $\partial_{t}\left(\psi(t) u_{1}^{n}(t)\right)=p^{n}$, we get

$$
\begin{aligned}
\partial_{t} p^{n}+L p^{n} & =\psi^{\prime \prime}(t) u_{1}^{n}(t)+\psi^{\prime}(t) \partial_{t} u_{1}^{n}(t) \\
p^{n}(0) & =0,\left.p^{n}\right|_{\partial \Omega}=0 .
\end{aligned}
$$

So,

$$
\begin{align*}
\int_{0}^{t+1}\left(\left|L \partial_{t}\left(\psi u_{1}^{n}\right)\right|^{2}+\left|\partial_{t}^{2}\left(\psi u_{1}^{n}\right)\right|^{2}\right) d s & =\int_{0}^{t+1}\left(\left\|p^{n}(s)\right\|_{2}^{2}+\left|\partial_{t} p^{n}(s)\right|^{2}\right) d s \leq \\
& C \int_{0}^{t+1}\left(\left|u_{1}^{n}\right|^{2}+\left|\partial_{t} u_{1}^{n}\right|^{2}\right) d s \tag{2.8}
\end{align*}
$$

Combining (2.8) and (2.7), we obtain

$$
\begin{equation*}
\int_{0}^{t+1} \psi^{2}(s)\left(\left\|\partial_{t} u_{1}^{n}(s)\right\|_{2}^{2}+\left|\partial_{t}^{2} u_{1}^{n}(s)\right|^{2}\right) d s \leq M_{5}(t+1) \tag{2.9}
\end{equation*}
$$

Now we apply the operator $L$ to both sides of equation (2.3) and get:

$$
\begin{aligned}
L^{2} u_{1}^{n}(t) & =-\partial_{t} L u_{1}^{n}(t), \\
\left.L u_{1}^{n}\right|_{\partial \Omega} & =-\left.\partial_{t} u_{1}^{n}(t)\right|_{\partial \Omega}=0 .
\end{aligned}
$$

Therefore

$$
\begin{equation*}
\int_{0}^{t+1} \psi^{2}(s)\left|L^{2} u_{1}^{n}(s)\right|^{2} d s=\int_{0}^{t+1} \psi^{2}(s)\left|\partial_{t}\left(L u_{1}^{n}(s)\right)\right|^{2} d s \leq M_{6}(t+1) \tag{2.10}
\end{equation*}
$$

Finally, by virtue of (2.7), (2.9), and (2.10), we conclude:

$$
\int_{1}^{t+1}\left(\left\|\partial_{t} u_{1}^{n}(s)\right\|_{2}^{2}+\left|\partial_{t}^{2} u_{1}^{n}(s)\right|^{2}+\left\|u_{1}^{n}(s)\right\|_{2}^{2}+\left\|u_{1}^{n}(s)\right\|_{4}^{2}\right) d s \leq M_{7}(t+1)
$$

In particular, the sequence $\left\{u_{1}^{n}(s)\right\}$ is compact in $H^{\mathrm{r}}\left(Q_{1, \Gamma+1}\right)$ and $\left\{\tilde{u}_{1}^{n}(s)\right\}$ is compact in $H^{r}\left(Q_{0, \Gamma}\right)$.

Now we shall prove that the sequence $\left\{u_{2}^{n}(s)\right\}$ is compact in $H^{\mathbf{r}}\left(Q_{0, \Gamma+1}\right)$ as well. According to (2.5) it is sufficient to prove that the sequence $B\left(u^{n}(s)\right)=$ $B\left(u^{n}(s), u^{n}(s)\right)$ is precompact in $L_{2}(0, \Gamma+1 ; H)$. (From (2.1) it follows that the sequence $\left\{g_{n}(s)\right\}$ is precompact in $L_{2}(0, \Gamma+1 ; H)$ ). The sequence $\left\{u^{n}(s)\right\}$ is bounded in $H^{\mathrm{r}}\left(Q_{0, \Gamma+1}\right)$, hence, by refining, we may assume that $u_{n}(s)-u(s)(n \rightarrow+\infty)$ weakly in $H^{r}\left(Q_{0, \Gamma+1}\right)$. Thus, $\partial_{t} u_{n}(s)-\partial_{t} u(s)(n \rightarrow+\infty)$ weakly in $L_{2}(0, \Gamma+1 ; H)$ and $\partial^{\alpha} u(s)-\partial^{\alpha} u(s)(n \rightarrow+\infty)$ weakly in $L_{2}(0, \Gamma+1 ; H)$ for any $\alpha=\left(\alpha_{1}, \alpha_{2}\right),|\alpha| \leq 2$. Let us prove that

$$
\begin{equation*}
B\left(u^{n}(s)\right) \rightarrow B(u(s))(n \rightarrow+\infty) \text { strongly in } L_{2}(0, \Gamma+1 ; H) \tag{2.11}
\end{equation*}
$$

By the Nicolskiy theorem (see [3])

$$
\begin{equation*}
H^{\mathbf{r}}\left(Q_{0, \Gamma+1}\right) \subset H_{q}^{\rho}\left(Q_{0, \Gamma+1}\right), \mathbf{r}=\left(r_{1}, r_{2}, r_{3}\right), \rho=\left(\rho_{1}, \rho_{2}, \rho_{3}\right), q \geq 2 \tag{2.12}
\end{equation*}
$$

whenever

$$
\begin{equation*}
\rho_{j} / r_{j} \leq 1-(1 / 2-1 / q)\left(1 / r_{1}+1 / r_{2}+1 / r_{3}\right), j=1,2,3 . \tag{2.13}
\end{equation*}
$$

