## HEIGHTS FOR p-ADIC HOLOMORPHIC FUNCTIONS OF SEVERAL VARIABLES

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## § 1. Introduction.

The relation between the growth of an entire function and its zeroes was studied early by Hadamard. R. Nevanlinna considered this problem for meromorphic functions and constructed a famous theory well-known as the value distribution theory. Nevanlinna theory in higher dimensions is constructed by Griffiths, King, Stoll, Carlson and others. In [2], [3], [5] we give a p-adic version of value distribution theory in one-dimensional case. In the present paper we consider the relation between the growth of a p-adic holomorphic function of several variables and the distribution of its zeros. This problem is a part of our plan to construct p-adic analog of Nevanlinna theory in higher dimensions. As we have mentioned in [4] this study is stimulated by the papers about the relation between Nevanlinna theory and number theory (see [6], [7]).

To generalize p-adic Nevanlinna theory to higher dimensions in [4] we introduced the notion of heights for p-adic meromorphic functions of one variable. In the present paper this notion is defined for p-adic holomorphic functions of several variables and used to prove an analog of the Poisson-Jensen formula. It is well-known that in the higher dimensional case the set of zeros of a holomorphic functions is not discrete. This makes it difficult to use analytical arguments. Here the Poisson-Jensen formula is described in terms of relations of global and local heights. Almost all of the arguments in this paper are easy "geometrically" but require longer proofs using the analytic definitions, which are often omitted.

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§ 2. Heights for holomorphic functions of several variables.

2.1. Let p be a prime number,  $\mathbf{Q}_p$  the field of p-adic numbers, and  $\mathbf{C}_p$  the p-adic completion of the algebraic closure of  $\mathbf{Q}_p$ . The absolute value in  $\mathbf{Q}_p$  is normalized so that  $|\mathbf{p}| = \mathbf{p}^{-1}$ . We further use the notion  $\mathbf{v}(\mathbf{z})$  for the additive valuation in  $\mathbf{C}_p$  which extends  $\operatorname{ord}_p$ . Let  $D_1$  be the open unit disk in  $\mathbf{C}_p$ :

$$D_1 = \{ z \in C_p; |z| < 1 \}$$
,

and  $D = D_1 \times ... \times D_1$  be the "unit polydisk" in  $\mathbb{C}_p^k$ . Let  $f(z_1,...,z_k)$  be a p-adic holomorphic function on D represented by a convergent series

$$f(z_1,...,z_k) = \sum_{|m|=0}^{\infty} a_{m_1...m_k} z_1^{m_1} ... z_k^{m_k} .$$
(1)

This means that for all  $(z_1,...,z_k) \in D$  we have

$$\lim_{|\mathbf{m}| \longrightarrow \infty} |\mathbf{a}_{\mathbf{m}} \mathbf{z}^{\mathbf{m}}| = 0 ,$$

where  $\mathbf{a}_{\mathbf{m}} = \mathbf{a}_{\mathbf{m}_1\cdots\mathbf{m}_k}$ ,  $\mathbf{z}^{\mathbf{m}} = \mathbf{z}_1^{\mathbf{m}_1}\cdots\mathbf{z}_k^{\mathbf{m}_k}$  and  $|\mathbf{m}| = \mathbf{m}_1 + \cdots + \mathbf{m}_k$ . For every  $(\mathbf{t}_1,\dots,\mathbf{t}_k) \in \mathbb{R}_+^k$  we have

$$\lim_{|\mathbf{m}| \to \infty} \{ \mathbf{v}(\mathbf{a}_{\mathbf{m}}) + \mathbf{m}_1 \mathbf{t}_1 + \dots + \mathbf{m}_k \mathbf{t}_k \} = \mathbf{\omega}$$

From this it follows that for every  $(t_1,...,t_k) \in \mathbb{R}^k_+$  there exists  $(m_1,...,m_k) \in \mathbb{N}^k$  for which  $v(a_m) + \sum_{i=1}^k m_i t_i$  is minimal.

