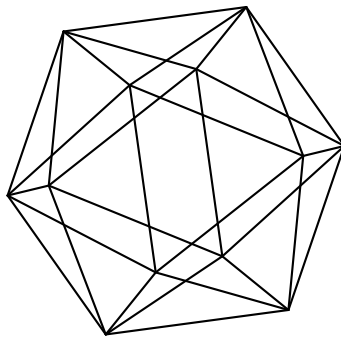


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Formal solution to the \hbar -dependent KP hierarchy

by

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Formal solution to the \hbar -dependent KP hierarchy

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Abstract

We find all formal solutions to the \hbar -dependent KP hierarchy that admit the zero dispersion limit. The solutions are found in the form of formal series for the logarithm of the tau-function. An explicit combinatorial description of the coefficients of the series is provided.

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1 Introduction

1.1 Motivation

The partial differential equation (PDE)

$$\frac{3}{4} u_{yy} = \frac{\partial}{\partial x} \left(u_t - \frac{3}{2} uu_x - \frac{1}{4} u_{xxx} \right) \quad (1)$$

was derived by Kadomtsev and Petviashvili (KP) in 1970 for description of non-linear waves in two-dimensional media with small dispersion. Later it was recognized that this equation is integrable and it can be naturally embedded into an infinite system of compatible PDE's. This system is now called the KP integrable hierarchy. The KP hierarchy can be most naturally formulated in terms of bilinear equations for the tau-function $\tau = \tau(t_1, t_2, t_3, t_4, \dots)$ of the infinite set of "times" $\mathbf{t} = \{t_1, t_2, t_3, \dots\}$, the first three of which are identified with x, y, t as $t_1 = x, t_2 = y, t_3 = t$. The variable u in equation (1) is expressed through the tau-function as $u = 2\partial_x^2 F$, where $F = \log \tau$.

The KP hierarchy has a lot of exact solutions of very different nature: non-linear waves and excitations in dispersive media (quasi-periodic and soliton solutions [6, 20]), generating functions for topological invariants in algebraic geometry [27, 9], partition functions for models of random matrices [14], etc.

The tau-function admits the well-known expansion in Schur functions depending on the times t_i [21]. The structure of this expansion is studied in detail and well understood [2, 5, 4]. However, in many cases of prime interest is the F -function rather than the tau-function itself. At the same time, series expansions for the F -function are missing in the literature. This is the problem that we address in the present paper. It should be noted that we deal with not necessarily convergent series. The corresponding solutions are called formal.

One can introduce an auxiliary formal parameter \hbar by re-scaling $t_k \rightarrow t_k/\hbar$, then the KP equation acquires the form

$$\frac{3}{4} u_{yy} = \frac{\partial}{\partial x} \left(u_t - \frac{3}{2} uu_x - \frac{\hbar^2}{4} u_{xxx} \right) \quad (2)$$

The corresponding re-scaling in the whole hierarchy is called the \hbar -formulation of the KP hierarchy (or the \hbar -dependent KP hierarchy [22]). The coefficients of its formal solutions are formal series in \hbar . The F -function is defined as $F = \hbar^2 \log \tau$.

The parameter \hbar has a meaning of the Planck's constant in the "auxiliary space", i.e., the space where the Lax operator of the KP hierarchy acts. The limit $\hbar \rightarrow 0$ is the quasiclassical limit in the auxiliary space. In the "physical space" of dynamical variables this limit is realized as the dispersionless limit, where higher space-time derivatives of dynamical variables are set to be negligibly small. For example, equation (2) at $\hbar = 0$ becomes the Khokhlov-Zabolotskaya equation (the dispersionless KP equation).

The $\hbar \rightarrow 0$ limit of the KP hierarchy is called the dispersionless KP (dKP) hierarchy. It is a particular case of general Whitham hierarchy of partial differential equations [7, 8]. The dispersionless limit is of great interest on its own. (For applications to interface dynamics and problems of complex analysis see [12, 13, 28, 29, 19] and [26, 30] respectively.) A class of solutions to the dKP hierarchy can be obtained as the $\hbar \rightarrow 0$ limits of solutions to the \hbar -dependent KP hierarchy. However, such limits do not always exist in the class of smooth functions.

In the present paper we construct all formal solutions to the \hbar -dependent KP hierarchy in the form of an infinite formal series with the coefficients defined by an explicit recurrence procedure. The solution is determined by an infinite set of arbitrary functions of one variable $f_0(x), f_1(x), f_2(x), \dots$ which are supposed to be formal series or differentiable infinitely many times. These functions are initial data for the solution. In particular, $F(x; \mathbf{0}) = f_0(x)$. However, the functions f_i with $i \geq 1$ coincide with the standard Cauchy data $\partial_{t_i} F(x, \mathbf{t}) \Big|_{\mathbf{t}=\mathbf{0}}$ only at $\hbar = 0$. At $\hbar \neq 0$ these functions differ from the first order derivatives by some terms which are of higher order in \hbar . We call the set $\{f_0(x), f_1(x), f_2(x), \dots\}$ *the Cauchy-like data*.

The fact that solutions to the KP hierarchy can be restored from the first order derivatives of the F -function at $\mathbf{t} = \mathbf{0}$ was pointed out earlier [3, 17, 18]. However, no explicit solution of the Cauchy problem for the KP hierarchy is available even in the sense of formal series. In this paper we give explicit formulas that allow one to restore the formal solution from the arbitrary set of the Cauchy-like data $\{f_0(x), f_1(x), f_2(x), \dots\}$.

1.2 Preliminaries

1.2.1 Young diagrams and symmetric functions

Here we list the necessary notations and facts related to Young diagrams and Schur functions.

Young diagrams. Following [10], we will denote the Young diagrams as λ, μ , etc. Let $\lambda = [\lambda_1, \lambda_2, \dots, \lambda_\ell]$ be the Young diagram with $\ell = \ell(\lambda)$ rows of non-zero lengths $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_\ell > 0$. We identify λ with the partition of the number $|\lambda| := \lambda_1 + \dots + \lambda_\ell$ into the ℓ non-zero parts λ_i . Another convenient notation is $\lambda = (1^{m_1} 2^{m_2} \dots r^{m_r} \dots)$, which means that exactly m_i parts of the partition λ have length i : $m_i = \text{card} \{j : \lambda_j = i\}$. In particular, the Young diagram with one row (respectively, one column) of length k is

denoted as (k) (respectively, (1^k)). Put

$$\rho(\lambda) = \lambda_1 \dots \lambda_{\ell(\lambda)}, \quad \sigma(\lambda) = m_1! \dots m_{\ell(\lambda)}!, \quad z_\lambda = \sigma(\lambda)\rho(\lambda).$$

One can introduce some orderings on the set of diagrams with fixed $|\lambda|$ [10]. One of them is the reverse lexicographical order: λ precedes μ if the first non-vanishing difference $\lambda_i - \mu_i$ is positive. In this ordering (n) comes first and (1^n) comes last. It is a linear ordering. Another ordering is the natural partial ordering which is defined as follows:

$$\lambda \geq \mu \iff \lambda_1 + \dots + \lambda_i \geq \mu_1 + \dots + \mu_i \quad \text{for all } i \geq 1. \quad (3)$$

As soon as $|\lambda| \geq 6$ it is not a total ordering.

Schur functions. The general reference is [10]. Let $\mathbf{t} = \{t_1, t_2, t_3, \dots\}$ be an infinite set of variables. The Schur polynomials $s_\lambda(\mathbf{t})$ labeled by Young diagrams λ can be defined by the determinant formula

$$s_\lambda(\mathbf{t}) = \det_{i,j=1,\dots,\ell(\lambda)} h_{\lambda_i - i + j}(\mathbf{t}), \quad (4)$$

where the polynomials $h_j(\mathbf{t})$ are defined with the help of the generating series

$$\exp\left(\sum_{k \geq 1} t_k z^k\right) = \sum_{k \geq 0} h_k(\mathbf{t}) z^k,$$

or, explicitly, $h_k(\mathbf{t}) = \sum_{k_1+2k_2+\dots=k} \frac{t_1^{k_1}}{k_1!} \frac{t_2^{k_2}}{k_2!} \dots = \sum_{l=1}^k \frac{1}{l!} \sum_{\substack{k_1, \dots, k_l \geq 1 \\ k_1 + \dots + k_l = k}} t_{k_1} \dots t_{k_l}$. The first few poly-

nomials are $h_1(\mathbf{t}) = t_1$, $h_2(\mathbf{t}) = \frac{1}{2}t_1^2 + t_2$, $h_3(\mathbf{t}) = \frac{1}{6}t_1^3 + t_1t_2 + t_3$, $h_4(\mathbf{t}) = \frac{1}{24}t_1^4 + \frac{1}{2}t_2^2 + \frac{1}{2}t_1^2t_2 + t_1t_3 + t_4$. It is convenient to put $h_0(\mathbf{t}) = 1$, $h_k(\mathbf{t}) = 0$ for $k < 0$ and $s_\emptyset(\mathbf{t}) = 1$. The functions h_k are elementary Schur polynomials in the sense that for one-row diagrams $s_{(j)}(\mathbf{t}) = h_j(\mathbf{t})$. Equation (4) is known as the Jacobi-Trudi identity.