Moreower, the embedding (2.12) is compact if inequalities in (2.13) are strict.
The values $\mathbf{r}=\left(r_{1}, r_{2}, r_{3}\right)=(2,2,1), \rho=\left(\rho_{1}, \rho_{2}, \rho_{3}\right)=(1,1,0), q \leq 4$ suit the conditions (2.13), since $\rho_{j} / r_{j} \leq 1 / 2 \leq 1-(1 / 2-1 / q) 2$. So we conclude that

$$
\begin{equation*}
\left\|\frac{\partial v}{\partial x_{i}}\right\|_{L_{q}\left(Q_{0, r+1}\right)} \leq C_{q}\|v\|_{H^{\mathbf{r}}\left(Q_{0, r+1}\right)}, i=1,2 ; 2 \leq q \leq 4 . \tag{2.14}
\end{equation*}
$$

For $q<4$ the embedding $H^{\mathrm{r}}\left(Q_{0, \Gamma+1}\right) \subset \subset H_{q}^{(1,1,0)}\left(Q_{0, \Gamma+1}\right)$ is compact. Similarly, taking $\rho=\left(\rho_{1}, \rho_{2}, \rho_{3}\right)=(0,0,0), \rho_{j} / r_{j}=0<1-\left(1 / 2-1 / q_{1}\right) 2$ for any $q_{1} \geq 2$, we obtain

$$
\|v\|_{L_{q_{1}}\left(Q_{0, \Gamma+1}\right)} \leq C_{q_{1}}^{\prime}\|v\|_{H^{\mathbf{r}}\left(Q_{0, \Gamma+1}\right)}
$$

and the embedding $H^{\mathbf{r}}\left(Q_{0, \Gamma+1}\right) \subset \subset L_{q_{1}}\left(Q_{0, \Gamma+1}\right)$ is compact.
Finally we get

$$
\begin{aligned}
&\left\|B\left(u^{n}\right)-B(u)\right\|_{L_{2}(0, \Gamma+1 ; H)} \equiv \\
& C\left(\int_{Q_{0, \Gamma+1}}\left|u^{n}-u\right|^{2}\left|\nabla u^{n}\right|^{2} d x d s\right)^{n}+C\left(u_{Q_{0, \Gamma+1}}|u|^{2}\left|\nabla\left(u^{n}-u\right)\right|^{2} d x d s\right)^{1 / 2} \leq \\
& C_{1}\left(\int_{Q_{0, \Gamma+1}}\left|\nabla u^{n}\right|^{3} d x d s\right)^{1 / 2}\left(\int_{Q_{0, \Gamma+1}}\left|u^{n}-u\right|^{6} d x d s\right)^{1 / 6}+ \\
&(2.15) \quad C_{1}\left(\int_{Q_{0, \Gamma+1}}|u|^{6} d x d s\right)^{1 / 6}\left(\int_{Q_{0, \Gamma+1}}\left|\nabla\left(u^{n}-u\right)\right|^{3} d x d s\right)^{1 / 6}
\end{aligned}
$$

Since $H^{\mathbf{r}}\left(Q_{0, \Gamma+1}\right) \subset \subset H_{3}^{(1,1,0)}\left(Q_{0, \Gamma+1}\right)$ and $H^{\mathbf{r}}\left(Q_{0, \Gamma+1}\right) \subset \subset L_{6}\left(Q_{0, \Gamma+1}\right)$, we get

$$
\int_{Q_{0, \Gamma+1}}\left|\nabla\left(u^{n}-u\right)\right|^{3} d x d s \rightarrow 0, \int_{Q_{0, \Gamma+1}}\left|u^{n}-u\right|^{6} d x d s \rightarrow 0(n \rightarrow \infty)
$$

and, by (2.14) and (2.2),

$$
\int_{Q_{0, r+1}}\left|\nabla u^{n}\right|^{3} d x d s \leq M^{\prime}
$$

Therefore, the right-hand side of (2.15) tends to zero as $n \rightarrow \infty$ and (2.11) is proved.
Thus, the right-hand sides of (2.5) forms a precompact set in $L_{2}(0, \Gamma+1 ; H)$ and, hence, the set of solutions $\left\{u_{2}^{n}(s)\right\}$ is precompact in $H^{\mathbf{r}}\left(Q_{0, \Gamma+1}\right)$. Consequently, $\left\{\tilde{u}_{2}^{n}(s)\right\}$ is precompact in $H^{r}\left(Q_{0, \Gamma}\right)$. The sum $\left\{\tilde{u}^{n}(s)\right\}$ of two precompact sequences $\left\{\tilde{u}_{1}^{n}(s)\right\}$ and $\left\{\tilde{u}_{2}^{n}(s)\right\}$ is precompact in $H^{\mathbf{r}}\left(Q_{0, \Gamma}\right)$. Lemma 2.1 is proved.

## 3 On the structure of trajectory attractors

In this section we shall describe the structure of trajectory attractors from Theorems 1.2 and 2.1 in terms of complete trajectories of equation 1.1, i.e. when solutions $u(s), s \in \mathbf{R}$, are determined on the whole time axis $\mathbf{R}$.

Let the function $g_{0}(x, s)$ satisfies (1.2) and let $\mathcal{H}_{+}\left(g_{0}\right)$ be the hull of $g_{0}$ in $L_{2, w}^{\text {loc }}\left(\mathbf{R}_{+}, H\right)$. As usually, $\mathcal{H}_{+}\left(g_{0}\right)$ is a complete metric space and the translation semigroup $\{T(t)\}$ acts on $\mathcal{H}_{+}\left(g_{0}\right), T(t) \mathcal{H}_{+}\left(g_{0}\right) \subseteq \mathcal{H}_{+}\left(g_{0}\right), \quad T(t)$ is continuous for any $t \geq 0$. Consider the attractor $\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ of the semigroup $\{T(t)\}$ on $\mathcal{H}_{+}\left(g_{0}\right)$,

$$
\begin{equation*}
T(t) \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)=\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right) \forall t \geq 0 \tag{3.1}
\end{equation*}
$$

