# LOWER CURVATURE BOUNDS, TOPONOGOV'S THEOREM,

# AND BOUNDED TOPOLOGY I / II

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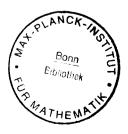
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# LOWER CURVATURE BOUNDS, TOPONOGOV'S THEOREM, AND BOUNDED TOPOLOGY I



#### Introduction:

Classically the theory of non-compact Riemannian manifolds with negative sectional curvature is based on the visibility axiom (c.f.[EN]); heuristically speaking this axiom requires that the curvatures do not decay to zero to quickly. In contrast the theory of manifolds  $\mathtt{M}^n$  with positive curvature does not require an additional hypothesis in the non-compact case. There are even nice results, if one supposes the curvature only to be non-negative: By the Toponogov splitting theorem such a manifold is isometric to a Riemannian product  $\mathtt{N}^k \times \mathtt{R}^{n-k}$ , where the factor  $\mathtt{N}^k$  does not contain a line. The soul theorem due to Cheeger and Gromoll claims that any non-negatively curved manifold  $\mathtt{M}^n$  is diffeomorphic to the normal bundle of a compact, embedded submanifold. Moreover Gromov has shown that there is a universal upper bound  $\mathtt{C}(\mathtt{n})$  on the sum of the Betti numbers  $\beta_1(\mathtt{M}^n)$ .

In this paper we are going to study a larger class of manifolds and include for instance "asymptotically flat manifolds".

# Definition:

A complete Riemannian manifold  $(M^n,g)$  with base point o is called asymptotically non-negatively curved, iff there exists a monotone function  $\lambda\colon [0,\infty) \longrightarrow [0,\infty)$  such that

i) 
$$b_0(\lambda) := \int_0^{\pi} \mathbf{r} \cdot \lambda(\mathbf{r}) d\mathbf{r} < -$$

and ii) the sectional curvatures at any point  $p \in M^n$  are bounded from below by  $-\lambda(d(o,p))$ .

The convergence of the integral  $b_0(\lambda)$  implies a decay condition on the lower curvature bound  $\lambda$ . This condition is analyzed in more detail in chapter II. For instance it asserts that there is a unique non-negative solution of the Riccati equation  $u'(r)=u(r)^2-\lambda(r)$  which decays to zero for  $r+\infty$ . Thus one has another numerical invariant

$$b_1(\lambda) := \int_0^{\pi} u(r) dr$$

Both  $b_0$  and  $b_1$  depend on  $\lambda$  in a monotone way, and they can be re-

garded as invariants of the manifold  $M^n$  by taking the minimal monotone function  $\lambda$  which meets the conditions (i) and (ii); notice that the numbers do not change when the metric g on  $M^n$  is scaled with a global factor.

#### Main Results:

# A) a generalized triangle comparison theorem of Toponogov type:

The model spaces will be arbitrary simply-connected surfaces of revolution with non-positive curvature, and the comparison triangle will have one vertex at the pole of the model space (c.f. I.3.1 and I.3.2).

We apply this theorem to triangles in asymptotically non-negatively curved manifolds which have one vertex at the base point o. Employing in addition the analysis done in chapter II, we obtain lower bounds on their angles which are uniform with respect to the size of the triangles (c.f. III.1). Such uniform bounds can be derived from the standard Toponogov theorem only in the case of non-negative curvature, and in this setting they provide an important tool. Similarly our uniform estimates are the key to the following theorem.

#### B) Theorem:

For asymptotically non-negatively curved manifolds  $M^n$  there exist universal upper bounds on the number of ends and on the Betti numbers:

1.) 
$$\#\{ends \ of \ M^n\} \le 2 \cdot \pi^{n-1} \cdot \exp((n-1) \cdot b_1(M^n))$$

2.) 
$$\sum_{i} \beta_{i}(M^{n}) \leq C(n) \cdot \exp(\frac{15n-13}{4} \cdot b_{1}(M^{n}))$$

The function C(n) can be effectively estimated by an expression which grows exponentially in  $n^3$ .

The proof of B1 is carried out in chapter III, while B2 is deferred to a subsequent paper. Finally theorem B is optimal in the sense that the topology of a surface M<sup>2</sup> is not necessarily bounded, when its integral b diverges. We can prove even more:

#### C) Theorem:

Suppose that the integral  $b_0(\lambda)$  of a function  $\lambda: [0,\infty) \longrightarrow [0,\infty)$  diverges. Then every non-compact, connected surface  $M^2$  with base point o carries a  $C^2$ -metric whose curvature  $\kappa$  obeys:

$$\kappa(p) = -\lambda(d(o,p)) , p \in M^2 .$$

# I. Models and Toponogov's Theorem:

The standard Toponogov theorem compares triangles in a Riemannian manifold  $(M^n,g)$  to the corresponding Alexandrov triangles in suitable spaces of constant curvature (c.f. [CE] or [K]). It is worthwhile noticing that the models are essentially two-dimensional. We are going to extend the theorem and allow for any simply-connected surface of revolution with non-positive curvature as model space.

1. More precisely we consider all continuous functions  $k: [0,\infty) \to [0,\infty)$ . Each of them determines a unique surface of revolution  $M^2(-k)$  with pole  $p_0$  such that the curvature equals the function  $-k(d(.,p_0))$ ; here d denotes the Riemannian distance in  $M^2(-k)$ .