2.2 <u>Definition</u>. The height of the function  $f(z_1,...,z_k)$  is defined by

$$H_{f}(t_{1},...,t_{k}) = \min_{0 \le |m| < \infty} \{v(a_{m}) + \sum_{i=1}^{k} m_{i}t_{i}\}$$

2.3 <u>Definition</u>. The group of functions mod 0(1) on D denoted by  $\mathscr{K}(D)$  is defined by

$$\mathscr{K}(D) = \{ \text{function } g : D \longrightarrow \mathbb{R} \} / \{ \text{bounded functions} \}$$

2.4. Let f be a holomorphic function on D, the relative height associated to f is defined by the equivalent class of the following function in the group  $\mathcal{K}(D)$ :

$$\widetilde{\mathtt{H}}_{f}:\mathtt{D} \longrightarrow \mathbb{R} \text{ , where } \widetilde{\mathtt{H}}_{f}(\mathtt{z}_{1},...,\!\mathtt{z}_{k}) = \mathtt{H}_{f}(\mathtt{v}(\mathtt{z}_{1}),...,\!\mathtt{v}(\mathtt{z}_{k}))$$

2.5. We set

$$\begin{split} \mathrm{I}_{f}(\mathtt{t}_{1},...,\mathtt{t}_{k}) &= \{(\mathtt{m}_{1},...,\mathtt{m}_{k}) \in \mathbb{N}^{k} ,\\ \mathrm{v}(\mathtt{a}_{m}) + \sum_{i=1}^{k} \mathtt{m}_{i}\mathtt{t}_{i} &= \mathrm{H}_{f}(\mathtt{t}_{1},...,\mathtt{t}_{k})\} \\ \mathrm{n}_{i}^{+}(\mathtt{t}_{1},...,\mathtt{t}_{k}) &= \min\{\mathtt{m}_{i} \mid \exists(\mathtt{m}_{1},...,\mathtt{m}_{i},...,\mathtt{m}_{k}) \in \mathrm{I}_{f}(\mathtt{t}_{1},...,\mathtt{t}_{k})\} \\ \mathrm{n}_{i}^{-}(\mathtt{t}_{1},...,\mathtt{t}_{k}) &= \max\{\mathtt{m}_{i} \mid \exists(\mathtt{m}_{1},...,\mathtt{m}_{i},...,\mathtt{m}_{k}) \in \mathrm{I}_{f}(\mathtt{t}_{1},...,\mathtt{t}_{k})\} \\ \mathrm{h}_{i}^{+}(\mathtt{t}_{1},...,\mathtt{t}_{k}) &= \mathtt{n}_{i}^{+}(\mathtt{t}_{1},...,\mathtt{t}_{k})\mathtt{t}_{i} ,\\ \mathrm{h}_{i}^{-}(\mathtt{t}_{1},...,\mathtt{t}_{k}) &= \mathtt{n}_{i}^{-}(\mathtt{t}_{1},...,\mathtt{t}_{k})\mathtt{t}_{i} ,\\ \mathrm{h}_{i}(\mathtt{t}_{1},...,\mathtt{t}_{k}) &= \mathtt{n}_{i}^{-}(\mathtt{t}_{1},...,\mathtt{t}_{k}) - \mathtt{h}_{i}^{+}(\mathtt{t}_{1},...,\mathtt{t}_{k}) \\ \mathrm{h}_{f}(\mathtt{t}_{1},...,\mathtt{t}_{k}) &= \sum_{i=1}^{k} \mathtt{h}_{i}(\mathtt{t}_{1},...,\mathtt{t}_{k}) \end{split}$$

2.6. <u>Definition</u>.  $h_f(t_1,...,t_k)$  is called the local height of the function  $f(z_1,...,z_k)$  at  $(t_1,...,t_k) = (v(z_1),...,v(z_k))$ .