(See Proposition 1.2).
Similarly to $L_{2}^{l o c}\left(\mathbf{R}_{+}, H\right)$ and $L_{2}^{a}\left(\mathbf{R}_{+}, H\right)$ we consider spaces $L_{2}^{l o c}(\mathbf{R}, H)$ and $L_{2}^{a}(\mathbf{R}, H)$ of functions on the whole axis. The space $L_{2}^{a}(\mathbf{R}, H)$ has a norm:

$$
\|\zeta\|_{L_{2}^{a}(\mathbf{R} ; H)}^{2}=\sup _{t \in \mathbf{R}} \int_{t}^{t+1}|\zeta(s)|^{2} d s<+\infty
$$

Consider any external force $g \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$. The invariance property (3.1) implies that there is a function $g_{1}(s), g_{1} \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ such that $T(1) g_{1}=g$. Consider the function $\zeta(s), s \geq-1, \zeta(s)=g_{1}(s+1)$. Obviously, $\zeta(s) \equiv g(s)$ for $s \geq 0$, hence, $\zeta(s)$ is a prolongation of $g(s)$ on the semiaxis $[-1,+\infty[$. In such doing, there is $g_{2} \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ such that $T(1) g_{2}=g_{1}, T(2) g_{2}=g$. Put $\zeta(s)=g_{2}(s+2)$ for $s \geq-2$. Evidently, the function $\zeta(s)$ is well defined, since $g_{2}(s+2)=g_{1}(s+1)$ for $s \geq-1$. Continuing this process, we define $\zeta(s)=g_{n}(s+n)$ for $s \in[-n,+\infty[$, where $g_{n} \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ and $n \in \mathbf{N}$. We have defined a function $\zeta(s), s \in \mathbf{R}$, which is a prolongation of the initial external force $\zeta(s), s \in \mathbf{R}_{+}$. Moreover, the function $\zeta(s)$ satisfies the following property: $\Pi_{+} \zeta_{t}(s) \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ for any $t \in \mathbf{R}$, where $\zeta_{t}(s)=\zeta(t+s)$. Here $\Pi_{+}=\Pi_{0, \infty}$ is the restriction operator to the semiaxis $\mathbf{R}_{+}$. Evidently, $\zeta(s) \in L_{2}^{a}(\mathbf{R}, H)$ and $\|\zeta\|_{L_{2}^{a}(\mathbf{R}: H)}^{2} \leq\left\|g_{0}\right\|_{L_{2}^{a}\left(\mathbf{R}_{+} ; H\right)}^{2}$.

Definition 3.1 (i) A function $\zeta(s) \in L_{2}^{a}(\mathbf{R}, H)$ is said to be a complete external force in $\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ if $\Pi_{+} \zeta_{t}(s)=\Pi_{+} \zeta(t+s) \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$, $s \in \mathbf{R}_{+}$, for any $t \in \mathbf{R}$.
(ii) Let $Z\left(g_{0}\right)$ be the set of all complete external forces in $\mathcal{H}_{+}\left(g_{0}\right)$.

As it was showed above, for any symbol $g \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ there exist at least one complete external force $\zeta(s)$ which is the prolongation of $g$ for negative $s$. Notice at once, that, in general, this prolongation need not be unique.

By analogy to section 1, we introduce in the cylinder $Q=\Omega \times \mathbf{R}$ the space $H^{\mathrm{r}, l o c}(Q)=L_{2}^{l o c}\left(\mathbf{R} ; H_{2}\right) \cap\left\{\partial_{t} v \in L_{2}^{\text {loc }}(\mathbf{R} ; H)\right\}$, i.e. $v(s) \in H^{\mathbf{r}, l o c}(Q)$ if

$$
\left\|\Pi_{t_{1}, t_{2}} v\right\|_{\left.H \mathbf{r}_{\left(Q_{1}, t_{2}\right.}\right)}^{2}<+\infty \forall\left[t_{1}, t_{2}\right] \subseteq \mathbf{R}
$$

We shall use the topological spaces $H_{s}^{\text {r,loc }}(Q), H_{w}^{\text {r,loc }}(Q)$, and the Banach space $H^{\mathbf{r}, a}(Q)$ with the norm:

$$
\|v\|_{H^{\mathbf{r}, \mathbf{a}}(Q)}^{2}=\|v\|_{\mathbf{r}, a}^{2}=\sup _{t \in \mathbf{R}}\left\|\Pi_{t, t+1} v\right\|_{H^{\mathbf{r}}\left(Q_{t, t+1}\right)}^{2} .
$$

Let we be given some complete external force $\zeta(s), s \in \mathbf{R}$, in $\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$. Consider the equation

$$
\begin{equation*}
\partial_{t} u+\nu L u+B(u)=\zeta(x, t),(\nabla, u)=0,\left.u\right|_{\partial \Omega}=0, x \in \Omega, t \in \mathbf{R} \tag{3.2}
\end{equation*}
$$

Definition 3.2 The kernel $\mathcal{K}_{\zeta}$ of equation (3.2) with the complete external force $\zeta(s) \in Z\left(g_{0}\right)$ is the set of all solutions $u(s), s \in \mathbf{R}$, of the equation (3.2) that are bounded in the space $H^{\mathbf{r}, a}(Q)$.

The following Theorem specifies the structure of the trajectory attractor from Theorems 1.2 and 2.1.