It is convenient to simultaneously consider the approximating functions  $k_c:[0,\infty)\to[0,\infty)$  which are defined by

1.1 
$$k_{\epsilon}(r) := \sup\{k(r') \mid r' \ge 0 \text{ and } |r-r'| \le \epsilon\}$$
,  $\epsilon \ge 0$ 

By notation  $k_0 = k$ . In polar coordinates  $(r, \phi)$  the metric of  $M^2(-k_{\epsilon})$  looks like:

$$dr^2 + y_{\varepsilon}(r)^2 \cdot d\phi^2$$

where the function y is given by the Jacobi field equation:

1.3 
$$y_{\varepsilon}^{"} = k_{\varepsilon} \cdot y_{\varepsilon}$$
,  $y_{\varepsilon}(0) = 0$ , and  $y_{\varepsilon}^{\dagger}(0) = 1$ 

2. We proceed to summarize the elementary properties of our model spaces

2.1 Lemma:

The coordinate functions r(s) and  $\phi(s)$  along a unit-speed geodesic  $s \mapsto \gamma(s)$  in the model surface  $M^2(-k)$  obey the equations:

$$(1)$$
  $r^{2} + (y \cdot r)^{2} \cdot \phi^{2} = 1$ 

ii) 
$$(y \circ r)^2 \cdot \phi^* = const$$
 (Clairaut)

$$(y \bullet r)^2 \cdot (1 - r'^2) = const^2$$

We skip the obvious proof and recall that by notation  $p_0$  always denotes the pole of the model space. When looking at a geodesic triangle  $\Delta = (p_0, p_1, p_2)$  with edges of length  $t_i = d(p_{i+1}, p_{i+2})$  - indices taken modulo 3 - , formula 2.1iii becomes:

$$y(t_1) \cdot \sin(x + p_2) = y(t_2) \cdot \sin(x + p_1)$$

This generalizes the well-known Law of Sines in euclidean geometry ( $k\equiv 0$ ,  $y\equiv id$ ) and in hyperbolic geometry ( $k\equiv -1$ ,  $y\equiv sinh$ ).

#### 2.2 Lemma:

Given triangles  $\Delta = (p_0, p_1, p_2)$  and  $\Delta' = (p_0, p_1', p_2')$  in a surface  $M^2(-k)$  such that  $L_0 = L_0'$  and  $L_1 = L_1'$ , one has monotonicity:

$$xat p_2 < xat p_2' \iff x_2 < x_2'$$

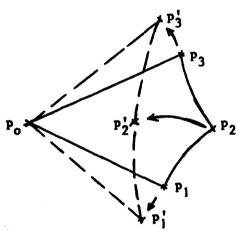
# Proof:

We may rotate  $\Delta'$  about  $p_0$  and without loss of generality may assume that  $p_2' = p_2$ . Then the claim becomes obvious, since  $M^2(-k)$  is simply-connected and has non-positive curvature.

#### 2.3 Lemma:

Let  $\,p_0^{}$  ,  $p_1^{}$  ,  $p_2^{}$  , and  $\,p_3^{}$  be the vertices of a quadrilateral in  $M^2(-k)$  . Moreover suppose that  $\,\,$  Lat  $\,p_2^{}<\pi\,\,$  and that

$$d(p_1,p_2) + d(p_2,p_3) < d(p_3,p_0) + d(p_0,p_1)$$
Then there is a triangle



Then there is a triangle  $\Delta = (p_0, p_1', p_3')$ , unique up to rotation about  $p_0$ , such that:

#### Proof:

The idea is to bend in the corner at  $p_2$ : we move  $p_2$  towards the pole  $p_0$ . We keep the length of all edges fixed by moving the vertices  $p_1$  and  $p_3$  in an appropriate way. Obviously

 For later use we state another continuity property, which is due to the fact that the functions  $\mathbf{k}_{\epsilon}$  converge to  $\mathbf{k}$  uniformly on compact subsets.

#### 2.4 Lemma:

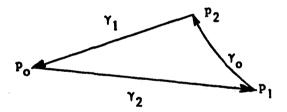
Given triangles  $\Delta = (p_0, p_1, p_2)$  in  $M^2(-k)$  and  $\Delta^{\epsilon} = (p_0^{\epsilon}, p_1^{\epsilon}, p_2^{\epsilon})$  in  $M^2(-k_{\epsilon})$  which have edges of equal length  $l_i^{\epsilon} = l_i$ , i=1,2,3, then their angles depend continuously on  $\epsilon$ , e.g.:

$$\lim_{\varepsilon \to 0} at p_i^{\varepsilon} = at p_i$$

3. In this section we are going to establish the generalized comparison theorem. Notation will be changed slightly: if there is a bar above a letter this symbol will refer to data in the model space, whereas unbarred letters will refer to data in the Riemannian manifold (M<sup>n</sup>,g).

#### 3.1 Assumptions:

i)  $p_0$ ,  $p_1$ , and  $p_2$  are the vertices of a (generalized) geodesic triangle in a Riemannian manifold  $M^n$ ; the edges  $\gamma_1$  and  $\gamma_2$  are supposed to be minimizing, whereas  $\gamma_0$  is only required to be a geodesic.



We continue denoting the length of  $\gamma_i$  by  $l_i$ , i=1,2,3.

ii) at any point  $p \in M^n$  the sectional curvatures shall be bounded from below by  $-k(d(p,p_0))$ .

iii) the pole  $\bar{p}_0$  of  $M^2(-k)$  shall be a vertex of the comparison triangle  $\bar{\Delta}=(\bar{p}_0,\bar{p}_1,\bar{p}_2)$ .

#### 3.2 Theorem:

Under the assumptions 3.1 the following conclusions hold:

- a) if  $L_i = \overline{L}_i$  for all the edges, then \* at  $p_1 \ge *$  at  $\overline{p}_1$  and \* at  $p_2 \ge *$  at  $\overline{p}_2$ .
- b) if  $l_0 = \overline{l_0}$ ,  $l_1 = \overline{l_1}$ , and  $tat p_2 \le tat \overline{p_2}$ , then  $l_2 \le \overline{l_2}$ .

#### 3.3 Remarks:

i) Actually it is sufficient to require condition 3.1ii only for those points  $p \in M^n$  which are  $\epsilon$ -close to any minimizing geodesic from  $p_0$  to a point on  $\gamma_0$ . These points p obey the conditions:

$$d(p,p_0) + d(p,p_1) \leq t_0 + t_1 + \epsilon \quad ; i = 1,2,$$
and
$$d(p,p_0) + \frac{1}{2} \cdot (d(p,p_1) + d(p,p_2)) \leq t_0 + \frac{1}{2} \cdot (t_1 + t_2) + \epsilon$$

- ii) The Alexandrov triangle  $\bar{\Delta} = (\bar{p}_0, \bar{p}_1, \bar{p}_2)$  which is required in part (a) of the theorem exists, if and only if  $\ell_0 = \ell_1 + \ell_2$ .
- iii) Even if one assumes in addition that the edge  $\gamma_{o}$  is minmizing, there is in contrast to the constant curvature case in general no easy way to restore the information on the angles at  $p_{o}$  and  $\bar{p}_{o}$ . The reason is that  $\bar{p}_{o}$  plays the rather special role of the pole in  $M^{2}(-k)$ .