2.7. <u>Remark</u>. The local height induces a function on  $\mathbb{C}_p^k : \tilde{h}_f : \mathbb{C}_p^k \longrightarrow \mathbb{R}$ 

$$\mathtt{\tilde{h}}_f(\mathtt{z}_1, ..., \mathtt{z}_k) = \mathtt{h}_f(\mathtt{v}(\mathtt{z}_1), ..., \mathtt{v}(\mathtt{z}_k))$$

2.8. <u>Proposition</u>. 1) If  $\tilde{h}_{f}(z_{1}^{0},...,z_{k}^{0}) \neq 0$  then  $f(z_{1},...,z_{k})$  has zeros at  $v(z_{i}) = v(z_{i}^{0})$ , i = 1,...,k.

2) If  $\tilde{h}_{f}(z_{1},...,z_{k}) = 0$  then  $f(z_{1},...,z_{k}) \neq 0$  and we have

$$|f(z_1,...,z_k)| = p^{-\widetilde{H}_f(z_1,...,z_k)}$$

2.9. We now give a geometrical interpretation of heights. Consider the function represen-

ted by the series (1). For each  $(m_1,...,m_k)$  we draw the graph  $\Gamma_{m_1...m_k}$  which depicts  $v(a_m z^m)$  as a function of  $(t_1,...,t_k)$ . We obtain a hyperplane in  $\mathbb{R}^{k+1}$ :

$$\Gamma_{m_1...m_k} : t_{k+1} = v(a_{m_1...m_k}) + \sum_{i=1}^{k} m_i t_i$$

Since  $\lim_{|m| \to \infty} \{v(a_m) + \sum_{i=1}^k m_i t_i\} = \infty \text{ for each } (t_1, \dots, t_k) \in \mathbb{R}_+^k \text{ there exists a hyperplane which lies below any other one at } (t_1, \dots, t_k) \in \mathbb{R}_+^k \text{ , i.e.}$ 

$$\mathbf{t}_{k+1}(\Gamma_{m_1\cdots m_k}) \leq \mathbf{t}_{k+1}(\Gamma_{m_1'\cdots m_k'})$$

for all  $\Gamma_{m'_1...m'_k}$ . Let H be the boundary of the intersection of all parts in  $\mathbb{R}^k_+$  of the half-spaces lying below the hyperplanes  $\Gamma_{m_1...m_k}$ . It is easy to see that if  $(t_1,...,t_k, t_{k+1})$  is a point of H then we have

$$\mathbf{t_{k+1}} = \mathbf{H_f}(\mathbf{t_1}, \dots, \mathbf{t_k})$$

2.10. <u>Proposition</u>. H is the boundary of a convex polyedron in  $\mathbb{R}^k_+ \times \mathbb{R}$ .

2.11. <u>Proposition</u>. In the one-dimensional case (k=1) the local height  $h_f(t)$  is equals to the sum of valuations of zeros of f(z) at v(z) = t.

2.12. <u>Definition</u>. A point  $(t_1,...,t_k) \in \mathbb{R}^k_+$  is called a critical point of  $f(z_1,...,z_k)$  if  $h_f(t_1,...,t_k) \neq 0$ .

2.13. <u>Proposition</u>. The set of critical points of the function  $f(z_1,...,z_k)$  denotes by  $\Delta(H)$  consists the sides of the polyedron H.

2.14. <u>Remark</u>. It is easy to see that for every finite parallelpiped of  $\mathbb{R}_{+}^{k}$   $P = \{0 < r_{i} < t_{i} < s_{i} < +\infty, i = 1,...,k\}$ ,  $H \cap P \times \mathbb{R}$  is consisted of the parts of a finite number of hyperplanes  $\Gamma_{m_{1}...m_{k}}$ . In fact, these are hyperplanes  $\Gamma_{m_{1}...m_{k}}$  for which there exists at least one index i such that  $m_{i} = n_{i}^{\pm}(t_{1},...,t_{k})$  for some  $(t_{1},...,t_{k},t_{k+1}) \in P \times \mathbb{R}$ .