Theorem 3.1 (i) Let $g_{0}(s)$ be tr.-c. in $L_{2, w}^{\text {loc }}\left(\mathbf{R}_{+}, H\right)$ then the trajectory attractor $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ in $H_{w}^{\text {r,loc }}\left(Q_{+}\right)$of the translation semigroup $\{T(t)\}$ acting on $\mathcal{K}^{+}=\mathcal{K}_{\mathcal{H}_{+}\left(g_{0}\right)}^{+}$ can be represented in the form:

$$
\begin{equation*}
\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}=\mathcal{A}_{\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)}=\Pi_{+} \bigcup_{\zeta \in Z\left(g_{0}\right)} \mathcal{K}_{\zeta}=\Pi_{+} \mathcal{K}_{Z\left(g_{0}\right)} . \tag{3.3}
\end{equation*}
$$

The set $\mathcal{K}_{Z\left(g_{0}\right)}$ is compact in $H_{w}^{\mathbf{r}, l o c}(Q)$ and it is bounded in $H^{\mathbf{r}, a}(Q)$. For any $\zeta \in$ $Z\left(g_{0}\right)$ the kernel $\mathcal{K}_{\zeta}$ is not empty. Any function $u(s) \in \mathcal{K}_{\zeta}$ is tr.-c. in $H_{w}^{\text {r,loc }}(Q)$.
(ii) Let $g_{0}(s)$ be tr.-c. in $L_{2}^{l o c}\left(\mathbf{R}_{+}, H\right)$ then the set $\mathcal{K}_{Z\left(g_{0}\right)}$ is compact in $H_{s}^{\text {r,loc }}(Q)$ and any function $u(s) \in \mathcal{K}_{\zeta}$ is tr.-c. in $H_{s}^{\text {r,loc }}(Q)$.

The proof of Theorem 3.1 is given in [5] and it uses the invariance property 1.6 of the trajectory attractor $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}: T(t) \mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}=\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)} \forall t \geq 0$.

Remark 3.1 It was mentioned above that, in general, the prolongation $\zeta(s)$ of an external force $g(s) \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ for $s<0$ need not be unique. Let us describe an important case when it is unique. Let $g_{0}(s)$ be tr.-c. function in $L_{2}^{a}\left(\mathbf{R}_{+} ; H\right)$, i.e. the set $\left\{g_{0}(s+h) \mid h \in \mathbf{R}_{+}\right\}$is precompact in the Banach space $L_{2}^{a}\left(\mathbf{R}_{+} ; H\right)$ with the uniform norm (1.2) and, hence, the hull $\mathcal{H}_{+}\left(g_{0}\right)$ is compact in $L_{2}^{a}\left(\mathbf{R}_{+} ; H\right)$. It can be proved that there exists a unique function $\tilde{g}_{0}(s), s \in \mathbf{R}$, such that $\tilde{g}_{0}(s)$ is tr.-c. in $L_{2}^{a}(\mathbf{R} ; H)$ and

$$
\int_{t}^{t+1}\left|g_{0}(s)-\tilde{g}_{0}(s)\right|^{2} d s \rightarrow 0(t \rightarrow \infty)
$$

Therefore, $\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)=\mathcal{H}_{+}\left(\tilde{g}_{0}\right)$. Tr.-c. functions in $L_{2}^{a}(\mathbf{R} ; H)$ are also called almost periodic functions in the Stepanov sence. These functions meet all the main properties of usual almost periodic function (in the Bohr or Bochner-Amerio sence,
see [1]). In particular, the translation semigroup $\{T(t)\}$ is invertible on $\mathcal{H}_{+}\left(\tilde{g}_{0}\right)$ and $\mathcal{H}_{+}\left(\tilde{g}_{0}\right)=\Pi_{+} \mathcal{H}\left(\tilde{g}_{0}\right)$, where $\mathcal{H}\left(\tilde{g}_{0}\right)=\left[\left\{\tilde{g}_{0}(s+h) \mid h \in \mathbf{R}\right\}\right]_{L_{2}(\mathbf{R} ; H)}$ is a hull of the almost periodic function $\tilde{g}_{0}$. Finally, in (3.3) $Z\left(g_{0}\right)=\mathcal{H}\left(\tilde{g}_{0}\right)$ and every external force $g(s) \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ possesses a unique prolongation for $s<0$ as an almost periodic function.

To conclude the section we describe the uniform (w.r.t. $g \in \mathcal{H}_{+}\left(g_{0}\right)$ ) attractor $\mathbf{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ for the family of processes $\left\{U_{g}(t, \tau) \mid t \geq \tau \geq 0\right\}, g \in \mathcal{H}_{+}\left(g_{0}\right)$, corresponding to the equation (1.1). By Theorem 1.1, for any $g \in \mathcal{H}_{+}\left(g_{0}\right)$, one defines a process $\left\{U_{g}(t, \tau) \mid t \geq \tau \geq 0\right\}$ acting on $V: U_{g}(t, \tau) u_{\tau}=u_{g}(t)$, where $u_{g}(t)$ is a solution of (1.1) with the initial condition $\left.u\right|_{t=\tau}=u_{\tau}, \tau \geq 0$. Now consider the set $Z\left(g_{0}\right)$. By the similar way, to any $\zeta \in Z\left(g_{0}\right)$ there corresponds a complete process $\left\{U_{\zeta}(t, \tau) \mid t \geq\right.$ $\tau, \tau \in \mathbf{R}\}, U_{g}(t, \tau) u_{\tau}=u_{\zeta}(t)$, where $u_{\zeta}(t)$ is a solution of (3.2) with the initial condition $\left.u\right|_{t=\tau}=u_{\tau}, \tau \in \mathbf{R}$. Consider the kernel $\mathcal{K}_{\zeta}$ corresponding to $\zeta$.

By $\mathcal{K}_{\zeta}(t)$ we denote a kernel section at time $t \in \mathbf{R}: \mathcal{K}_{\zeta}(t)=\{u(t) \mid u(.) \in$ $\left.\mathcal{K}_{\zeta}\right\} \subset V$. It is clear that

$$
U_{\zeta}(t, \tau) \mathcal{K}_{\zeta}(\tau)=\mathcal{K}_{\zeta}(t) \forall t \geq \tau, \tau \in \mathbf{R} .
$$