# Proof: (c.f. [CE], [K])

We give a straight forward extension of the classical argument.

#### $a) \Longrightarrow b)$ :

- If  $t_0 \ge t_1 + t_2$ , the claim is an obvious consequence of the triangle inequality  $\overline{t}_0 \le \overline{t}_1 + \overline{t}_2$  which holds in  $M^2(-k)$ . Else there exists an Alexandrov triangle and the claim can be deduced from part (a) by means of the monotony principle 2.2.
- a) We pick  $r_{\Delta} > 0$  and K > 0 such that the edge  $\gamma_{O}$  is contained in the ball  $B(p_{O}, r_{\Delta})$  and that the sectional curvatures in  $B(p_{O}, r_{\Delta}+1)$  are bounded from above by K. Next we put the comparison triangles into the model spaces  $M^{2}(-k_{\epsilon})$  instead of  $M^{2}(-k)$ . By a limiting argument based on lemma 2.4 it is sufficient to prove the result (a) for all surfaces  $M^{2}(-k_{\epsilon})$  with  $0 < \epsilon < \min\{1, \pi/\sqrt{K}\}$ . We fix the value of  $\epsilon$ , subdivide  $\gamma_{O}$  into pieces shorter than  $\epsilon/2$ , and pick minimizing geodesics from  $p_{O}$  to all the partition points on  $\gamma_{O}$ . Provided that the claimed comparison result holds for all the small triangles, the deformation lemma 2.3 extends the inequalities to  $\Delta$  and  $\Delta$ . In view of the monotony principle 2.2 we have reduced the proof to showing:

In order to see this, we extend  $-\gamma_0^{\prime}(t_0)$  and  $-\bar{\gamma}_0^{\prime}(t_0)$  to parallel

vector fields along the edges  $\gamma_1$  and  $\overline{\gamma}_1$  repectively. They give raise to ruled surfaces c and  $\overline{c}$ . For example c:  $\mathbb{R} \times [0, l_1] \longrightarrow M^n$ ,  $(s,t) \longmapsto c(s,t)$  is characterized by the formulae:

$$c(0,t) = \gamma_1(t)$$
  $c'(0,0) = -\gamma'_0(t_0)$ 
 $\nabla_c c'|_{(0,t)} = 0$   $\nabla_{c'} c' = 0$ 

Here as usual a prime denotes a derivative with respect to s and a dot denotes a derivative with respect to t .

Observations:

i)  $\overline{\gamma}_2$  is contained in the image of  $[0,\infty) \times [0,\ell_1]$  under  $\overline{c}$ . By notation  $\overline{\gamma}_2(\overline{\ell}_2) = \overline{p}_1$  and  $\overline{\gamma}_2(0) = \overline{p}_0$ . Because of the Gauß-Bonnet theorem  $\frac{1}{2}(\overline{\gamma}_2',\overline{c}')$  is non-decreasing along  $\overline{\gamma}_2$ . Hence  $\overline{\gamma}_2$  is contained in  $\overline{V} := \overline{c}(U)$ , where U stands for the cube  $[0,\epsilon/2) \times [0,\ell_1]$ . ii) c(U) is contained in  $B(p_0,r_{\Delta}+1)$ , and therefore our choices above imply that in U there are no focal points on the geodesics  $s \mapsto c(s,t)$ 

$$-k(d(p_o,c(s,t))) \geq -k_{\epsilon/2}(d(p_o,c(0,t)))$$

$$= -k_{\epsilon/2}(d(\bar{p}_o,\bar{c}(0,t))) \geq -k_{\epsilon}(d(\bar{p}_o,\bar{c}(s,t)))$$

holds for all (s,t) € U . Hence Rauch's comparison theorem yields :

$$|\dot{c}| \leq |\dot{c}|$$
 on t

By construction the inequality

Here  $\bot$  denotes the component orthogonal to the unit vectors c' resp.  $\bar{c}'$ . We conclude that the map  $c \circ \bar{c}^{-1} \colon \bar{V} \longrightarrow M^n$  is distance non-increasing.

It follows that  $t \mapsto c \cdot \overline{c}^{-1} \cdot \overline{\gamma}_{2}(t)$  defines a curve in  $M^{n}$  which joins  $p_{0}$  and  $p_{1}$  and is not longer than  $\overline{\gamma}_{2}$ . This proves (\*).

# II. Analyzing the Decay Condition

Throughout this chapter we assume  $\lambda\colon [0,\infty) \longrightarrow [0,\infty)$  to be a monotone non-increasing function. Roughly speaking the integral  $b_0(\lambda)$  converges, iff  $\lambda(r)$  decays a little quicker than  $r^{-2}$  for  $r \to \infty$ . We start making this observation more precise.