We will need the Cauchy-Littlewood identity

$$\sum_{\lambda} s_\lambda(\mathbf{t}) s_\lambda(\mathbf{t}') = \exp\left(\sum_{k \geq 1} kt_k t'_k\right), \quad (5)$$

where the sum is over all Young diagrams including the empty one. The both sides can be regarded as formal series in the variables \mathbf{t}, \mathbf{t}' . Writing it in the form

$$\sum_{\lambda} s_\lambda(\mathbf{y}) s_\lambda(\tilde{\partial}) = \exp\left(\sum_{k \geq 1} y_k \partial_{t_k}\right),$$

where $\tilde{\partial} = \{\partial_{t_1}, \frac{1}{2}\partial_{t_2}, \frac{1}{3}\partial_{t_3}, \dots\}$ and applying to $s_\mu(\mathbf{t})$, we get the relation

$$s_\lambda(\tilde{\partial}) s_\mu(\mathbf{t}) \Big|_{\mathbf{t}=0} = \delta_{\lambda\mu} \quad (6)$$

which reflects the orthonormality of the Schur functions.

The Schur functions are usually regarded as symmetric functions of the variables x_i defined by $kt_k = \sum_i x_i^k$. In terms of the variables x_i ($i = 1, \dots, N$, $N \geq \ell(\lambda)$),

$$s_\lambda(\mathbf{t}) = s_\lambda(\{x_i\}_N) = \frac{\det_{1 \leq i, j \leq N} (x_i^{N+\lambda_j - j})}{\det_{1 \leq i, j \leq N} (x_i^{N-j})}, \quad t_k = \frac{1}{k} \sum_i x_i^k. \quad (7)$$

It can be proved [10] that the Schur polynomials form an orthonormal basis in the space of symmetric functions.

1.2.2 Dual bases in the space of polynomials

Let us consider the linear space \mathcal{P} of polynomials in the variables $\mathbf{t} = \{t_1, t_2, t_3, \dots\}$. The basis vectors are naturally labeled by Young diagrams with basis polynomials $v_\lambda(\mathbf{t})$ being quasi-homogeneous in the sense that $v_\lambda(at_1, a^2t_2, a^3t_3, \dots) = a^{|\lambda|}v_\lambda(t_1, t_2, t_3, \dots)$. By definition, the polynomial labelled by the empty diagram \emptyset is $v_\emptyset(\mathbf{t}) = 1$. One may choose such a basis in many different ways. The simplest example is the usual monomial basis

$$t_\lambda(\mathbf{t}) := t_{\lambda_1}t_{\lambda_2}\dots t_{\lambda_\ell} = \prod_{i \geq 1} t_i^{m_i(\lambda)}$$

Other examples are the basis $h_\lambda(\mathbf{t}) = h_{\lambda_1}h_{\lambda_2}\dots h_{\lambda_\ell}$ and the Schur polynomial basis $s_\lambda(\mathbf{t})$. Having in mind the interpretation of polynomials of t_k as symmetric functions of the variables x_i discussed above, we will call polynomials from the space \mathcal{P} symmetric functions (although they are *not* symmetric w.r.t. the variables t_k). Another standard basis in \mathcal{P} is the basis of monomial symmetric functions $m_\lambda = m_\lambda(\mathbf{t})$ which are easily defined in terms of the variables x_1, x_2, \dots, x_n provided $n \geq \ell(\lambda)$ (it is implied that $\lambda_j = 0$ if $j > \ell(\lambda)$):

$$m_\lambda(x_1, x_2, \dots, x_n) = \frac{1}{(n - \ell(\lambda))! \sigma(\lambda)} \sum_{P \in \mathcal{S}_n} x_1^{\lambda_{P(1)}} x_2^{\lambda_{P(2)}} \dots x_n^{\lambda_{P(n)}}.$$

The normalization factor is chosen in such a way that the function $m_\lambda(\mathbf{t})$ does not depend on n if $n \geq \ell(\lambda)$. For example, $m_{(k)}(\mathbf{t}) = \sum_j x_j^k = kt_k$. The first few functions m_λ are:

$$\begin{aligned} m_{(1)}(\mathbf{t}) &= t_1 \\ m_{(2)}(\mathbf{t}) &= 2t_2, \quad m_{(1^2)}(\mathbf{t}) = \frac{1}{2}t_1^2 - t_2 \\ m_{(3)}(\mathbf{t}) &= 3t_3, \quad m_{(21)}(\mathbf{t}) = 2t_2t_1 - 3t_3, \quad m_{(1^3)}(\mathbf{t}) = \frac{1}{6}t_1^3 - t_2t_1 + t_3 \end{aligned} \tag{8}$$

It is also convenient to keep the standard notation p_k for the power sums $p_k = kt_k$ and the corresponding basis $p_\lambda(\mathbf{t}) = \rho(\lambda)t_\lambda$.

One can introduce the scalar product in the space \mathcal{P} as follows:

$$\langle u_\lambda, v_\mu \rangle = u_\lambda(\tilde{\partial}) v_\mu(\mathbf{t}) \Big|_{\mathbf{t}=0}. \tag{9}$$

This definition is symmetric, i.e., $\langle u_\lambda, v_\mu \rangle = \langle v_\mu, u_\lambda \rangle$. This scalar product coincides with the one from [10] defined axiomatically in the space of symmetric functions. In particular, we have: $\langle p_\lambda, p_\mu \rangle = z_\lambda \delta_{\lambda\mu}$, where $\langle s_\lambda, s_\mu \rangle = \delta_{\lambda\mu}$ and $\langle h_\lambda, m_\mu \rangle = \delta_{\lambda\mu}$. If $\langle u_\lambda, v_\mu \rangle = \delta_{\lambda\mu}$ for all λ, μ , we say that u_λ, v_λ are dual bases.

Lemma 1.1 *Let $u_\lambda(\mathbf{t}), v_\lambda(\mathbf{t})$ be any pair of dual bases in \mathcal{P} , and $g(\mathbf{t})$ be any function real-analytic around the point $\mathbf{t} = 0$, then the Taylor series at $\mathbf{t} = 0$ can be represented in the form*

$$g(\mathbf{t}) = \sum_\lambda u_\lambda(\tilde{\partial}) g(\mathbf{t}') \Big|_{\mathbf{t}'=0} v_\lambda(\mathbf{t}). \tag{10}$$

The proof is obvious. ■

2 The \hbar -KP hierarchy for the tau-function

Hereafter we work with the \hbar -formulation [22] of the KP hierarchy and call it the \hbar -KP hierarchy. Let $\tau = \tau(t_1, t_2, t_3, \dots) = \tau(\mathbf{t})$ be the tau-function of the hierarchy. It depends on the infinite set of time variables $\mathbf{t} = \{t_1, t_2, \dots\}$. It also contains \hbar as a parameter but we will not write it explicitly.

2.1 Hirota equations for the tau-function

The \hbar -KP hierarchy can be represented in different equivalent forms. We start with the Hirota bilinear equations for the tau-function. They can be encoded in a functional relation. Below we use the notation

$$\tau^{[z_1, \dots, z_m]}(\mathbf{t}) = \tau\left(\mathbf{t} + \hbar \sum_{i=1}^m [z_i^{-1}]\right) = e^{\hbar(D(z_1) + \dots + D(z_m))} \tau$$

where

$$\mathbf{t} \pm \hbar[z^{-1}] := \left\{ t_1 \pm \hbar z^{-1}, t_2 \pm \frac{\hbar}{2} z^{-2}, t_3 \pm \frac{\hbar}{3} z^{-3}, \dots, \right\}$$

and the differential operator $D(z)$ is defined by

$$D(z) = \sum_{k \geq 1} \frac{z^{-k}}{k} \partial_k \quad (11)$$

Hereafter we abbreviate $\partial_k = \partial/\partial t_k$.

The Hirota functional relation for the tau-function reads

$$(z_1 - z_2) \tau^{[z_1, z_2]} \tau^{[z_3]} + (z_2 - z_3) \tau^{[z_2, z_3]} \tau^{[z_1]} + (z_3 - z_1) \tau^{[z_3, z_1]} \tau^{[z_2]} = 0 \quad (12)$$

It is to be fulfilled for all z_1, z_2, z_3 . By tau-function (of the \hbar -KP hierarchy) we mean any solution to this equation. Differential equations of the hierarchy are obtained by expanding this equation in powers of z_1, z_2, z_3 . Another form of the functional relation for the τ -function is

$$\hbar \partial_1 \log \frac{\tau^{[z_1]}}{\tau^{[z_2]}} = (z_2 - z_1) \left(\frac{\tau^{[z_1, z_2]} \tau}{\tau^{[z_1]} \tau^{[z_2]}} - 1 \right) \quad (13)$$

which is sometimes called the differential Fay identity.

Proposition 2.1 *Equations (12) and (13) are equivalent.*

Proof. Eq. (13) follows from eq. (12) in the limit $z_3 \rightarrow \infty$. Eq. (12) can be obtained from (13) by summing the equations written for the pairs $\{z_1, z_2\}$, $\{z_2, z_3\}$, $\{z_3, z_1\}$. ■

Proposition 2.2 *The tau-function $\tau = \tau(\mathbf{t})$ of the \hbar -KP hierarchy satisfies the equations*

$$\prod_{1 \leq i < j \leq m} (z_j - z_i) \cdot \tau^{[z_1, \dots, z_m]} \tau^{m-1} = \det_{1 \leq j, k \leq m} \left((z_j - \hbar \partial_1)^{k-1} \tau^{[z_j]} \right) \quad (14)$$

for any $m \geq 2$ and any z_1, \dots, z_m .