Using Theorem 3.1, Corollary 2.1, and Corollary 1.2 we get
Corollary 3.1 (i) If $g_{0}(s)$ is tr.-c. in $L_{2}^{l o c}\left(\mathbf{R}_{+}, H\right)$ then the set

$$
\begin{equation*}
\mathbf{A}_{\mathcal{H}_{+}\left(g_{0}\right)}=\bigcup_{\zeta \in Z\left(g_{0}\right)} \mathcal{K}_{\zeta}(0) \tag{3.4}
\end{equation*}
$$

is the uniform (w.r.t. $g \in \mathcal{H}_{+}\left(g_{0}\right)$ ) attractor $\mathbf{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ in $V$ of the family of processes $\left\{U_{g}(t, \tau) \mid t \geq \tau \geq 0\right\}, g \in \mathcal{H}_{+}\left(g_{0}\right)$, the set $\mathbf{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ is compact in $V$.
(ii) If $g_{0}(s)$ is tr.-c. in $L_{2, \omega}^{\text {loc }}\left(\mathbf{R}_{+}, H\right)$ then the set $\mathbf{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ defined in (3.4) serves as the uniform (w.r.t. $g \in \mathcal{H}_{+}\left(g_{0}\right)$ ) attractor in $V_{w}$ (with a weak topology of $V$ ) and it is bounded in $V$. In particular, $\mathbf{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ is the uniform attractor in $H_{1-\delta}, \mathbf{A}_{\mathcal{H}_{+}\left(g_{0}\right)} \subset \subset$ $H_{1-\delta}, 0<\delta \leq 1$.

## 4 Trajectory attractors for 3D N.-S. system.

In this section we shall construct a trajectory attractor for the non-autonomous Navier-Stokes system in a 3D domain $\Omega \subset \subset \mathbf{R}^{3}$. The structure of the trajectory attractor will be described and some properties of the attractor will be given. Only the brief general scheme will be sketched, without proofs and detailed explanations. This part will be expounded in more detail in another publication (see also [7], [10], [18]).

Consider 3D Navier-Stokes system in the semicylinder $Q_{+}=\Omega \times \mathbf{R}_{+}$:
(4.1) $\partial_{t} u+\nu L u+B(u)=g(x, t),(\nabla, u)=0,\left.u\right|_{\partial \Omega}=0, x \in \Omega \subset \subset \mathbf{R}^{3}, t \geq 0$,
where, $x=\left(x_{1}, x_{2}, x_{3}\right), u=u(x, t)=\left(u^{1}, u^{2}, u^{3}\right), g=g(x, t)=\left(g^{1}, g^{2}, g^{3}\right) . L$ is the 3D Stokes operator: $L u=-P \Delta u ; B(u)=B(u, u), B(u, v)=P(u, \nabla) v=$ $P \sum_{i=1}^{3} u_{i} \partial_{x_{i}} v$. The spaces $H$ and $V$ are determined similar to the 2D case. Suppose $g(x, t) \in L_{2}^{l o c}\left(\mathbf{R}_{+}, H\right)$.

Let we are given an initial external force $g_{0}(x, t) \in L_{2}^{\text {loc }}\left(\mathbf{R}_{+}, H\right)$ in (4.1). Assume that $g_{0}$ is $\operatorname{tr}$.-c. in $L_{2, w}^{l o c}\left(\mathbf{R}_{+}, H\right) \equiv L_{2, w}^{l o c}$, i.e.

$$
\begin{equation*}
\left\|g_{0}\right\|_{L_{2}^{a}\left(\mathbf{R}_{+} ; V^{\prime}\right)}^{2}=\left\|g_{0}\right\|_{a}^{2}=\sup _{t \in \mathbf{R}_{+}} \int_{t}^{t+1}\left|g_{0}(s)\right|^{2} d s<+\infty \tag{4.2}
\end{equation*}
$$

Let $\Sigma=\mathcal{H}_{+}\left(g_{0}\right) \equiv\left[\left\{g_{0}(s+t) \mid t \geq 0\right\}\right]_{L_{2,4}^{\prime \infty}\left(\mathbf{R}_{+}, V^{\prime}\right)}$ be a hull of the function $g_{0}(s)$ in the space $L_{2, w}^{\text {loc }}\left(\mathbf{R}_{+}, H\right)$. It can be proved that $\mathcal{H}_{+}\left(g_{0}\right)$ is a complete metric space. The translation semigroup $\{T(t)\}$ is continuous on $\mathcal{H}_{+}\left(g_{0}\right)$ and $T(t) \mathcal{H}_{+}\left(g_{0}\right) \subseteq \mathcal{H}_{+}\left(g_{0}\right)$ for any $t \geq 0$, moreower, for any $g \in \mathcal{H}_{+}\left(g_{0}\right)$ one has: $\|g\|_{a}^{2} \leq\left\|g_{0}\right\|_{a}^{2}$.

To study the trajectory attractor of the equation (4.1) we consider the family of these equations with various external forces $g \in \mathcal{H}_{+}\left(g_{0}\right)$.

To describe a trajectory space $\mathcal{K}_{g}^{+}$of equation (4.1) with the external force $g$ we shall consider weak solutions of equation (4.1) in the space $L_{2}^{\text {loc }}\left(\mathbf{R}_{+} ; V\right) \cap$ $L_{\infty}^{l o c}\left(\mathbf{R}_{+} ; H\right)$. If $u(s) \in L_{2}^{l o c}\left(\mathbf{R}_{+} ; V\right) \cap L_{\infty}^{l o c}\left(\mathbf{R}_{+} ; H\right)$ then equation (4.1) makes sence in the distribution space $D^{\prime}\left(\mathbf{R}_{+} ; V^{\prime}\right)$, where $V^{\prime}$ is the dual space of $V$. This is a usual way to define weak solutions of equation (4.1) (see [16]).

Definition 4.1 The trajectory space $\mathcal{K}_{g}^{+}$is the union of all weak solutions $u(s) \in$ $L_{2}^{\text {loc }}\left(\mathbf{R}_{+} ; V\right) \cap L_{\infty}^{\text {loc }}\left(\mathbf{R}_{+} ; H\right)$ of equation (4.1) with the external force $g$ that satisfy the following inequality:

$$
\begin{equation*}
\frac{1}{2} \frac{d}{d t}|u(t)|^{2}+\nu\|u(t)\|^{2} \leq(g(t), u(t)), t \in \mathbf{R}_{+} . \tag{4.3}
\end{equation*}
$$

The equality (4.3) should be read as follows: for any function $\psi(s) \in C_{0}^{\infty}(] 0,+\infty[)$, $\psi \geq 0$,
(4.4) $-\frac{1}{2} \int_{0}^{+\infty}|u(s)|^{2} \psi^{\prime}(s) d s+\nu \int_{0}^{+\infty}\|u(s)\|^{2} \psi(s) d s \leq \int_{0}^{+\infty}(g(s), u(s)) \psi(s) d s$.