#### 1.1 Lemma:

Whenever  $b_0(\lambda)$  converges, there exist monotone non-increasing functions:

$$\lambda_{1} : r \longmapsto \int_{r}^{r} \lambda(\rho) d\rho$$

$$\lambda_{2} : r \longmapsto \int_{r}^{r} \lambda_{1}(\rho) d\rho$$

$$\lambda_{b} : r \longmapsto \int_{r}^{r} \rho \cdot \lambda(\rho) d\rho = \lambda_{2}(r) + r \cdot \lambda_{1}(r)$$

Moreover the following estimates hold:  $(r \ge 0)$ 

$$\begin{aligned} \mathbf{r}^2 \cdot \lambda(\mathbf{r}) & \stackrel{\checkmark}{=} 2 \cdot \mathbf{b}_0(\lambda) \\ \mathbf{r} \cdot \lambda_1(\mathbf{r}) & \stackrel{\checkmark}{=} \mathbf{b}_0(\lambda) \\ & \tilde{\mathbf{b}}_0(\lambda) & := \int_0^\infty \inf \left\{ \lambda_1(\mathbf{r}), \sqrt{\lambda(\mathbf{r})} \right\} d\mathbf{r} & \stackrel{\checkmark}{=} \lambda_2(0) & = \mathbf{b}_0(\lambda) \end{aligned}.$$

#### Proof:

The expressions  $\lambda_1(r)$  and  $\lambda_b(r)$  obviously converge. The existence of  $\lambda_2(r)$  follows from the theorems by Fubini and Tonelli:

$$\lambda_{2}(\mathbf{r}) = \int_{\mathbf{r}}^{\infty} \int_{\mathbf{t}}^{\infty} \lambda(\rho) \, d\rho d\mathbf{r} = \int_{\mathbf{r}}^{\infty} (\rho - \mathbf{r}) \cdot \lambda(\rho) \, d\rho$$
$$= \lambda_{b}(\mathbf{r}) - \mathbf{r} \cdot \lambda_{1}(\mathbf{r})$$

The remaining estimates are due to the computations:

$$r^{2} \cdot \lambda(r) = 2 \cdot \lambda(r) \cdot \int_{0}^{r} \rho \, d\rho \leq 2 \cdot \int_{0}^{r} \rho \cdot \lambda(\rho) \, d\rho \leq 2 \cdot b_{0}(\lambda)$$
and
$$r \cdot \lambda_{1}(r) = \lambda_{1}(r) \cdot \int_{0}^{r} d\rho \leq \int_{0}^{r} \lambda_{1}(\rho) \, d\rho \leq b_{0}(\lambda)$$

#### 1.2 Remarks:

i) Almost the same computations give raise to the formulae:

$$\lim_{r\to\infty} r^2 \cdot \lambda(r) = 0$$

and 
$$\lim_{r\to\infty} r \cdot \lambda_1(r) = 0$$

ii) Observe that for  $T_c\lambda(r) := c^2 \cdot \lambda(c \cdot r)$ ,  $r \ge 0$ , c > 0, one has:

and 
$$(T_c \lambda)_1(r) = c \cdot \lambda_1(c \cdot r)$$
  
 $(T_c \lambda)_2(r) = \lambda_2(c \cdot r)$ 

Therefore the invariant  $b_0(M^n)$  does not change, when the metric of the asymptotically non-negatively curved manifold is scaled with some global factor.

iii) We point out that it does not depend on the choice of the base point o in a Riemannian manifold  $(M^n,g)$  whether the integral  $b_0$  converges. However its numerical value is very sensitive with respect to the position of o . This is related to the fact that  $b_0$  does not detect certain curvature singularities at o . Such a task would require much refined numerical invariants.

Later on we shall need information about the models  $M^2(-\lambda)$ . This means basically that we have to study the Jacobi field equation:

$$y''(r) = \lambda(r) \cdot y(r)$$

#### 2.1 Lemma:

The following conditions are equivalent:

- i)  $b_0(\lambda) < \infty$
- ii) for any solution y of equation (\*) there exists  $y'(\infty):=\lim_{n\to\infty} y'(r)$ .

#### Proof:

We assume that  $r > r_1 > 0$  and compute:

$$|y'(r) - y'(r_1)| \leq \int_{r_1}^{r} \lambda(\rho) \cdot |y(\rho)| d\rho$$

$$\leq \lambda_1(r_1) \cdot |y(r_1)| + \lambda_2(r_1) \cdot |y'(r_1)|$$

$$+ \lambda_2(r_1) \cdot \max\{|y'(\rho) - y'(r_1)| \mid r_1 \leq \rho \leq r\}$$

Provided that  $r_1$  is sufficiently large, we know that  $\lambda_2(r_1) \le \frac{1}{2}$ , and hence we obtain for  $r > r_1 >> 0$  that:

$$|y'(r) - y'(r_1)| \le 2 \cdot \lambda_1(r_1) \cdot |y(r_1)| + 2\lambda_2(r_1) \cdot |y'(r_1)| =: C(r_1)$$

This already shows that y' remains bounded. We iterate the inequality

and conclude that for  $r > r_2 > r_4 >> 0$  we have:

$$|y'(r) - y'(r_2)| \le 2 \cdot \lambda_1(r_2) \cdot |y(r_1)| + 2 \cdot (r_2 \cdot \lambda_1(r_2) + \lambda_2(r_2)) \cdot (|y'(r_1)| + C(r_1))$$

The right-hand side converges to zero for  $r_2 + \infty$ .

#### 2.2 Lemma:

$$(1+b_{o}(\lambda)) \cdot z_{\infty}(\infty) \leq 1$$

This estimate is an obvious consequence of the following formulae:

$$z_{\infty}^{1}(r) = \int_{r}^{\infty} \lambda(\rho) \cdot z_{\infty}(\rho) d\rho$$

$$z_{\infty}(r) = z_{\infty}(\infty) + \int_{r}^{\infty} (\rho - r) \cdot \lambda(\rho) \cdot z_{\infty}(\rho) d\rho \ge z_{\infty}(\infty) \cdot (1 + \lambda_{2}(r))$$
.

The Jacobi field  $z_{\infty}$  is closely related to the invariant  $b_{1}$ ; observe that the function  $-z_{\infty}(r)^{-1} \cdot z_{\infty}(r)$  converges to zero for  $r + \infty$ , and that it obeys the Riccati equation:

(\*\*) 
$$u'(r) = u(r)^2 - \lambda(r)$$

#### 2.3 Lemma:

Let  $b_0(\lambda) < -$ ; then there is a unique solution u of (\*\*) such that  $u(r) \longrightarrow 0$  for  $r \longrightarrow \infty$ . Even more one has the estimates:

i) 0 
$$\leq u(r) \leq \min\{\lambda_1(r), \sqrt{\lambda(r)}\}$$

$$ii$$
)  $b_1(\lambda) := \int_0^{\infty} u(r) dr \leq \tilde{b}_0(\lambda) \leq b_0(\lambda)$ 

#### Proof:

Consider the continuous functions u, which vanish identically on  $[2,\infty)$  and solve for (\*\*) on [0,2]. Since  $0'=0 \ge -\lambda$  and  $\lambda_1'=-\lambda$  $\leq \lambda_1^2 - \lambda$  , standard monotony arguments yield the estimate

$$0 \quad \neq \quad u_{\underline{t}}(r) \quad \neq \quad \lambda_{\underline{1}}(r)$$

Therefore the limits

$$u(r) := \lim_{n \to \infty} u_n(r)$$

exist and the function u meets the desired conditions.