Proof. At $m = 2$ equation (14) reads

$$(z_2 - z_1)\tau^{[z_1, z_2]}\tau = \begin{vmatrix} \tau^{[z_1]} & (z_1 - \hbar\partial_1)\tau^{[z_1]} \\ \tau^{[z_2]} & (z_2 - \hbar\partial_1)\tau^{[z_2]} \end{vmatrix}$$

which is (13). The rest of the proof is induction in m . See Appendix A for details. \blacksquare

Equation (14) was first suggested in [1].

2.2 Formal solution for the tau-function

Let us introduce the differential operators

$$\partial_k^\hbar = \frac{k}{\hbar} h_k(\hbar\tilde{\partial}) = \partial_k + \hbar \sum_{l=1}^{k-1} \frac{k\partial_l\partial_{k-l}}{2l(k-l)} + O(\hbar^2), \quad (15)$$

where $h_k(\mathbf{t})$ are the elementary Schur polynomials. These operators are “ \hbar -deformations” of the partial derivatives in the sense that $\partial_k^{\hbar=0} = \partial_k$. We call them \hbar -deformed partial derivatives. Their properties are studied below in the next section.

In the KP theory the first variable, t_1 , is distinguished. Having this in mind, we will treat the tau-function depending on t_i as a result of the evolution of $\tau(x; \mathbf{0})$ according to the KP flows: $\tau(x; \mathbf{0}) \rightarrow \tau(x; \mathbf{t}) = f(x)\hat{\tau}(x + t_1, t_2, t_3, \dots)$. Our aim is to represent it as a formal series in the t_i ’s given $\tau(x; \mathbf{0})$ and some Cauchy-like data to be specified below.

With the help of the operators ∂_i^\hbar we now define modified Cauchy data which are necessary for constructing the formal solution. We call them the *Cauchy-like data*.

Definition 2.1 *The Cauchy-like data of a solution $\tau(x; \mathbf{t})$ to the \hbar -KP hierarchy is the set of functions $\tau(x; \mathbf{0})$, $\partial_k^\hbar \tau(x; \mathbf{t}) \big|_{\mathbf{t}=\mathbf{0}}$, $k \geq 1$.*

The following theorem asserts that there exists a formal solution for arbitrary infinitely differentiable Cauchy-like data. It also provides its constructive representation assuming $\hbar \neq 0$.

Theorem 2.1 *Let $\tau(x, \mathbf{t}) = f(x)\hat{\tau}(x + t_1, t_2, \dots)$ be a tau-function of the \hbar -KP hierarchy with respect to the variables t_j , with $\tau(x, \mathbf{0})$ being an infinitely differentiable function of x . Then the coefficients of the series*

$$\tau(x; \mathbf{t}) = \sum_{\lambda} c_{\lambda}(x) s_{\lambda}(\mathbf{t}/\hbar) \quad (16)$$

are connected by the relations

$$c_{\lambda}(x) = (c_0(x))^{1-\ell(\lambda)} \det_{1 \leq i, j \leq \ell(\lambda)} \left[\sum_{k=0}^{j-1} (-\hbar)^k \binom{j-1}{k} \partial_x^k c_{\lambda_i - i + j - k}(x) \right] \quad (17)$$

where $\binom{j-1}{k} = \frac{(j-1)!}{k!(j-1-k)!}$ is the binomial coefficient, $c_0(x) = c_\emptyset(x)$, $c_k(x) = c_{(k)}(x)$ and $c_1 = \partial_x c_0 - c_0 \partial_x \log f$.

Conversely, let $\hbar \neq 0$ and $c_k(x)$, $k = 0, 1, 2, \dots$, be arbitrary infinitely differentiable functions of x (with $c_0(x)$ being not identically 0); for any Young diagram λ define the coefficients $c_\lambda(x)$ by (17). Then the series (16) is a formal solution to the \hbar -KP hierarchy ($\hbar \neq 0$) with the Cauchy-like data

$$\tau(x; \mathbf{0}) = c_0(x), \quad \partial_k^\hbar \tau(x; \mathbf{t}) \Big|_{\mathbf{t}=\mathbf{0}} = \frac{k}{\hbar} c_k(x), \quad k \geq 1.$$

Proof. To prove the first part of the theorem, we note that equations (14) for the tau-function $\tau(x; \mathbf{t})$ can be written in the form

$$\prod_{1 \leq a < b \leq m} (z_b - z_a) \cdot \tau^{[z_1, \dots, z_m]}(x; \mathbf{t}) \tau^{m-1}(x; \mathbf{t}) = \det_{1 \leq i, j \leq m} \left((z_i - \hbar \partial_x)^{j-1} \tau^{[z_i]}(x; \mathbf{t}) \right) \quad (18)$$

(as is easy to see, derivatives of f coming from $\partial_x^l(f\tau)$ cancel in the determinant in the right hand side after taking proper linear combinations of columns). The idea is to substitute (16) into this equation and equate the coefficients of the z_i -expansion of both sides at $\mathbf{t} = 0$. Let us rewrite (18) in the form convenient for expanding in powers of z_i^{-1} :

$$\tau^{[z_1, \dots, z_m]}(x; \mathbf{t}) = \frac{\det \left(z_i^{j-m} (1 - \hbar z_i^{-1} \partial_x)^{j-1} \tau^{[z_i]}(x; \mathbf{t}) \right)}{\det \left(z_i^{j-m} \right) \tau^{m-1}(x; \mathbf{t})}, \quad m \geq 2. \quad (19)$$

It follows from the Cauchy-Littlewood identity that the expansion of the left hand side is

$$e^{\hbar(D(z_1) + \dots + D(z_m))} \tau(x; \mathbf{t}) = \sum_{\lambda} s_{\lambda}(\{z_i^{-1}\}) s_{\lambda}(\hbar \tilde{\partial}) \tau(x; \mathbf{t}) \quad (20)$$

(here only terms with $\ell(\lambda) \leq m$ are non-zero). The numerator of the right hand side is $\det_{1 \leq i, j \leq m} \left(\sum_{l \geq 0} Z_{il} M_{lj} \right)$, where $Z_{il} = z_i^{-l}$ is the rectangular semi-infinite $m \times \mathbb{Z}_{\geq 0}$ matrix and

$$M_{lj} = \sum_{a=0}^{j-1} (-\hbar)^a \binom{j-1}{a} \partial_x^a h_{l+j-a-m}(\hbar \tilde{\partial}) \tau(x; \mathbf{t})$$

is the rectangular semi-infinite $\mathbb{Z}_{\geq 0} \times m$ matrix (we put $c_k = 0$ at $k < 0$). Application of the Cauchy-Binet formula gives

$$\det_{1 \leq i, j \leq m} \left(\sum_{l \geq 0} Z_{il} M_{lj} \right) = \sum_{l_1 > l_2 > \dots > l_m \geq 0} \det_{ij} \left(z_i^{-l_j} \right) \cdot \det_{jk} M_{l_j k}$$

Setting $l_j = m + \lambda_j - j$, we can represent the multiple sum as summation over Young diagrams with rows λ_i . Using (7), we see that the expansion of the right hand side is

$$\tau(x, \mathbf{t})^{1-m} \sum_{\lambda} s_{\lambda}(\{z_i^{-1}\}) \det_{ij} \left[\sum_{a=0}^{j-1} (-\hbar)^a \binom{j-1}{a} \partial_x^a h_{\lambda_i - i + j - a}(\hbar \tilde{\partial}) \tau(x; \mathbf{t}) \right]$$

Comparing with (20), it remains to put $\mathbf{t} = \mathbf{0}$ and use the orthonormality of the Schur functions.

Now let us prove that the series (16) with c_λ built from arbitrary c_k according to (17) solves the Hirota equations (12) or (13). First we repeat the above derivation in reverse order to prove that equations (18) hold for any z_1, \dots, z_m and $m \geq 2$ at $\mathbf{t} = 0$. The next step is to deduce that this set of relations for “initial values” of $\tau^{[z_1, \dots, z_m]}$ is equivalent to

$$(z_2 - z_1)\tau^{[z_1, z_2, z_3, \dots, z_m]}(x; \mathbf{0})\tau^{[z_3, \dots, z_m]}(x; \mathbf{0}) = \begin{vmatrix} \tau^{[z_1, z_3, \dots, z_m]}(x; \mathbf{0}) & (z_1 - \hbar\partial_x)\tau^{[z_1, z_3, \dots, z_m]}(x; \mathbf{0}) \\ \tau^{[z_2, z_3, \dots, z_m]}(x; \mathbf{0}) & (z_2 - \hbar\partial_x)\tau^{[z_2, z_3, \dots, z_m]}(x; \mathbf{0}) \end{vmatrix}$$

(which is the Jacobi identity for the matrix $N_{ij} = (z_i - \partial_x)^{j-1}\tau^{[z_i]}(x; \mathbf{0})$, see appendix A for details). In its turn, this latter relation, being valid for all z_1, \dots, z_m and $m \geq 2$, is equivalent to

$$(z_2 - z_1)\tau^{[z_1, z_2]}(x; \mathbf{t})\tau(x; \mathbf{t}) = \begin{vmatrix} \tau^{[z_1]}(x; \mathbf{t}) & (z_1 - \hbar\partial_x)\tau^{[z_1]}(x; \mathbf{t}) \\ \tau^{[z_2]}(x; \mathbf{t}) & (z_2 - \hbar\partial_x)\tau^{[z_2]}(x; \mathbf{t}) \end{vmatrix} \quad (21)$$

for any \mathbf{t} . This can be formally justified by noticing that if $e^{\hbar(D(z_1) + \dots + D(z_k))}\mathcal{F}(\mathbf{t}) \Big|_{\mathbf{t}=0} = 0$ for some $\mathcal{F}(\mathbf{t})$ for all z_1, \dots, z_k and $k \geq 0$, then $\sum_\lambda s_\lambda(\{z_i^{-1}\})s_\lambda(\tilde{\partial})\mathcal{F}(\mathbf{t}) \Big|_{\mathbf{t}=0} = 0$, whence $s_\lambda(\tilde{\partial})\mathcal{F}(\mathbf{t}) \Big|_{\mathbf{t}=0} = 0$ for all λ which means that $\mathcal{F}(\mathbf{t}) \equiv 0$ as a formal series. Multiplying both sides of equation (21) by $\frac{\tau^{[z_3]}}{\tau^{[z_1]}\tau^{[z_2]}}$ and summing the equations obtained in this way for all cyclic permutations of $\{z_1, z_2, z_3\}$, we get the Hirota equation (12) which, by Proposition 2.2, is equivalent to (13). The latter equation has the form (21) with $\partial_x \rightarrow \partial_1$, so the assertion is proved.