2.15. Example. Consider the function

$$f(z_1, z_2) = \log(1 + z_1) - \log(1 + z_2)$$

The simple computation gives us:

$$h_{1}(t_{1},t_{2}) = \begin{cases} 0 & \text{if } t_{1} < t_{2} & \text{or } t_{1} > t_{2} \neq 1/\varphi(p^{1}) \quad \forall i \\ 1 & \text{if } t_{1} > t_{2} = 1/\varphi(p^{i}) & \text{for some } i \\ p/p-1 & \text{if } t_{1} = t_{2} = 1/\varphi(p^{i}) & \text{for some } i \\ p^{i-1}t & \text{if } t_{1} = t_{2} = t , \quad 1/\varphi(p^{i}) < t < 1/\varphi(p^{i-1}) \end{cases}$$

where  $\varphi(n)$  is the Euler function,  $\varphi(p^{i}) = p^{i} - p^{i-1}$ 

$$h_{2}(t_{1},t_{2}) = \begin{cases} 0 & \text{if } t_{2} < t_{1} & \text{or } t_{2} > t_{1} \neq 1/\varphi(p^{i}) \quad \forall i \\ 1 & \text{if } t_{2} > t_{1} = 1/\varphi(p^{i}) & \text{for some } i \\ p/p-1 & \text{if } t_{2} = t_{1} = 1/\varphi(p^{i}) & \text{for some } i \\ p^{i-1}t & \text{if } t_{1} = t_{2} = t , \quad 1/\varphi(p^{i}) < t < 1/\varphi(p^{i-1}) \end{cases}$$

$$h(t_1, t_2) = \begin{cases} 0 & \text{if } t_2 > t_1 \neq 1/\varphi(p^i) \forall i & \text{or } t_1 > t_2 \neq 1/\varphi(p^i) \forall i \\ 1 & \text{if } t_1 > t_2 = 1/\varphi(p^i) & \text{for some } i & \text{or} \\ t_2 > t_1 = 1/\varphi(p^i) & \text{for some } i \\ 2p/p-1 & \text{if } t_1 = t_2 = 1/\varphi(p^i) & \text{for some } i \\ 2p^{i-1}t & \text{if } t_1 = t_2 = t, \ 1/\varphi(p^i) < t < 1/\varphi(p^{i-1}) \end{cases}$$

$$\mathbf{H}_{f}(t_{1},t_{2}) = \begin{cases} 1/p-1 + [\log_{p}(p-1)t_{1}] & \text{if } t_{1} \leq t_{2} \\ \frac{1}{p-1} + [\log_{p}(p-1)t_{2}] & \text{if } t_{1} > t_{2} \end{cases}$$

where [x] denotes the largest integer being equals or less than x.

The set of critical points is

$$\left\{ \left[ \frac{1}{\varphi(\mathbf{p}^{\mathbf{i}})}, \frac{1}{\varphi(\mathbf{p}^{\mathbf{i}})} + \mathbf{t}_{2} \right], \mathbf{t}_{2} \in \mathbb{R}_{+}, \mathbf{i} = 0, 1, \dots \right\}$$
$$\cup \left\{ \left[ \mathbf{t}_{1} + \frac{1}{\varphi(\mathbf{p}^{\mathbf{i}})}, \frac{1}{\varphi(\mathbf{p}^{\mathbf{i}})} \right], \mathbf{t}_{1} \in \mathbb{R}_{+}, \mathbf{i} = 0, 1, \dots \right\}$$
$$\cup \left\{ (\mathbf{t}, \mathbf{t}), \mathbf{t} \in \mathbb{R}_{+} \right\} .$$

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§ 3. The Poisson-Jensen formula.