- i) It is also easy to verify that the functions u, are monotone and that hence  $u_{r}(r) = \sqrt{\lambda(r)}$ .
- ii) This inequality is clear from the definitions.

2.4 Remarks:

i) 
$$z_{\infty}(r) = \exp(-\int_{0}^{r} u(\rho) d\rho) \ge z_{\infty}(\infty) > 0$$

ii) By lemma 2.2 and lemma 2.3ii it is clear that all our invariants associated to a function  $\lambda$  are equivalent in some non-linear sense:

$$b_1(\lambda)$$
  $\stackrel{\checkmark}{=}$   $\tilde{b}_0(\lambda)$   $\stackrel{\checkmark}{=}$   $b_0(\lambda)$   $\stackrel{\checkmark}{=}$   $\exp(b_1(\lambda)) - 1$ 

Moreover all the invariants depend on the function  $\lambda$  in a monotone way.

In chapter III there will be a situation where some uniform control on a family of model spaces  $M^2(\neg\lambda)$  is required. This estimate can be done comparing the solutions  $z_{\ell}$  of (\*) to the function  $z_{\infty}$ . For the sake of brevity we shall use the notation:

$$\beta := z_{\infty}(\infty) = \exp(-b_{1}(\lambda))$$

## 2.5 Lemma:

$$\vec{i} \qquad \beta \leq z_{\infty}(r) \leq 1 \qquad , 0 \leq r < \infty$$

ii) 
$$(1-\frac{r}{t}) \cdot z_{\infty}(t) \leq z_{t}(r)$$
 ,  $0 \leq r \leq t$ 

iii) 
$$\frac{\beta}{t} = -z_{t}^{\dagger}(t) = -z_{t}^{\dagger}(0) = -z_{\infty}^{\dagger}(0) + \frac{1}{t} \cdot z_{\infty}(t) = \frac{1}{t} + \lambda_{1}(0)$$

## Proof:

- i) c.f. remark 2.4i .
- ii) The difference  $\Delta z := z_{\infty} z_{\chi}$  also solves the differential equation (\*). As it is non-negative on  $[0,\infty)$ , it is a convex function:

$$\Delta z(r) \leq \frac{r}{t} \cdot \Delta z(t) + (1 - \frac{r}{t}) \cdot \Delta z(0) = \frac{r}{t} \cdot z_{\infty}(t)$$

$$\Rightarrow z_{\underline{t}}(r) \geq z_{\underline{\omega}}(r) - \frac{r}{t} \cdot z_{\underline{\omega}}(t) \geq (1 - \frac{r}{t}) \cdot z_{\underline{\omega}}(t)$$

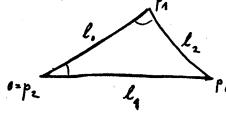
iii) Using part (ii) and monotony, the first, the second, and the last inequality are obvious. In order to obtain the third inequality, we use the convexity of Δz and compute:

$$z_{\infty}^{\dagger}(0) - z_{\underline{t}}^{\dagger}(0) = \Delta z^{\dagger}(0) \leq \frac{1}{\underline{t}} \cdot \Delta z(\underline{t}) = \frac{1}{\underline{t}} \cdot z_{\infty}(\underline{t})$$

# III. Geodesic Triangles and the Number of Ends in asymptotically non-negatively curved Manifolds

The generalized triangles which have one of their vertices at the base point o of M form a rather distinguished class of objects. They might serve as tools to study the properties of M; in view of packing arguements their angle at o deserves special interest. At a first look this very angle seems to cause difficulties: there might be conjugate points which prevent one from contoling the Jacobi fields along a family of geodesics emanating from o; moreover there is no hypothesis on the cut-locus, and hence one does not know the lower curvature bound along these geodesics explicitely. Nevertheless the generalized Toponogov theorem allows for some rough estimates.

1. Proposition:



Let  $a, \epsilon \in (0,1)$  and let  $\Delta = (p_0, p_1, p_2)$  be a generalized geodesic triangle in an asymptotically non-negatively curved manifold  $M^n$ . Suppose moreover that  $a = (1-\epsilon) \cdot a$  and that a = 1 is the base

point o of M<sup>n</sup>. Then the following estimates hold:

i) 
$$\cos(\frac{\pi}{at} \circ) \ge \sqrt{1 - a^2 \cdot \beta^2 \cdot \epsilon^2}$$

$$\Rightarrow \ell_2 \le \ell_1 - \ell_0 \cdot \sqrt{1 - a^2}$$

ii) 
$$\cos(\frac{1}{2}at p_1) \ge -\sqrt{1-a^2}$$

$$\Rightarrow \ell_1 \le \ell_2 + \ell_0 \cdot \sqrt{1-a^2 \cdot \beta^2 \cdot \epsilon^2}$$

iii) 
$$\neq$$
 at o acute,  
 $\Rightarrow$   $|\sin(\neq at o)| \Rightarrow \beta^2 \cdot \epsilon^2 \cdot |\sin(\neq at p_1)|$ 

#### Proof:

We put  $l := l_1 = d(p_0, 0)$  and  $k(r) := \lambda(|l-r|)$ , r > 0. Making use of the triangle inequality and the monotonicity of  $\lambda$ , we see that for all p in  $M^n$ :

1.1 curvatures at 
$$p = -\lambda(d(p,o)) = -k(d(p,p_o))$$

i) We can apply the generalized comparison theorem (c.f. I.3.2.b) and reduce things to a problem in the model space  $M^2(-k)$ , where the radial