It remains to show that the tau-function represented by the series (16) does have the form $f(x)\hat{\tau}(x + t_1; t_2, \dots)$, i.e., it essentially depends on $x + t_1$. For this we notice that the above argument implies that

$$(\partial_x - \partial_1)\left(\log \tau(x; \mathbf{t} + \hbar[z^{-1}]) - \log \tau(x; \mathbf{t})\right) = 0$$

for all \mathbf{t}, z . From this it then follows that $\varphi := (\partial_x - \partial_1)\log \tau(x; \mathbf{t})$ does not depend on \mathbf{t} . Indeed, we have

$$0 = \varphi(\mathbf{t} + \hbar[z^{-1}]) - \varphi(\mathbf{t}) = \hbar\partial_1\varphi z^{-1} + \frac{1}{2}(\hbar^2\partial_1^2\varphi + \hbar\partial_2\varphi)z^{-2} + \dots$$

from which we can conclude that $\partial_1\varphi = \partial_2\varphi = \dots = 0$. Therefore, $(\partial_x - \partial_1)\log \tau(x; \mathbf{t}) = \varphi(x)$. A simple calculation at $\mathbf{t} = \mathbf{0}$ shows that $\varphi(x) = \partial_x \log c_0(x) - \frac{c_1(x)}{c_0(x)}$. ■

Remark 2.1 Putting $c_1(x) = \partial_x c_0(x)$, one obtains tau-functions $\tau(x + t_1, t_2, \dots)$ whose t_1 -evolution is equivalent to the shift of x .

Remark 2.2 Theorem 2.1 has been basically proven in [1], where equation (17) (with $\hbar = 1$) has appeared as a functional equation for commuting transfer matrices of the quantum Gaudin model.

3 The \hbar -KP hierarchy for the F -function

3.1 Hirota equations for the F -function

For many applications in physics and mathematics one needs to deal with logarithm of the tau-function rather than with the tau-function itself. It is possible to represent the Hirota equations as equations for the logarithm. Let us introduce the F -function as

$$F(x; \mathbf{t}) = \hbar^2 \log \tau(x; \mathbf{t}). \quad (22)$$

Representing shifts of the arguments in (12) as action of exponential of the differential operators $D(z_i)$ to the function F , we can rewrite (12) in terms of F :

$$\begin{aligned} & (z_1 - z_2) \exp\left[\hbar^{-2} e^{\hbar(D(z_1)+D(z_2))} F\right] \exp\left[\hbar^{-2} e^{\hbar D(z_3)} F\right] \\ & + (z_2 - z_3) \exp\left[\hbar^{-2} e^{\hbar(D(z_2)+D(z_3))} F\right] \exp\left[\hbar^{-2} e^{\hbar D(z_1)} F\right] \\ & + (z_3 - z_1) \exp\left[\hbar^{-2} e^{\hbar(D(z_1)+D(z_3))} F\right] \exp\left[\hbar^{-2} e^{\hbar D(z_2)} F\right] = 0. \end{aligned} \quad (23)$$

One can represent (23) in a more suggestive form of a non-linear difference equation. Let us introduce the difference operator

$$\Delta(z) = \frac{e^{\hbar D(z)} - 1}{\hbar}. \quad (24)$$

It can be easily checked that equation (23) acquires the form

$$(z_1 - z_2) e^{\Delta(z_1)\Delta(z_2)F} + (z_2 - z_3) e^{\Delta(z_2)\Delta(z_3)F} + (z_3 - z_1) e^{\Delta(z_3)\Delta(z_1)F} = 0. \quad (25)$$

Tending $z_3 \rightarrow \infty$ we get the differential Fay identity (13) in terms of F :

$$e^{\Delta(z_1)\Delta(z_2)F} = 1 - \frac{\Delta(z_1)\partial_1 F - \Delta(z_2)\partial_1 F}{z_1 - z_2}. \quad (26)$$

In the form (25) the equation is suitable for the \hbar -expansion as $\hbar \rightarrow 0$. The function F is supposed to have a regular \hbar -expansion:

$$F = F^{(0)} + \hbar F^{(1)} + \hbar^2 F^{(2)} + O(\hbar^3). \quad (27)$$

The \hbar -expansion of the \hbar -KP hierarchy was investigated in [23, 24] (see also [25]). The case $\hbar = 0$ is called the zero dispersion (or dispersionless) limit. In this limit we have $\lim_{\hbar \rightarrow 0} \Delta(z) = D(z)$ and equation (26) becomes the familiar dispersionless Hirota equation for $F^{(0)}$.

3.2 The KP hierarchy in an unfolded form

Another useful representation of the KP hierarchy is an ‘‘unfolded’’ form suggested in [3, 17]. The notation $\partial := \partial_x$, $F_k := \partial_k F$, $F_{kl} := \partial_k \partial_l F$, etc is convenient. The following theorem can be proven in the same way as [17, Theorem 2], with minor modifications keeping track of the \hbar -dependence.

Theorem 3.1 *There exist universal rational coefficients $R_{ij}^n \left(\begin{smallmatrix} s_1 & \cdots & s_n \\ r_1 & \cdots & r_n \end{smallmatrix} \right)$ such that*

$$F_{kl} = \sum_{n \geq 1} \sum \hbar^{\sum_i (r_i - 1)} R_{kl}^n \left(\begin{smallmatrix} s_1 & \cdots & s_n \\ r_1 & \cdots & r_n \end{smallmatrix} \right) \partial^{r_1} F_{s_1} \cdots \partial^{r_n} F_{s_n} \quad (28)$$

Here the second sums are taken over all matrices $\left(\begin{smallmatrix} s_1 & \cdots & s_n \\ r_1 & \cdots & r_n \end{smallmatrix} \right)$ such that $s_i, r_i \geq 1$ and $\sum_{i=1}^n (s_i + r_i) = k + l$.

Equations (28) represent the KP hierarchy in the unfolded form. They express F_{kl} with $k, l > 1$ as certain universal polynomials of $\partial^r F_j$'s with $r, j \geq 1$. The coefficients of these polynomials are fixed rational numbers which do not depend on a particular solution.

Corollary 3.1 *For any integer $m \geq 2$ there exist universal rational coefficients*

$R_{k_1 \dots k_m}^n \left(\begin{smallmatrix} s_1 & \cdots & s_n \\ r_1 & \cdots & r_n \end{smallmatrix} \right)$ such that

$$F_{k_1 \dots k_m} = \sum_{n \geq 1} \sum \hbar^{\sum_i (r_i - 1) + 2 - m} R_{k_1 \dots k_m}^n \left(\begin{smallmatrix} s_1 & \cdots & s_n \\ r_1 & \cdots & r_n \end{smallmatrix} \right) \partial^{r_1} F_{s_1} \cdots \partial^{r_n} F_{s_n} \quad (29)$$

The second sums are taken over all matrices $\left(\begin{smallmatrix} s_1 & \cdots & s_n \\ r_1 & \cdots & r_n \end{smallmatrix} \right)$ such that $s_i, r_i \geq 1$ with the conditions $\sum_{i=1}^n (s_i + r_i) = \sum_{i=1}^n k_i, \sum_{i=1}^n r_i \geq n + m - 2$.

Proof. The proof consists in induction on m using the Leibniz rule. ■

It follows from the Corollary that the quantities $F_j, j \geq 1$ restricted to zero values of t_k with $k \geq 2$ define the solution up to a constant. In this way, one produces a unique formal Taylor series in t_j 's which reconstructs a formal solution to the KP hierarchy from the Cauchy data $f_i(x) := \partial_i F(x; \mathbf{t}) \Big|_{t_1=t_2=\dots=0}$. In general, the functions f_i can be Taylor series in \hbar .

The following theorem can be proven in the same way as Theorem 4.2 from [18].

Theorem 3.2 *If $\sum_{i=1}^n (r_i - 1) - m \equiv 1 \pmod{2}$, then $R_{k_1 \dots k_m}^n \left(\begin{smallmatrix} s_1 & \cdots & s_n \\ r_1 & \cdots & r_n \end{smallmatrix} \right) = 0$.*

We see that equations (29) contain even powers of \hbar only. Therefore, if the Cauchy data $f_i(x)$ are series in \hbar^2 , then so is the formal solution. In particular, the formal solution is expanded in only even powers of \hbar if the Cauchy data are \hbar -independent.