Let us formulate the existence
Theorem 4.1 Let $g \in L_{2}^{l o c}\left(\mathbf{R}_{+} ; H\right)$ and $u_{0} \in H$; then there exists a weak solution $u(s)$ of equation (4.1) belonging to the space $L_{2}^{\text {loc }}\left(\mathbf{R}_{+} ; V\right) \cap L_{\infty}^{l o c}\left(\mathbf{R}_{+} ; H\right)$ such that $u(0)=u_{0}$ and $u(s)$ satisfies the inequality (4.4).

The existence theorem is a classical result (see [14], [15], [16], [19]). The proof uses the Faedo-Galerkin approximations method. To get inequality (4.4) one has to pass to the limit in the corresponding a priori equality involving the sequence $\left\{u_{m}\right\}$ of the Faedo-Galerkin approximations.

Remark 4.1 For $3 D$ case, the uniqueness problem is still open. Also, it is not known whether any weak solution of (4.1) satisfies inequality (4.3).

It can be showed that any weak solution $u(s) \in L_{2}^{l o c}\left(\mathbf{R}_{+} ; V\right) \cap L_{\infty}^{\text {loc }}\left(\mathbf{R}_{+} ; H\right)$ of the equation (4.1) satisfies

$$
\partial_{t}^{1 / 4-\varepsilon} u \in L_{2}^{l o c}\left(\mathbf{R}_{+} ; H\right) \forall \varepsilon 0<\varepsilon<1 / 4
$$

(see [16]), and

$$
\partial_{\mathrm{t}} u \in L_{4 / 3}^{\mathrm{loc}}\left(\mathbf{R}_{+} ; V^{\prime}\right)
$$

(see $[20]$ ). Consider the following space:

$$
\begin{aligned}
\mathcal{F}_{+}^{l o c} & =L_{2}^{l o c}\left(\mathbf{R}_{+} ; V\right) \cap L_{\infty}^{l o c}\left(\mathbf{R}_{+} ; H\right) \cap \\
\left\{v \mid \partial_{t}^{1 / 4-c} v\right. & \left.\in L_{2}^{l o c}\left(\mathbf{R}_{+} ; V^{\prime}\right)\right\} \cap\left\{v \mid \partial_{t} v \in L_{4 / 3}^{l o c}\left(\mathbf{R}_{+} ; V^{\prime}\right)\right\}
\end{aligned}
$$

where $\varepsilon$ is fixed, $0<\varepsilon<1 / 4$. The space $\mathcal{F}_{+}^{\text {loc }}$ is endowed with the following "weak" convergence topology.
Definition 4.2 A sequence $\left\{v_{n}\right\} \subset \mathcal{F}_{+}^{\text {loc }}$ converges (in a weak sense) to $v \in \mathcal{F}_{+}^{\text {loc }}$ as $t \rightarrow \infty$ if $v_{n}(s) \rightarrow v(s)(n \rightarrow \infty)$ weakly in $L_{2}\left(t_{1}, t_{2} ; V\right)$, *-weakly in $L_{\infty}\left(t_{1}, t_{2} ; H\right)$, $\partial_{t}^{1 / 4-e} v_{n}(s) \rightarrow \partial_{t}^{1 / 4-\varepsilon} v(s)(n \rightarrow \infty)$ weakly in $\left.L_{2}\left(t_{1}, t_{2} ; H\right)\right\}$, and $\partial_{t} v_{n}(s) \rightarrow \partial_{t} v(s)$ $(n \rightarrow \infty)$ weakly in $\left.L_{4 / 3}\left(t_{1}, t_{2} ; V^{\prime}\right)\right\}$ for any $\left[t_{1}, t_{2}\right] \subset \mathbf{R}_{+}$.

The space $\mathcal{F}_{+}^{\text {loc }}$ with the above weak topology is denoted by $\Theta_{+}^{\text {loc }}$. We shall use also the space

$$
\begin{aligned}
\mathcal{F}_{+}^{a} & =L_{2}^{a}\left(\mathbf{R}_{+} ; V\right) \cap L_{\infty}^{a}\left(\mathbf{R}_{+} ; H\right) \cap \\
\left\{v \mid \partial_{t}^{1 / 4-\epsilon} v\right. & \left.\in L_{2}^{a}\left(\mathbf{R}_{+} ; V^{\prime}\right)\right\} \cap\left\{v \mid \partial_{\mathrm{t}} v \in L_{4 / 3}^{a}\left(\mathbf{R}_{+} ; V^{\prime}\right)\right\}
\end{aligned}
$$

that is a subspace of $\mathcal{F}_{+}^{\text {loc }}$. If $X$ is a Banach space then $L_{p}^{a}\left(\mathbf{R}_{+} ; X\right)$ means the subspace of $L_{p}^{l o c}\left(\mathbf{R}_{+} ; X\right)$ having the finite norm

$$
\|v\|_{L_{p}^{a}\left(\mathbf{R}_{+} ; X\right)}^{p}=\sup _{t \geq 0} \int_{t}^{t+1}\|v(s)\|_{X}^{p} d s
$$

Similarly, the space $L_{p}^{a}(\mathrm{R} ; X)$ has the norm

$$
\|v\|_{L_{p}^{a}(\mathbf{R} ; X)}^{p}=\sup _{t \in \mathbf{R}} \int_{t}^{t+1}\|v(s)\|_{X}^{p} d s
$$

Lemma 4.1 (i) $\mathcal{K}_{g}^{+} \in \mathcal{F}_{+}^{a}$ for any $g \in \mathcal{H}_{+}\left(g_{0}\right)$;
(ii) for any $u(s) \in \mathcal{K}_{g}^{+}$

$$
\begin{equation*}
\|T(t) u(.)\|_{\mathcal{F}_{+}^{a}} \leq C\|u(.)\|_{L_{\infty}(0,1 ; H)}^{2} \exp (-\lambda t)+R_{0} \forall t \geq 0 \tag{4.5}
\end{equation*}
$$

where $\lambda$ is the first eigenvalue of the operator $\nu L ; C$ depends on $\lambda$ and $R_{0}$ depends on $\lambda$ and $\left\|g_{0}\right\|_{L_{2}^{a}\left(\mathrm{R}_{+} ;{ }^{\prime \prime}\right)}^{2}$.