Jacobi field y is a multiple of the function  $z_{\ell}(\ell-.)$  defined in section II.2. We consider the function r along the edge  $\bar{\gamma}_0$ . This unit-speed geodesic joins  $\bar{p}_1 = \bar{\gamma}_0(0)$  and  $\bar{p}_2 = \bar{\gamma}_0(\ell_0)$ . By monotonicity we may restrict to the case where

$$r'(t_0) = \cos(xat \bar{p}_2) = \sqrt{1-a^2 \cdot \beta^2 \cdot \epsilon^2}$$

The conservation law I.2.1iii becomes:

1.2 
$$z_{i}(1-r)^{2} \cdot (1-r^{2}) = const$$

Observing that  $r(t_0) = \overline{t}_1 = t_1$ , we obtain:

$$a^{2} \cdot \beta^{2} \cdot \epsilon^{2} = z_{t}(0)^{2} \cdot (1 - \cos^{2}(\frac{1}{2} \operatorname{at} \overline{p}_{2}))$$

$$= z_{t}(t - r(s))^{2} \cdot (1 - r'(s)^{2})$$

$$\geq \epsilon^{2} \cdot z_{\infty}(t)^{2} \cdot (1 - r'(s)^{2}) , 0 \leq s \leq t_{0}$$

here the inequality is due to lemma II.2.5ii and to the fact that  $r(s) = t_1 - t_2 = \epsilon \cdot t$ . We conclude that

$$a^2 \ge 1 - r'(s)^2 \qquad , 0 \le s \le \ell_0$$

Therefore the continuous function r' does not vanish in the interval  $[0,t_0]$ , and there we get:

$$r' = \sqrt{1-a^2}$$

Hence 
$$\bar{t}_2 = r(0) \le r(t_0) - t_0 \cdot \sqrt{1-a^2} = t_1 - t_0 \cdot \sqrt{1-a^2}$$
.

ii) Here an indirect proof works: assume that  $\ell_1 > \ell_2 + \ell_0 \cdot \sqrt{1-a^2 \cdot \beta^2 \cdot \epsilon^2}$ . Again we make use of the generalized Toponogov theorem. Exchanging the roles of  $p_1$  and  $p_2$ , we obtain a triangle  $\Delta = (\vec{p}_0, \vec{p}_1, \vec{p}_2)$  in the model  $M^2(-k)$  such that

$$\bar{t}_0 = t_0$$
 ,  $\bar{t}_1 \ge t_1$  ,  $\bar{t}_2 = t_2$  ,  $\cos(4at \bar{p}_1) = -\sqrt{1-a^2}$ .

The function r along  $\bar{\gamma}_0$  obeys  $r(0) = t_2$  and  $r'(0) = \sqrt{1-a^2}$ . Since  $t - \bar{t}_2 \le t_0 \le (1-\epsilon) \cdot t$ , we can deduce from formula 1.2 that

$$z_{\underline{t}}(\underline{t-r})^{2} \cdot (\underline{1-r'}^{2}) = z_{\underline{t}}(\underline{t-\bar{t}}_{2})^{2} \cdot (\underline{1-r'}(0)^{2})$$

$$= a^{2} \cdot z_{\underline{t}}((\underline{1-\epsilon}) \cdot \underline{t})^{2} = a^{2} \cdot \beta^{2} \cdot \epsilon^{2}$$

As long as  $r(s) \le t$ , we have  $z_{\frac{1}{2}}(t-r) \le 1$ , and hence:

$$r(s) = t_2 + s \cdot \sqrt{1 - a^2 \cdot \beta^2 \cdot \epsilon^2}$$

The standard continuity arguement now yields the contradiction

$$\bar{t}_1 = r(t_0) \leq t_2 + t_0 \cdot \sqrt{1 - a^2 \cdot \beta^2 \cdot \epsilon^2} < t_1$$

iii) Put a<sub>1</sub>:=sin(≰at p<sub>1</sub>) ; then we conclude with the aid of part (ii)
that

$$\ell_1 \leq \ell_2 + \ell_0 \cdot \sqrt{1 - a_1^2 \cdot \beta^2 \cdot \epsilon^2}$$

Reversing the implication in (i), we obtain:

$$\cos(\frac{1}{2}at o) \leq \sqrt{1-a_1^2 \cdot \beta^4 \cdot \epsilon^4}$$

The proof is then finished, as the angle at o is acute by hypothesis.

We recall that two curves  $c_1$ ,  $c_2:[0,\infty) \longrightarrow M$  are said to be cofinal, if and only if for every compact set K<M there is some t>0 such that  $c_1(t_1)$  and  $c_2(t_2)$  lie in the same connected component of M\K for all  $t_1$ ,  $t_2 \ge t$ . An equivalence class of cofinal curves is called an end of M.

### Elementary Properties:

2.1. Any family of relatively compact open sets  $(U_i)_{i \in \mathbb{N}}$  which exhaust M, i.e. which obey  $U_i \in U_{i+1}$  and  $\bigvee_i U_i = M$ , defines a bijection:

{ends E of M} 
$$\stackrel{\simeq}{\longleftrightarrow}$$
 {(E<sub>i</sub>)<sub>i∈N</sub>|E<sub>i+1</sub>∈E<sub>i</sub> and E<sub>i</sub> is a connected component of M\ $\overline{U_i}$ }

Notice that for each of these inverse systems  $E = (E_i)_{i \in \mathbb{N}}$  the sets  $E_i$  are non-empty and their closures  $\overline{E_i}$  in M are non-compact. Moreover, if M has only finitely many ends, then there is some  $i_0 > 0$  such that all the inverse systems  $(E_i)_{i \in \mathbb{N}}$  stabilize for  $i \ge i_0$ , i.e.  $E_i = E_i$ .