At $\hbar = 0$ only the terms with $r_i = 1$ survive in (28) and these equations yield the polynomial expressions of $F_{kl}^{(0)}$ with $k, l > 1$ through $F_{1j}^{(0)}$'s. In this case there is a relatively simple recurrence formula for the coefficients, see [17]. In general any explicit combinatorial description of the coefficients $R_{k_1 \dots k_m}^n$ is not available.

In the rest part of the paper we show that some closed description of expansion coefficients can be achieved for non-zero \hbar , too, by a re-summation of the Taylor series and passing to another basis in the space of polynomials in t_k 's. We will exploit the formal similarity of the Hirota equation (26) with its dispersionless limit.

3.3 The “ \hbar -deformed partial derivatives” ∂_i^\hbar

Let us recall the definition of the “ \hbar -deformed partial derivatives” ∂_i^\hbar introduced in (15):

$$\partial_k^\hbar = \hbar^{-1} k h_k(\tilde{\hbar}\partial), \quad \tilde{\hbar} \equiv \{\partial_1, \frac{1}{2}\partial_2, \frac{1}{3}\partial_3, \dots\} \quad (30)$$

The first few are: $\partial_1^\hbar = \partial_1$, $\partial_2^\hbar = \partial_2 + \hbar\partial_1^2$, $\partial_3^\hbar = \partial_3 + \frac{3}{2}\hbar\partial_1\partial_2 + \frac{1}{2}\hbar^2\partial_1^3$. It is convenient to put $\partial_0^\hbar = 1$. Here we discuss these operators in some detail.

The general explicit formula is

$$\partial_k^\hbar = \sum_{l=1}^k \frac{\hbar^{l-1} k}{l!} \sum_{\substack{k_1, \dots, k_l \geq 1 \\ k_1 + \dots + k_l = k}} \frac{\partial_{k_1} \dots \partial_{k_l}}{k_1 \dots k_l}. \quad (31)$$

There is also a determinant representation which can be extracted from [10]:

$$\partial_n^\hbar = \frac{1}{(n-1)!} \begin{vmatrix} \partial_1 & -1 & 0 & 0 & \dots & 0 \\ \partial_2 & \hbar\partial_1 & -2 & 0 & \dots & 0 \\ \partial_3 & \hbar\partial_2 & \hbar\partial_1 & -3 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ \partial_{n-1} & \hbar\partial_{n-2} & \hbar\partial_{n-3} & \hbar\partial_{n-4} & \dots & -(n-1) \\ \partial_n & \hbar\partial_{n-1} & \hbar\partial_{n-2} & \hbar\partial_{n-3} & \dots & \hbar\partial_1 \end{vmatrix}. \quad (32)$$

The operators ∂_k^\hbar have rather special properties. In particular, they satisfy the following generalized Leibniz rule.

Lemma 3.1 *The differential operators ∂_k^\hbar satisfy the generalized Leibniz rule:*

$$\partial_k^\hbar \prod_{i=1}^n f_i = \sum_{\substack{k_1, \dots, k_n \geq 0 \\ k_1 + \dots + k_n = k}} \frac{\hbar^{\nu(k_1, \dots, k_n) - 1} k}{[k_1 \dots k_n]} \partial_{k_1}^\hbar f_1 \partial_{k_2}^\hbar f_2 \dots \partial_{k_n}^\hbar f_n \quad (33)$$

where $\nu(k_1, \dots, k_n)$ is the number of nonzero k_i 's in the sequence k_1, k_2, \dots, k_n and $[k_1 \dots k_n] := \prod_{i=1}^n \max\{k_i, 1\}$ is their product.

Proof. Expanding the both sides of the obvious identity $e^{\hbar D(z)} \prod_{i=1}^n f_i = \prod_{i=1}^n (e^{\hbar D(z)} f_i)$ in powers of z , we get:

$$\sum_{k \geq 0} z^{-k} \mathbf{h}_k \prod_{i=1}^n f_i = \sum_{k_1, \dots, k_n \geq 0} (z^{-k_1} \mathbf{h}_{k_1} f_1) \dots (z^{-k_n} \mathbf{h}_{k_n} f_n),$$

where we have put $h_k := h_k(\hbar\tilde{\partial})$ for brevity. Equating coefficients in front of powers of z in the both sides, we obtain the identity¹

$$h_k \prod_{i=1}^n f_i = \sum_{\substack{k_1, \dots, k_n \geq 0 \\ k_1 + \dots + k_n = k}} (h_{k_1} f_1) \dots (h_{k_n} f_n)$$

Being rewritten in terms of the operators ∂_k^\hbar , it coincides with (33). ■

In the limit $\hbar \rightarrow 0$ (33) becomes the usual Leibniz rule for the partial derivatives ∂_k .

3.4 The \hbar -KP hierarchy in terms of ∂_i^\hbar

Following [15], we define the combinatorial constants $\tilde{P}_{ij}(s_1 - 1, \dots, s_m - 1)$ to be the number of sequences of positive integers $(i_1, \dots, i_m), (j_1, \dots, j_m)$ such that $i_1 + \dots + i_m = i$, $j_1 + \dots + j_m = j$ and $s_k = i_k + j_k$. Put

$$P_{ij}(s_1 - 1, \dots, s_m - 1) = \frac{(-1)^{m+1} ij}{m(s_1 - 1) \dots (s_m - 1)} \tilde{P}_{ij}(s_1 - 1, \dots, s_m - 1).$$

Lemma 3.2 *The \hbar -KP hierarchy (26) is equivalent to the system of equations*

$$\partial_i^\hbar \partial_j^\hbar F = \sum_{m \geq 1} \sum_{\substack{s_1, \dots, s_m > 1 \\ s_1 + \dots + s_m = i+j}} P_{ij}(s_1 - 1, \dots, s_m - 1) \partial_1 \partial_{s_1-1}^\hbar F \dots \partial_1 \partial_{s_m-1}^\hbar F \quad (34)$$

for the function $F(x; \mathbf{t})$.

Proof. The Hirota equation (26) $e^{\Delta(z_1)\Delta(z_2)F} = 1 - \frac{\Delta(z_1)\partial_1 F - \Delta(z_2)\partial_1 F}{z_1 - z_2}$ yields

$$\begin{aligned} e^{\Delta(z_1)\Delta(z_2)F} &= 1 + z_1^{-1} z_2^{-1} \sum_{j=1}^{\infty} \frac{1}{j} \frac{(z_1^{-j} - z_2^{-j})}{(z_1^{-1} - z_2^{-1})} \partial_1 \partial_j^\hbar F \\ &= 1 + z_1^{-1} z_2^{-1} \sum_{j=1}^{\infty} \frac{1}{j} \left(\sum_{\substack{s+v=j-1 \\ s,v \geq 0}} z_1^{-s} z_2^{-v} \right) \partial_1 \partial_j^\hbar F = 1 + \sum_{j=1}^{\infty} \frac{1}{j} \left(\sum_{\substack{s+v=j+1 \\ s,v \geq 1}} z_1^{-s} z_2^{-v} \right) \partial_1 \partial_j^\hbar F. \end{aligned}$$

Therefore,

$$\begin{aligned} \Delta(z_1)\Delta(z_2)F &= \sum_{m=1}^{\infty} \frac{(-1)^{m+1}}{m} \left(\sum_{n=1}^{\infty} \left(\sum_{\substack{s+v=n+1 \\ s,v \geq 1}} z_1^{-s} z_2^{-v} \right) \frac{1}{n} \partial_1 \partial_n^\hbar F \right)^m \\ &= \sum_{j=1}^{\infty} \frac{(-1)^{m+1}}{m} \sum_{i,j \geq 1} z_1^{-i} z_2^{-j} \sum_{\substack{i_1 + \dots + i_m = i \\ j_1 + \dots + j_m = j \\ i_k, j_k \geq 1}} \frac{\partial_1 \partial_{i_1+j_1-1}^\hbar F}{i_1 + j_1 - 1} \dots \frac{\partial_1 \partial_{i_m+j_m-1}^\hbar F}{i_m + j_m - 1} \end{aligned}$$

¹This means that the sequence of operators h_0, h_1, h_2, \dots is a Hasse-Schmidt derivation, see, e.g., [11].

that is

$$\begin{aligned} \partial_i^{\hbar} \partial_j^{\hbar} F &= \sum_{m=1}^{\infty} \sum_{k_1+\dots+k_m=i+j} \frac{(-1)^{m+1}}{m} \frac{ij}{(k_1-1)\dots(k_m-1)} \\ &\quad \cdot \tilde{P}_{ij}(k_1-1, \dots, k_m-1) \partial_1 \partial_{k_1-1}^{\hbar} F \dots \partial_1 \partial_{k_m-1}^{\hbar} F. \end{aligned}$$

This proves that (26) implies (34). Performing the calculation in reverse order, we find that (34) implies (26). \blacksquare

Let $K_l(l^1, \dots, l^r)$ be the number of partitions of a set of l elements into ordered groups from l^1, \dots, l^r elements.

Define constants $P_{i_1 \dots i_r}^{\hbar} \left(\begin{smallmatrix} s_1 \dots s_m \\ l_1 \dots l_m \end{smallmatrix} \right)$ by the following recurrence relations.