Put

$$
\mathcal{K}_{\Sigma}^{+}=\bigcup_{g \in \mathcal{H}_{+}\left(g_{0}\right)} \mathcal{K}_{g}^{+}, \Sigma=\mathcal{H}_{+}\left(g_{0}\right) .
$$

The translation semigroup $\{T(t) \mid t \geq 0\}$ acts on $\mathcal{K}_{\Sigma}^{+}$:

$$
T(t) u(s)=u(t+s), s \geq 0
$$

Evidently

$$
T(t) u(s) \in \mathcal{K}_{T(t) g}^{+} \forall u \in \mathcal{K}_{g}^{+}, t \geq 0
$$

so, the family $\left\{\mathcal{K}_{g}^{+}, g \in \mathcal{H}_{+}\left(g_{0}\right)\right\}$ is translation-coordinated. Therefore

$$
T(t) \mathcal{K}_{\Sigma}^{+} \subseteq \mathcal{K}_{\Sigma}^{+} \forall t \geq 0
$$

It is clear that every mapping $T(t)$ is continuous in $\Theta_{+}^{l o c}$.
It follows from (4.5) that the ball $B_{0}=\|v\|_{\mathcal{F}_{+}^{a}} \leq 2 R_{0}$ serves as a uniformly absorbing set of the translation semigroup $\{T(t)\}$ acting on $\mathcal{K}_{\Sigma}^{+}$. The set $B_{0}$ is bounded in $\mathcal{F}_{+}^{a}$ and it is compact in $\Theta_{+}^{\text {loc }}$.

Lemma 4.2 The family $\left\{\mathcal{K}_{g}^{+}, g \in \Sigma\right\}$ is $\left(\Theta_{+}^{\text {loc }}, \mathcal{H}_{+}\left(g_{0}\right)\right)$-closed and $\mathcal{K}_{\Sigma}^{+}$is closed in $\Theta_{+}^{\text {loc }}$.

In such a way, by Lemmas 4.1 and 4.2 , Proposition 1.2 is applicable.
Let $\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ denote the global attractor of the semigroup $\{T(t)\}$ on $\mathcal{H}_{+}\left(g_{0}\right)$. Here

$$
\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)=\bigcap_{\tau \geq 0}\left[\bigcup_{t \geq \tau} T(t) \mathcal{H}_{+}\left(g_{0}\right)\right]_{L_{2, \omega}^{1 \infty}}
$$

is an $\omega$-limit set of $\mathcal{H}_{+}\left(g_{0}\right)$.
Let $Z\left(g_{0}\right)$ be the set of all complete external forces in $\mathcal{H}_{+}\left(g_{0}\right)$, i.e. the set of all functions $\zeta(s), s \in \mathbf{R}, \zeta(s) \in L_{2}^{\text {loc }}(\mathbf{R}, H)$ such that $\zeta_{t} \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ for any $t \in \mathbf{R}$, where $\zeta_{t}(s)=\Pi_{+} \zeta(s+t), s \geq 0$. Evidently, for any $g(s) \in \omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)$ there is at least one function $\zeta \in Z\left(g_{0}\right)$ such that $\zeta(s)$ is a prolongation $g(s)$ for negative $s$. To any complete external force $\zeta \in Z\left(g_{0}\right)$ there corresponds the kernel $\mathcal{K}_{\zeta}$ of equation (4.1). The kernel $\mathcal{K}_{\zeta}$ consists of all weak solutions $u(s), s \in \mathbf{R}$, of the equation

$$
\partial_{t} u+\nu L u+B(u)=\zeta(x, t), t \in \mathbf{R}
$$

that satisfy inequality (4.4) and that are bounded in the space

$$
\begin{aligned}
\mathcal{F}^{a} & =L_{2}^{a}(\mathbf{R} ; V) \cap L_{\infty}^{a}(\mathbf{R} ; H) \cap \\
\left\{v \mid \partial_{t}^{1 / 4-\varepsilon} v\right. & \left.\in L_{2}^{a}\left(\mathbf{R} ; V^{\prime}\right)\right\} \cap\left\{v \mid \partial_{t} v \in L_{4 / 3}^{a}\left(\mathbf{R} ; V^{\prime}\right)\right\} .
\end{aligned}
$$

Let us formulate the main

Theorem 4.2 Let $g_{0}(s)$ be tr.-c. in $L_{2, w}^{\text {loc }}\left(\mathbf{R}_{+} ; H\right)$ then the translation semigroup $\{T(t)\}$ acting on $\mathcal{K}_{\Sigma}^{+}\left(\Sigma=\mathcal{H}_{+}\left(g_{0}\right)\right)$ possesses a trajectory attractor $\mathcal{A}_{\Sigma}=\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ in $\Theta_{+}^{\text {loc }}$. The set $\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$ is bounded in $\mathcal{F}_{+}^{a}$ and compact in $\Theta_{+}^{\text {loc }}$. Moreower,

$$
\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}=\mathcal{A}_{\omega\left(\mathcal{H}_{+}\left(g_{0}\right)\right)}=\Pi_{+} \bigcup_{\zeta \in Z\left(g_{0}\right)} \mathcal{K}_{\zeta}=\Pi_{+} \mathcal{K}_{Z\left(g_{0}\right)}
$$

The kernel $\mathcal{K}_{\zeta}$ is not empty for any $\zeta \in Z\left(g_{0}\right)$; the set $\mathcal{K}_{Z\left(g_{0}\right)}$ is bounded in $\mathcal{F}^{a}$ and compact in $\Theta^{\text {loc }}$.