- 2.2. Given a point peM, then any end E of M contains a ray  $\gamma$  emanating from p; recall that by definition  $\gamma$  is a geodesic  $[0,\infty) \longrightarrow M$  such that each of its segments is shortest and that  $\gamma(0) = p$ .
- 2.3. Given any two distinct ends  $E^1$  and  $E^2$  of M, there is a line  $\gamma\colon\mathbb{R}\longrightarrow M$  such that the rays  $\gamma_\pm\colon [\cap,\infty)\longrightarrow M$ ,  $t\longmapsto \gamma(\pm t)$  are contained in  $E^1$  and  $E^2$  respectively.
- 2.4. As is the case for the ideal boundary in the theory of non-compact surfaces, the set of ends carries a natural topology; a basis for the open sets is parametrized by the non-compact closed subsets C < M:

$$U_C := \{ends (E_i)_{i \in \mathbb{N}} | E_i \in C \text{ for i sufficiently large} \}$$

In this way {ends E of M} becomes a compact, separable, totally disconnected space. (c.f. [AS], [R].)

## 3. Theorem:

Every asymptotically non-negatively curved manifold  $M^n$  has at most finitely many ends. More precisely:

#{ends E of M} 
$$\leq 2 \cdot \pi^{n-1} \cdot \exp((n-1) \cdot b_i)$$

Here  $b_1$  is the invariant introduced in II.2.3.

<u>Proof:</u> For each end E of M we pick a unit-speed ray  $\gamma_E$  which emanates from o and is contained in E. We consider the set of unit vectors  $\mathbf{v}_E$ := $\gamma_E^{\;!}(0)$  in  $\mathbf{T}_0^{\;M}$ . It is a consequence of proposition I that for any unit vector  $\mathbf{v} \in \mathbf{T}_0^{\;M}$  which is sufficiently close to some  $\mathbf{v}_E$  the geodesic  $\gamma\colon [0,\infty) \longrightarrow M$ ,  $t\longmapsto \exp_O(t\cdot \mathbf{v})$  is contained in the end E; in some more detail one obtains:

$$\langle v, v_E \rangle = \sqrt{1 - a^2 \cdot \beta^2 \cdot \epsilon^2}$$
,  $0 < a^2, \epsilon^2 < 1$   
 $\Rightarrow d(\gamma_E(t), \gamma((1-\epsilon) \cdot t)) \le t - (1-\epsilon) \cdot t \cdot \sqrt{1 - a^2} =: q_{a,\epsilon} \cdot t$ 

where  $0 < q_{a,\epsilon} < 1$ ; therefore  $\gamma$  is contained in E provided < v,  $v_E > \sqrt{1-\beta^2}$ . Thus the balls  $B_E^S$  in the unit sphere.  $S^{n-1} \subset T_0 M$  with centres  $v_E$  and radii  $\frac{1}{2}$ ; arcsin( $\beta$ ) are pairwise disjoint. Notice that  $\arcsin(\beta) \Rightarrow \beta = \exp(-b_1)$ ; so the claimed bound on the number of ends is a direct consequence of the following well-known packing lemma.

#### 3.1 Lemma:

Let  $0 < \rho \le \frac{\pi}{2}$ ; then the number of disjoint balls  $B^S(\rho) < S^{n-1}$  with radius  $\rho$  does not exceed

$$\frac{\text{vol } S^{n-1}}{\text{vol } B^{S}(\rho)} \quad \text{\'e} \quad 2 \cdot \left(\frac{\pi}{2 \cdot \rho}\right)^{n-1}$$

## IV. Surfaces and other Examples

In this chapter we are going to discuss the hypothesis and conclusions of theorem B. A first set of examples shows that for surfaces the theorem is definitely wrong when the integral  $b_0$  diverges (c.f. IV.1). Moreover we shall see that the given bounds on the number of ends and on the Betti numbers are reasonable in a certain sense: in section IV.2 we construct surfaces with large invariants  $b_0$  and  $b_1$  such that theorem B overestimates the number of ends by not more than a factor of  $2\pi$ ; in section IV.3 we consider the higher-dimensional case and give a set of examples where the bounds actually grow exponentially in  $n \cdot b_1(M^n)$ .

# 1. Theorem:

Let 
$$\lambda: [0, \infty) \longrightarrow [0, \infty)$$
 be a continuous function such that the integral 
$$\int_{0}^{\infty} r \cdot \lambda(r) dr$$

diverges. Then every non-compact, connected surface  $M^2$  with base point o carries a  $C^2$ -metric g with curvature

(\*) 
$$\kappa(p) = -\lambda(d(o,p))$$
 at any point  $p \in M^2$ 

#### Remarks:

- 1.1. Obviously  $\mathbb{R}^2$  becomes the surface of revolution  $M^2(-\lambda)$ , which has been described in chapter I.1.
- 1.2. Suppose that the curvature of a surface  $(M^2,g)$  with base point o obeys condition (\*) above. Then the complement of the cut-locus of o is isometric to a tree-like open subset in  $M^2(-\lambda)$ ; the isometry is given by exp and the obvious identifications.

Moreover the generic cut points, i.e. those cut points which are joined to o by precisely two minimizing geodesics, lie on open geodesic segments in  $(M^2,g)$ .

1.3. In order to reverse the preceeding observation and construct some more examples, we look at two non-intersecting geodesics  $\gamma_1$  and  $\gamma_2$  in  $M^2(-\lambda)$  which have equal distance to the base point. Notice that they can be mapped onto each other by an isometry  $\phi$  of  $M^2(-\lambda)$ . We take that component of  $M^2(-\lambda) \cap (\gamma_1 \cup \gamma_2)$  which contains the pole. We take its closure and glue the boundary components  $\gamma_1$  and  $\gamma_2$  by means of  $\phi$ . The differentiable structure of the quotient manifold

 $M^2$  is conveniently described using normal exponential coordinates around the geodesics  $\gamma_1$  and  $\gamma_2$ . The quotient metric g on the surface  $M^2$  turns out to be of class  $C^2$ ; the reason is that the curvature function of  $M^2(-\lambda)$  is invariant under the clutching map  $\phi$ .