- 1) $P_{i_1, i_2}^{\hbar} \left(\begin{smallmatrix} s_1 \dots s_m \\ 1 \dots 1 \end{smallmatrix} \right) = P_{i_1 i_2}(s_1, \dots, s_m)$ and $P_{i_1, i_2}^{\hbar} \left(\begin{smallmatrix} s_1 \dots s_m \\ l_1 \dots l_m \end{smallmatrix} \right) = 0$, if $\prod_{j=1}^m l_j > 1$.
- 2) $P_{i_1 \dots i_r}^{\hbar} \left(\begin{smallmatrix} x_1 \dots x_v \\ y_1 \dots y_v \end{smallmatrix} \right) = \sum P_{i_1 \dots i_{r-1}}^{\hbar} \left(\begin{smallmatrix} s_1 \dots s_m \\ l_1 \dots l_m \end{smallmatrix} \right) \frac{\hbar^{\nu(k_1, \dots, k_m)-1} i_r}{[k_1 \dots k_m]}$
 $\times K_{l_1}(l_1^1, \dots, l_1^{n_1}) P_{s_1 k_1}^{\hbar}(s_1^1 \dots s_{n_1}^1) \dots K_{l_m}(l_m^1, \dots, l_m^{n_m}) P_{s_m k_m}^{\hbar}(s_1^m \dots s_{n_m}^m),$

where the summation is carried over all sets of integral numbers $m > 0$, $s_i > 0$, $s_j^i > 0$, $k_i \geq 0$, $l_i > 0$, $l_j^i \geq 0$ such that

$$(x_1 \dots x_v) = (s_1^1, \dots, s_{n_1}^1, s_1^2, \dots, s_{n_2}^2, \dots, s_1^m, \dots, s_{n_m}^m), \quad s_i = \sum_{j=1}^{n_i} s_j^i;$$

$$(y_1 \dots y_v) = (l_1^1 + 1, \dots, l_{n_1}^1 + 1, l_1^2 + 1, \dots, l_{n_2}^2 + 1, \dots, l_1^m + 1, \dots, l_{n_m}^m + 1), \quad l_i = \sum_{j=1}^{n_i} l_j^i$$

$$\sum_{i=1}^m (s_i + l_i) = \sum_{j=1}^{r-1} i_j, \quad \sum_{i=1}^m k_i = i_r, \quad \sum_{i=1}^{n_j} s_i^j = k_j + s_j.$$

Lemma 3.2 and Lemma 3.1 imply

Theorem 3.3 *The \hbar -KP hierarchy (26) is equivalent to the system of equations*

$$\partial_{i_1}^{\hbar} \partial_{i_2}^{\hbar} \dots \partial_{i_r}^{\hbar} F = \sum_{m \geq 1} \sum_{\substack{s_1 + l_1 + \dots + s_m + l_m = \\ i_1 + \dots + i_r \\ 1 \leq s_i; 1 \leq l_i \leq r-1}} P_{i_1 \dots i_r}^{\hbar} \left(\begin{smallmatrix} s_1 \dots s_m \\ l_1 \dots l_m \end{smallmatrix} \right) \partial_1^{l_1} \partial_{s_1}^{\hbar} F \dots \partial_1^{l_m} \partial_{s_m}^{\hbar} F. \quad (35)$$

Proof. We use induction in r . Lemma 3.2 gives

$$\partial_{i_1}^{\hbar} \partial_{i_2}^{\hbar} F = \sum_{m \geq 1} \sum_{\substack{s_1 + 1 + \dots + s_m + 1 = \\ i_1 + i_2 \\ 1 \leq s_i}} P_{i_1 i_2}^{\hbar} \left(\begin{matrix} s_1 \dots s_m \\ 1 \dots 1 \end{matrix} \right) \partial_1 \partial_{s_1}^{\hbar} F \dots \partial_1 \partial_{s_m}^{\hbar} F. \quad (36)$$

Suppose the theorem is proved for $r = l - 1$. Then

$$\begin{aligned} & \partial_{i_1}^{\hbar} \partial_{i_2}^{\hbar} \dots \partial_{i_r}^{\hbar} F = \partial_{i_r}^{\hbar} (\partial_{i_1}^{\hbar} \partial_{i_2}^{\hbar} \dots \partial_{i_{r-1}}^{\hbar} F) \\ &= \sum_{m \geq 1} \sum_{\substack{s_1 + l_1 + \dots + s_m + l_m \\ = i_1 + \dots + i_{r-1} \\ 1 \leq s_i; 1 \leq l_i \leq r-2}} P_{i_1 \dots i_{r-1}}^{\hbar} \left(\begin{matrix} s_1 \dots s_m \\ l_1 \dots l_m \end{matrix} \right) \partial_{i_r}^{\hbar} (\partial_1^{l_1} \partial_{s_1}^{\hbar} F \dots \partial_1^{l_m} \partial_{s_m}^{\hbar} F) \\ &= \sum_{m \geq 1} \sum_{\substack{s_1 + l_1 + \dots + s_m + l_m \\ = i_1 + \dots + i_{r-1} \\ 1 \leq s_i; 1 \leq l_i \leq r-2}} P_{i_1 \dots i_{r-1}}^{\hbar} \left(\begin{matrix} s_1 \dots s_m \\ l_1 \dots l_m \end{matrix} \right) \sum_{\substack{k_1, \dots, k_m \geq 0 \\ k_1 + \dots + k_m = i_r}} \frac{\hbar^{\nu(k_1, \dots, k_m) - 1} i_r}{[k_1 \dots k_m]} \\ & \quad \partial_1^{l_1} \partial_{s_1}^{\hbar} \partial_{k_1}^{\hbar} F \dots \partial_1^{l_m} \partial_{s_m}^{\hbar} \partial_{k_m}^{\hbar} F \\ &= \sum_{m \geq 1} \sum_{\substack{s_1 + l_1 + \dots + s_m + l_m \\ = i_1 + \dots + i_{r-1} \\ 1 \leq s_i; 1 \leq l_i \leq r-2}} P_{i_1 \dots i_{r-1}}^{\hbar} \left(\begin{matrix} s_1 \dots s_m \\ l_1 \dots l_m \end{matrix} \right) \sum_{\substack{k_1, \dots, k_m \geq 0 \\ k_1 + \dots + k_m = i_r}} \frac{\hbar^{\nu(k_1, \dots, k_m) - 1} i_r}{[k_1 \dots k_m]} \\ & \quad \partial_1^{l_1} \left(\sum_{n_1 \geq 1} \sum_{\substack{s_1, \dots, s_{n_1} \geq 1 \\ s_1^1 + \dots + s_{n_1}^1 + n_1 = k_1 + s_1}} P_{s_1 k_1}^{\hbar} (s_1^1 \dots s_{n_1}^1) \partial_1 \partial_{s_1^1}^{\hbar} F \dots \partial_1 \partial_{s_{n_1}^1}^{\hbar} F \right) \dots \\ & \quad \partial_1^{l_m} \left(\sum_{n_m \geq 1} \sum_{\substack{s_1^m, \dots, s_{n_m}^m \geq 1 \\ s_1^m + \dots + s_{n_m}^m + n_m = k_m + s_m}} P_{s_m k_m}^{\hbar} (s_1^m \dots s_{n_m}^m) \partial_1 \partial_{s_1^m}^{\hbar} F \dots \partial_1 \partial_{s_{n_m}^m}^{\hbar} F \right). \end{aligned}$$

■

4 Formal solution for the F -function

4.1 The Cauchy-like data

Similarly to Definition 2.1, we can introduce the Cauchy-like data for the \hbar -KP hierarchy for F : $F(x; \mathbf{0})$ and $\partial_k^{\hbar} F(x; \mathbf{0}) := \partial_k^{\hbar} F(x; \mathbf{t}) \Big|_{\mathbf{t}=\mathbf{0}}$. Let us examine how the Cauchy-like data for τ and F are connected. First of all, we have

$$\tau(x; \mathbf{0}) = c_0(x) = e^{F(x; \mathbf{0})/\hbar^2}. \quad (37)$$

Next, we use the obvious identity $\hbar \frac{\Delta(z)\tau}{\tau} = e^{\frac{1}{\hbar}\Delta(z)F} - 1$ which immediately follows from the definition of $\Delta(z)$ ². Expanding it in powers of z and comparing the coefficients, we get:

$$\frac{\partial_k^{\hbar} \tau(x; \mathbf{t})}{\tau(x; \mathbf{0})} \Big|_{\mathbf{t}=\mathbf{0}} = \frac{k}{\hbar} h_k(\mathbf{y}), \quad y_l = \frac{1}{\hbar l} \partial_l^{\hbar} F(x; \mathbf{t}) \Big|_{\mathbf{t}=\mathbf{0}}, \quad (38)$$

²It is valid for *any* functions τ, F related by $F = \hbar^2 \log \tau$ (not necessarily KP solutions).

or, in terms of the coefficients $c_k(x)$ introduced in Theorem 2.1,

$$\frac{c_k(x)}{c_0(x)} = h_k(\mathbf{y}), \quad k = 1, 2, \dots \quad (39)$$

Therefore, the Cauchy-like data for τ are unambiguously determined by the ones for F . Theorem 2.1 implies the following

Corollary 4.1 *Let $\hbar \neq 0$. Then for any Cauchy-like data $F(x; \mathbf{0})$, $\partial_k^\hbar F(x; \mathbf{0})$, $k \geq 1$, there exists a formal solution $F(x; \mathbf{t})$ to the \hbar -KP hierarchy.*

4.2 Dual bases h_λ and m_λ and the formal solution

Theorem 3.3 gives $h_\lambda(\hbar\tilde{\partial})F(x; \mathbf{0})$ in terms the Cauchy-like data. Therefore, for the construction of the Taylor series we need the dual bases h_λ, m_μ . The functions $m_\mu(\mathbf{t})$ will be used in the expansion of the F -function instead of monomials t_λ , according to (10).