The detailed proof of Lemma 4.1, Lemma 4.2, and Theorem 4.2 will be given in [5].

Notice that the following embedding is continuous: $\Theta_{+}^{\text {loc }} \subset L_{2}^{\text {loc }}\left(\mathbf{R}_{+} ; H_{1-\delta}\right), 0<$ $\delta \leq 1$, so, we get

Corollary 4.1 For any set $B \subset \mathcal{K}^{+}$bounded in $\mathcal{F}_{+}^{a}$

$$
\operatorname{dist}_{L_{2}\left(0, \Gamma ; H_{1-\delta}\right)}\left(\Pi_{0, \Gamma} T(t) B, \Pi_{0, \Gamma} \mathcal{K}_{Z\left(g_{0}\right)}\right) \rightarrow 0(t \rightarrow \infty)
$$

where $\Gamma$ is fixed and any.
In conclusion, we shall formulate some properties of trajectory attractors of the Navier-Stokes system.
I) Let in (4.1) $g_{0}(x, s)=g_{1}(x, s)+a(x, s)$, where $g_{1}(x, s)$ and $a(x, s)$ are tr.-c. functions in $L_{2, w}^{\text {loc }}\left(\mathbf{R}_{+} ; H\right)$. Assume that $T(t) a \rightarrow 0(t \rightarrow+\infty)$ in $L_{2, w}^{\text {loc }}\left(\mathbf{R}_{+} ; H\right)$, i.e.

$$
\begin{equation*}
\int_{0}^{1}(a(s+t), \psi(s)) d s \rightarrow 0(t \rightarrow+\infty) \tag{4.6}
\end{equation*}
$$

for any $\psi(s) \in L_{2}(0,1 ; H)$. Then the trajectory attractors corresponding to $\Sigma=$ $\mathcal{H}_{+}\left(g_{1}+a\right)$ and to $\Sigma_{1}=\mathcal{H}_{+}\left(g_{1}\right)$ coincide:

$$
\begin{equation*}
\mathcal{A}_{\mathcal{H}_{+}\left(g_{1}+a\right)}=\mathcal{A}_{\mathcal{H}_{+}\left(g_{1}\right)} \tag{4.7}
\end{equation*}
$$

In particular, if $g_{1} \equiv 0$ then $\mathcal{A}_{\mathcal{H}_{+}(a)}=\mathcal{A}_{\mathcal{H}_{+}(0)}=\{0\}$.
For example, the function $a(x, s)=\varphi(x) \sin \left(t^{2}\right)$ satisfies (4.6) for any $\varphi \in H$. Thus more and more rapidly oscillating additional term $a(s)$ does not effect on the trajectory attractor. The equality (4.7) is valid as for 3D as for 2D N.-S. systems.
II) Let in (4.1) $g_{0}(x, s)=g_{0 c}(x, s)=g_{1}(x, s)+\varepsilon g_{2}(x, s)$, where $g_{i}(x, s)$ are tr.-c. functions in $L_{2, w}^{\text {loc }}\left(\mathbf{R}_{+} ; H\right)$ and $|\varepsilon| \leq 1$. Put $\mathcal{A}(\varepsilon)=\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}$. Then $\mathcal{A}(\varepsilon)$ is lower semi-continuous with respect to $\varepsilon$. More precisely. It can be proved that the ball $B_{0}=\|v\|_{\mathcal{F}_{+}} \leq R_{1}$ being a topological subspace of $\Theta_{+}^{l o c}$ is metrizable and in this metric:

$$
\begin{equation*}
\operatorname{dist}_{\theta_{+}^{\text {loc }}}(\mathcal{A}(\varepsilon), \mathcal{A}(0)) \rightarrow 0(t \rightarrow \infty) \tag{4.8}
\end{equation*}
$$

The radius $R_{1}$ is big enough to provide the inclusion: $\mathcal{A}(\varepsilon) \subseteq B_{1}$ for any $\varepsilon,|\varepsilon| \leq 1$. For the 2D N.-S. system (1.1) the property (4.8) is also valid with dist $_{\theta_{+}^{l o c}}$ being replaced by dist ${ }_{H} \mathbf{r}$,ioc or by $\operatorname{dist}_{H_{w}^{\text {r.loc }}}$ depending on the tr.-c. class the external force belongs to.
III) Let $\mathcal{A}_{\mathcal{H}_{+}\left(P_{N} g_{0}\right)}^{(N)} \equiv \mathcal{A}^{(N)}$ be the trajectory attractor of the Faedo-Galerkin approximation system of order $N$ for the equation (4.1), where $P_{N}$ is the projection onto the finite-dimensional subspace of $H$ spanned by the first $N$ eigenfunctions of the Stokes operator. Then

$$
\operatorname{dist}_{\Theta_{+}^{\text {loc }}}\left(\mathcal{A}^{(N)}, \mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}\right) \rightarrow 0(t \rightarrow \infty)
$$

In other words, for any neighbourhood $\mathcal{O}\left(\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}\right)$ in $\Theta_{+}^{\text {loc }}$ there is $N_{1}$ such that $\mathcal{A}^{(N)} \subseteq \mathcal{O}\left(\mathcal{A}_{\mathcal{H}_{+}\left(g_{0}\right)}\right)$ for any $N \geq N_{1}$.

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Institut for Information Transmission Problems
Russian Academy of Sciences
str. Ermolovoy 19, Moscow 101447, GSP-4, Russia
e-mail: chep@ippi.ac.msk.su


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