3.1. For every  $(t_1,...,t_k) \in \mathbb{R}_+^k$  we denote

$$\mathbf{h}_{\mathbf{f}}(\mathbf{t}_{1},\ldots,\mathbf{t}_{i},\ldots,\mathbf{t}_{k}) = \lim_{\epsilon \to 0} \mathbf{h}_{\mathbf{f}}(\mathbf{t}_{1},\ldots,\mathbf{t}_{i}-\epsilon,\ldots,\mathbf{t}_{k}) .$$

Note that the function  $h_f(t_1,...,t_k)$  is continuous only at the points  $(t_1,...,t_k)$  such that

$$h_{f}(t_{1},...,t_{k}) = 0$$
,

but can be continuous in some variables separately while  $h_f(t_1,...,t_k) \neq 0$ .

3.2. Let  $(t_1^0,...,t_k^0)$  and  $(t_1,...,t_k)$  be two points of  $\mathbb{R}^k_+$ . We set

$$\begin{split} \delta_{i} &= h^{-\epsilon_{i}}(t_{1}, \dots, t_{i-1}, t_{i}^{0-}, \dots, t_{k}^{0-}) - \\ &- h_{i}^{\epsilon_{i}}(t_{1}, \dots, t_{i-1}, t_{i}, t_{i+1}^{0-}, \dots, t_{k}^{0-}) + \\ &\sum_{i} h_{f}(t_{1}^{-}, \dots, t_{i-1}^{-}, s_{i}, t_{i+1}^{0-}, \dots, t_{k}^{0-}) , \end{split}$$

where  $\epsilon_i = sign(t_i^0 - t_i)$  and the sum in the right extends over all  $s_i \in (t_i^0, t_i)$ .

3.3. Theorem (the Poisson-Jensen formula)

$$H_{f}(t_{1}^{0},...,t_{k}^{0}) - H_{f}(t_{1},...,t_{k}) = \sum_{i=1}^{k} \epsilon_{i}\delta_{i}$$

3.4. <u>Remark</u>. When k=1 we have the Poisson-Jensen formula proved in [4].

3.5. <u>Remark</u>. Theorem 3.3 is not symmetric in variables  $t_1,...,t_k$ , and we obtain several formulas to express the global height in terms of local heights. From this one can deduce the equalities between local heights. This fact is similar to the one in the case of holomorphic functions of two complex variables (see H. Cartan [1]).

3.6. <u>Remark</u>. In view of Theorem 3.3 the relative height  $\tilde{H}_{f}$  induced by f depends only on the local height.

3.7. Theorem 3.3 is proved by using the following remarks.

1) For every finite parallelpiped P (see 2.4) and every hyperplane L in general position  $L \cap H \cap P$  is a hyperplane of k-1 dimension.

2) If the hyperplane  $t_i = s_i = \text{const}$  is not in general position then the hyperplane  $t_i = s_i - \epsilon$  is in general position with  $\epsilon$  enough small. On the other hand we have

$$\lim_{\epsilon \to 0} H_{\mathbf{f}}(\dots, s_{\mathbf{i}} - \epsilon, \dots) = H_{\mathbf{f}}(\dots, s_{\mathbf{i}}, \dots) \quad .$$

3) The set of critical points  $\Delta(H)$  is a union of planes of dimensions equal or less than k-1 (see 2.12, 2.13).

4) Suppose  $S = S_1 \cup ... \cup S_{k-1}$ , where  $S_i$  is the hyperplane  $t_i = s_i$ , i = 1,...,k-1. By replacing  $S_i$  by  $S_i^-: t_i = s_i - \epsilon$  one can assume that  $S_i$  are in general position. Then the intersection  $S \cap \Delta(H) \cap P$  is a finite set of points.

5) By the remarks above the proof of Theorem 3.3 is reduced to the proof of Poisson--Jensen formula on one-dimensional case (see [4]).

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