It is not difficult to incorporate the parameter \hbar into the formulas. For instance, re-scaling $\mathbf{t} \rightarrow \mathbf{t}/\hbar$ in the generalized Taylor expansion (10) with respect to a dual pair $\langle u_\lambda, v_\mu \rangle = \delta_{\lambda\mu}$ and redefining the function g as $g(\mathbf{t}/\hbar) = G(\mathbf{t})$, we can rewrite it in the form

$$G(\mathbf{t}) = \sum_\lambda u_\lambda(\hbar\tilde{\partial})G(\mathbf{t}')\Big|_{\mathbf{t}'=0} \cdot v_\lambda(\mathbf{t}/\hbar). \quad (40)$$

Here, $G(\mathbf{t})$ is an arbitrary series in the t_j 's with \hbar -dependent coefficients. Applying this formula for the dual pair h_λ, m_λ and the function $F(x; \mathbf{t})$, we can write:

$$F(x; \mathbf{t}) = \sum_\lambda h_\lambda(\hbar\tilde{\partial})F(x; \mathbf{t}')\Big|_{\mathbf{t}'=0} \cdot m_\lambda(\mathbf{t}/\hbar). \quad (41)$$

As the \hbar -deformation of the monomial basis t_λ we introduce the polynomials

$$t_\lambda^\hbar := \frac{\sigma(\lambda)}{\rho(\lambda)} \hbar^{\ell(\lambda)} m_\lambda(\mathbf{t}/\hbar). \quad (42)$$

The first few are (see (8)):

$$\begin{aligned} t_{(1)}^\hbar &= t_1 \\ t_{(2)}^\hbar &= t_2, \quad t_{(12)}^\hbar = t_1^2 - 2\hbar t_2 \\ t_{(3)}^\hbar &= t_3, \quad t_{(21)}^\hbar = t_2 t_1 - \frac{3}{2}\hbar t_3, \quad t_{(13)}^\hbar = t_1^3 - 6\hbar t_2 t_1 + 6\hbar^2 t_3. \end{aligned} \quad (43)$$

Clearly, $t_\lambda^{\hbar=0} = t_\lambda$. In these terms, the Taylor series for the function F can be written as follows:

$$F(x; \mathbf{t}) = \sum_\lambda \partial_\lambda^\hbar F(x; \mathbf{t}')\Big|_{\mathbf{t}'=0} \frac{t_\lambda^\hbar}{\sigma(\lambda)}. \quad (44)$$

All solutions of system (34) of this form are called *formal solutions*. An important corollary of Theorem 3.3 is

Corollary 4.2 *Any formal solution $F(x; \mathbf{t})$ of (26) is uniquely defined by the Cauchy-like data $F(0, 0)$ and $\{\partial_k^\hbar F(x; 0, 0, \dots)\}_{k=1, 2, \dots}$.*

4.3 t_λ^{\hbar} in terms of t_λ

Following [10], consider the transition matrix $L_{\lambda\mu}$ from power sums to the monomial symmetric functions:

$$p_\lambda(\mathbf{t}) = \sum_{\mu} L_{\lambda\mu} m_\mu(\mathbf{t}).$$

It has the following combinatorial description. Let λ be a partition of length $\ell = \ell(\lambda)$, and f be any mapping from the set $\{1, 2, \dots, \ell\}$ to the set of positive integers. Consider the infinite sequence $\{f_1^{(\lambda)}, f_2^{(\lambda)}, \dots\}$ whose i th component is

$$f_i^{(\lambda)} = \sum_{j: f(j)=i} \lambda_j \quad \text{for each } i \geq 1.$$

Theorem 4.1 ([10]) $L_{\lambda\mu}$ is equal to the number of mappings f such that $f_i^{(\lambda)} = \mu_i$ for each $i \geq 1$.

It follows from the theorem that $L_{\lambda\mu}$ are non-negative integer numbers. Let us regard the partitions of $n = |\lambda|$ as arranged in the reverse lexicographical order. It follows from the theorem that $L_{\lambda\mu} = 0$ unless μ precedes λ . In fact a stronger property holds: $L_{\lambda\mu} = 0$ unless $\mu \geq \lambda$, where the partial ordering \geq is defined in (3). This means that the matrix $L_{\lambda\mu}$ is strictly lower triangular:

$$p_\lambda(\mathbf{t}) = \sum_{\mu \geq \lambda} L_{\lambda\mu} m_\mu(\mathbf{t}), \quad m_\lambda(\mathbf{t}) = \sum_{\mu \geq \lambda} (L^{-1})_{\lambda\mu} p_\mu(\mathbf{t}). \quad (45)$$

(in particular, $L_{\lambda\mu} = (L^{-1})_{\lambda\mu} = 0$ if λ and μ are incomparable with respect to the partial ordering \geq).

4.4 Algebra of \hbar -differential operators.

Let F be a solution of the \hbar -KP hierarchy. It follows from Theorem 3.3 that $\{\partial_i^{\hbar} \mid i = 1, 2, \dots\}$ act on the algebra generated by $\{\partial_1^l \partial_s^{\hbar} F(x; t_1, 0, 0, \dots) \mid l, s = 1, 2, \dots\}$. In this subsection we prove that any family of functions of one variable generates a similar commutative algebra of differential operators. Later we use this algebra for constructing all formal solutions.

Consider an arbitrary set $\mathbf{f} = \{f_1, f_2, \dots\}$ of real or complex formal functions of the variable x . Let $A_{\mathbf{f}}$ be the algebra generated by $\{f_i\}$ and its derivatives $\partial^n f_i = \frac{\partial^n f_i}{\partial x^n}$.

Consider a family of linear operators $L_i^{\hbar} = L_i^{\hbar}[\mathbf{f}] : A_{\mathbf{f}} \rightarrow A_{\mathbf{f}}$, which are uniquely defined by the following properties:

- $L_i^{\hbar} \partial = \partial L_i^{\hbar}$;
- $L_i^{\hbar}(f_j) = \sum_{m \geq 1} \sum_{\substack{s_1, \dots, s_m > 1 \\ s_1 + \dots + s_m = i+j}} P_{ij}(s_1 - 1, \dots, s_m - 1) \partial f_{s_1-1} \dots \partial f_{s_m-1}$;

- (the generalized Leibniz rule) for any formal functions g_1, \dots, g_n , of t and \hbar it holds

$$L_k^\hbar(g_1 \dots g_n) = \sum_{\substack{k_1, \dots, k_n \geq 0 \\ k_1 + \dots + k_n = k}} \frac{\hbar^{\nu(k_1, \dots, k_n) - 1} k}{[k_1 \dots k_n]} L_{k_1}^\hbar g_1 L_{k_2}^\hbar g_2 \dots L_{k_r}^\hbar g_n; \quad (46)$$

In particular, $L_1^\hbar(f_j) = \sum_{m \geq 1} \sum_{\substack{s_1, \dots, s_m > 1 \\ s_1 + \dots + s_m = 1 + j}} P_{1j}(s_1 - 1, \dots, s_m - 1) \partial f_{s_1-1} \dots \partial f_{s_m-1} = \partial f_j$
and $L_j^\hbar(f_i) = L_i^\hbar(f_j)$ because $P_{ji}(s_1, \dots, s_m) = P_{ij}(s_1, \dots, s_m)$.

The lemma below follows from lemma 3.2. (This is a motivation for introducing the operators $L_i^\hbar(\cdot)$.)

Lemma 4.1 *Let F be the solution to the \hbar -KP hierarchy corresponding to the Cauchy-like data $F(x, 0)$ and $\{\partial_k^\hbar F(x, 0) = f_k(x) | k = 1, 2, \dots\}$. Then*

$$L_i^\hbar(f_j)(x) = \partial_i^\hbar \partial_j^\hbar F(x, 0).$$

Theorem 4.2 *The operators L_i^\hbar commute with each other.*

Proof. First assume that $\hbar \neq 0$. Then it follows from corollary 4.1 that there is a unique solution F to the \hbar -KP hierarchy with the Cauchy-like data \mathbf{f} . Hence

$$L_k^\hbar L_i^\hbar(f_j) = \partial_k^\hbar \partial_i^\hbar \partial_j^\hbar F(x; \mathbf{t}) = L_i^\hbar L_k^\hbar(f_j).$$

The operators L_i^\hbar are presented in the form of formal series $L_i^\hbar = \sum_{j=0}^{\infty} \hbar^j H_i^j$, where the linear operators $H_i^j = H_i^j[\mathbf{f}] : A_{\mathbf{f}} \rightarrow A_{\mathbf{f}}$ do not depend on \hbar and $H_i^0 = L_i^0$. The equalities $L_k^\hbar L_i^\hbar(f_j) = L_i^\hbar L_k^\hbar(f_j)$ for all non-zero \hbar give $H_k^0 H_i^0(f_j) = H_i^0 H_k^0(f_j)$. ■

Corollary 4.3 *For any i_1, \dots, i_r and $\sigma \in S_r$ the relations*

$$L_{i_1}^\hbar \dots L_{i_{r-1}}^\hbar(f_{i_r}) = L_{i_{\sigma(1)}}^\hbar \dots L_{i_{\sigma(r-1)}}^\hbar(f_{i_{\sigma(r)}})$$

and

$$L_{i_1}^\hbar \dots L_{i_{r-1}}^\hbar(f_{i_r}) = \sum_{m \geq 1} \sum_{\substack{s_1 + l_1 + \dots + s_m + l_m = \\ i_1 + \dots + i_r \\ 1 \leq s_i; 1 \leq l_i \leq r-1}} P_{i_1 \dots i_r}^\hbar \left(\begin{matrix} s_1 \dots s_m \\ l_1 \dots l_m \end{matrix} \right) \partial_1^{l_1} f_{s_1} \dots \partial_1^{l_m} f_{s_m}$$

are fulfilled.

Proof. The first relation directly follows from Theorem 4.2. The second one follows from Lemma 4.1 and Theorem 3.3. ■

4.5 Construction of formal solutions

Given a Young diagram $\lambda = [\lambda_1, \dots, \lambda_\ell]$, we put $\partial_\lambda = \partial_{\lambda_1} \partial_{\lambda_2} \dots \partial_{\lambda_\ell}$ and

$$P_\lambda^{\hbar} \begin{pmatrix} s_1 \dots s_m \\ l_1 \dots l_m \end{pmatrix} = P_{\lambda_1 \dots \lambda_r}^{\hbar} \begin{pmatrix} s_1 \dots s_m \\ l_1 \dots l_m \end{pmatrix}$$

Theorem 4.3 *For any \hbar and any family of smooth or formal functions*

$$\mathbf{f} = \{f_0(x), f_1(x), f_2(x), \dots\}$$

there exists a unique solution $F(x; \mathbf{t})$ of the \hbar -KP hierarchy such that $F(x; \mathbf{0}) = f_0(x)$ and $\partial_k^{\hbar} F^{\hbar}(x; t_1, t_2, \dots) \Big|_{\mathbf{t}=\mathbf{0}} = f_k(x)$. This solution has the form

$$F(x; \mathbf{t}) = f_0(x) + \sum_{|\lambda| \geq 1} \frac{f_\lambda^{\hbar}(x)}{\sigma(\lambda)} t_\lambda^{\hbar}, \quad (47)$$

where $f_{[k]}^{\hbar}(x) = f_k(x)$ and for $\ell(\lambda) > 1$

$$f_\lambda^{\hbar}(x) = \sum_{m \geq 1} \sum_{\substack{s_1 + l_1 + \dots + s_m + l_m = |\lambda| \\ 1 \leq s_i; 1 \leq l_i \leq \ell(\lambda) - 1}} P_\lambda^{\hbar} \begin{pmatrix} s_1 \dots s_m \\ l_1 \dots l_m \end{pmatrix} \partial_1^{l_1} f_{s_1}(x) \dots \partial_1^{l_m} f_{s_m}(x) \quad (48)$$

Proof. Let us consider the operators L_i^{\hbar} generated by the family $\{f_i | i = 0, 1, 2, \dots\}$. Given a Young diagram $\lambda = [\lambda_1, \dots, \lambda_r]$, denote by $[i, j, \lambda]$ the Young diagram with the rows $\{i, j, \lambda_1, \dots, \lambda_r\}$. Then, according to Corollary 4.3,

$$\partial_i^{\hbar} \partial_j^{\hbar} F = \sum_{\lambda} \frac{f_{[i, j, \lambda]}^{\hbar}(x)}{\sigma([i, j, \lambda])} t_\lambda^{\hbar} = \sum_{\lambda} \frac{L_i^{\hbar} L_j^{\hbar} f_\lambda^{\hbar}(x)}{\sigma(\lambda)} t_\lambda^{\hbar} = L_i^{\hbar} L_j^{\hbar} \sum_{\lambda} \frac{f_\lambda^{\hbar}(x)}{\sigma(\lambda)} t_\lambda^{\hbar},$$

for $i, j \geq 1$. Hence,

$$\partial_i^{\hbar} \partial_j^{\hbar} F(x; t_1, t_2, \dots) \Big|_{\mathbf{t}=\mathbf{0}} = L_i^{\hbar} L_j^{\hbar} F(x; \mathbf{0})$$

and

$$\partial_i^{\hbar} \partial_j^{\hbar} F = \sum_{m \geq 1} \sum_{\substack{s_1, \dots, s_m > 1 \\ s_1 + \dots + s_m = i+j}} P_{ij}(s_1 - 1, \dots, s_m - 1) \partial_1 \partial_{s_1-1}^{\hbar} F \dots \partial_1 \partial_{s_m-1}^{\hbar} F^{\hbar}$$

Therefore, according to Lemma 3.2, the function F is a formal solution of the \hbar -KP hierarchy. Moreover, according to Corollary 4.2, the solution is uniquely determined by the functions $f_k(x)$. \blacksquare

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Appendix A: Proof of Proposition 2.2

Here we give some details of the proof that the tau-function of the \hbar -KP hierarchy satisfies (14) for any $m \geq 2$:

$$\prod_{1 \leq i < j \leq m} (z_j - z_i) \cdot \tau^{[z_1, \dots, z_m]} \tau^{m-1} = \det_{1 \leq j, k \leq m} \left((z_j - \hbar \partial_1)^{k-1} \tau^{[z_j]} \right) \quad (\text{A1})$$

(Proposition 2.2). At $m = 2$ equation (A1) reads

$$(z_2 - z_1) \tau^{[z_1, z_2]} \tau = \begin{vmatrix} \tau^{[z_1]} & (z_1 - \hbar \partial_1) \tau^{[z_1]} \\ \tau^{[z_2]} & (z_2 - \hbar \partial_1) \tau^{[z_2]} \end{vmatrix} \quad (\text{A2})$$

which is the original equation for the tau-function (13). The rest of the proof is induction in m .

Suppose (A1) holds for any number of points z_i from 2 to $m - 1$. In what follows it is convenient to use the short-hand notation

$$\Delta_{1\dots m} = \prod_{a>b}^m (z_a - z_b), \quad \tau_{1\dots m} = \tau \left(\mathbf{t} + \hbar [z_1^{-1}] + \dots + \hbar [z_m^{-1}] \right).$$

After the shift $\mathbf{t} \rightarrow \mathbf{t} + \sum_{i=3}^m [z_i^{-1}]$ equation (A2) acquires the form

$$\Delta_{12} \tau_{123\dots m} \tau_{3\dots m} = \begin{vmatrix} \tau_{13\dots m} & (z_1 - \hbar \partial_1) \tau_{13\dots m} \\ \tau_{23\dots m} & (z_2 - \hbar \partial_1) \tau_{23\dots m} \end{vmatrix}. \quad (\text{A3})$$

Let N_{ij} be the matrix $N_{ij} = (z_i - \hbar \partial_1)^{j-1} \tau^{[z_i]}$, $1 \leq i, j \leq m$, and \tilde{N}_{ij} be the matrix whose first $m - 1$ columns are the same as for N_{ij} but the last column is different: $\tilde{N}_{im} = N_{i, m+1}$. One can check ³ that

$$\hbar \partial_1 \det N_{ij} = \left(\sum_{l=1}^m z_l \right) \det N_{ij} - \det \tilde{N}_{ij} \quad (\text{A4})$$

By $N_{ij}[a, b]$ we denote the matrix N_{ij} with removed row a and column b , and by $N_{ij} \begin{bmatrix} a, b \\ c, d \end{bmatrix}$ we denote the matrix N_{ij} with removed rows a, c and column b, d . By the assumption of the induction we have:

$$\tau_{3\dots m} = \frac{\det N_{ij} \begin{bmatrix} 1, & m-1 \\ 2, & m \end{bmatrix}}{\Delta_{3\dots m} \tau^{m-3}}, \quad \tau_{13\dots m} = \frac{\det N_{ij}[2, m]}{\Delta_{13\dots m} \tau^{m-2}}, \quad \tau_{23\dots m} = \frac{\det N_{ij}[1, m]}{\Delta_{23\dots m} \tau^{m-2}}.$$

³The proof is based on the easily verified identity $\sum_{l=1}^m \det \left(z_i^{\delta_{jl}} A_{ij} \right) = \left(\sum_{l=1}^m z_l \right) \det A_{ij}$ valid for any matrix A_{ij}

Substituting this into (A3), we get, after using (A4):

$$\Delta_{12} \tau_{1\dots m} \cdot \frac{\det N \begin{bmatrix} 1, & m-1 \\ 2, & m \end{bmatrix}}{\Delta_{3\dots m} \tau^{m-3}} = \frac{\begin{vmatrix} \det N[2, m] & \det N[2, m-1] \\ \det N[1, m] & \det N[1, m-1] \end{vmatrix}}{\Delta_{13\dots m} \Delta_{23\dots m} \tau^{2m-4}}$$

Since $\Delta_{12} \Delta_{13\dots m} \Delta_{23\dots m} = \Delta_{3\dots m} \Delta_{1\dots m}$, equation (A1) for m points, $\tau_{1\dots m} = \frac{\det N}{\Delta_{1\dots m} \tau^{m-1}}$, follows from the Jacobi identity for minors of the matrix N :

$$\det N \cdot \det N \begin{bmatrix} 1, & m-1 \\ 2, & m \end{bmatrix} = \begin{vmatrix} \det N[2, m] & \det N[2, m-1] \\ \det N[1, m] & \det N[1, m-1] \end{vmatrix}.$$

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