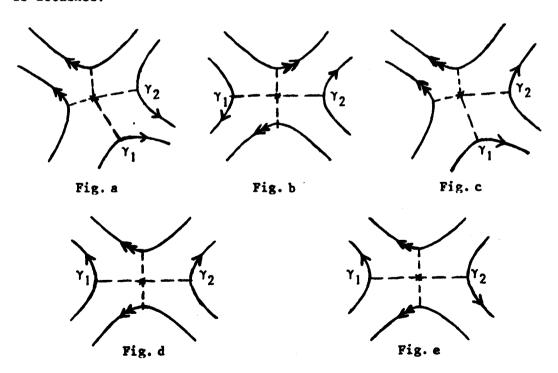
1.4. This construction can be iterated as long as one can find an appropriate pair of geodesics  $\gamma_1$ ,  $\gamma_2$  in

 $(T_0M_j^2)^{int} := \{x \in T_0M_j^2 \mid 0 \text{ and } x \text{ are joined by an arc which does not contain a cut point.} \}$ 

It gives rise to a surface  $M_{j+1}^2$ , which differs from  $M_j^2$  topologically and the metric  $g_{j+1}$  still obeys condition (\*). Depending on the position of the geodesics and the orientation of  $\phi$  there are four distinct cases:

i) If  $\gamma_1$  and  $\gamma_2$  lie in the same end  $E_j$  of  $(M_j^2, g_j)$ , then either  $E_j$  is split into two ends  $E_{j+1}^1$  and  $E_{j+1}^2$  (Fig. a & Fig. b) or a cross cap is attached to  $E_j$  (Fig. c).

ii) If  $\gamma_1$  and  $\gamma_2$  lie in different ends  $E_j^1$  and  $E_j^2$ , then these ends are glued; a handle (Fig. d) resp. a Kleinian bottle (Fig. e) is attached.



1.5. Basically it is the function  $\lambda$  which determines how often the constructions 1.4i and 1.4ii can be applied. Let us assume that

$$\int_{0}^{\infty} \mathbf{r} \cdot \lambda(\mathbf{r}) d\mathbf{r}$$

diverges. Then the integral of the curvature over an arbitrary sector in  $M^2(-\lambda)$  also diverges, and this surface turns out to be a visibility manifold (c.f. [EN]); the angle  $\alpha(\gamma)$  of the sector in which a geodesic  $\gamma$  is seen from the pole o decreases to zero when  $\operatorname{dist}(o,\gamma) \rightarrow \infty$ . Hence in any conical end of a surface  $M_j^2$  one can go out far enough and find geodesics  $\gamma_1$  and  $\gamma_2$ , suitable for the constructions 1.4i and 1.4ii. Moreover it is possible to pick these geodesics in such a way that the manifold  $M_{j+1}^2$  has only conical ends, provided  $M_j^2$  had.

Therefore - whenever the above integral of  $\lambda$  diverges - metrical considerations do not impose any conditions on the combinatorial patterns for iterating the constructions 1.4.

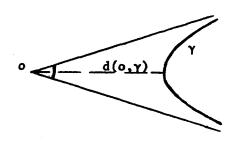
#### Proof of the Theorem:

Standard classification results imply that in remark 1.5 we have constructed all non-compact, orientable and non-orientable surfaces which have finite genus and finitely many ends. Next we consider a sequence of surfaces  $M_j^2$  and perform all the surgery simultaneously. This yields a manifold  $M_\infty^2$  which carries a metric  $g_\infty$  obeying condition (\*). Our goal is to finish the arguement using the classification of surfaces. This classification result is due to Richardson [R] and requires the following data:

- i) a triple of totally-disconnected, separable, compact sets A<B<C
- ii) orientability (dispensible, if  $A \neq \emptyset$ .)
- iii) genus (dispensible, if B≠Ø.)

Here A describes the infinitely non-orientable ends, B the ends with infinite genus, and C simply contains all points of the ideal boundary. It is known that totally-disconnected, separable, compact sets like Cantor sets are related to equivalence classes of trees. These trees govern the combinatorial pattern according to which the constructions 1.4 have been iterated.

2. Next we consider a function  $\lambda$  such that the integral  $b_0(\lambda)$  is finite. We are going to construct a surface  $M^2$  which has as many ends as possible. For this purpose we look at the geodesic triangle  $\Delta$  in  $M^2(-\lambda)$  which is given by the pole o and an arbitrary geodesic  $\gamma$  and which has two vertices at infinity. The Gauß-Bonnet theorem yields:



(\*\*) 
$$\neq$$
 at  $o = \pi - \int_{\Delta} \lambda(d(o,.)) dvol$ 

The differential equation  $y'' = \lambda \cdot y$  and the initial data y(0) = 0, y'(0) = 1 as usual describe a radial Jacobi field and determine polar coordinates. Moreover it

is possible to define another invariant

$$b_2(\lambda) := \lim_{r \to \infty} y^r(r)$$

We can now proceed and estimate the right-hand side of (\*\*):

$$\sharp \text{at o} \stackrel{d}{=} \pi - \int_{0}^{d(0,\gamma)} \lambda(r) \cdot y(r) \, dr \cdot \sharp \text{at o}$$

Hence  $(\mbox{$\not$}$  at o)  $\mbox{$\circ$} y'(d(o,\gamma)) \leq \pi$ , and we can pick at least  $2\mbox{$\circ$} [y'(d)]$  non-intersecting geodesics  $\gamma$  in  $M^2(-\lambda)$ , each of them with distance d to the base point o. Applying the construction from 1.4i as often as we can, we obtain a surface with [y'(d)] ends. Finally we pass to the limit  $d \leftrightarrow \infty$ :

## 2.1 Proposition:

Whenever the invariant integral  $b_0(\lambda)$  of some function  $\lambda: [0,\infty) \to [0,\infty)$  is finite, then there exists a surface  $(M^2,g)$  which has at least  $\exp(b_2(\lambda))-1$  ends and whose curvature obeys the condition

$$\kappa(p) = -\lambda(dist(p,base\ point))$$
 for all  $p \in M^2$ 

This proposition shows that for surfaces the previously given upper bound on the number of ends is sharp up to a factor of at most  $2\pi$ ; we pick  $\lambda$  to be the characteristic function of [0,d] and compute:

$$b_0(\lambda) = \frac{1}{2} \cdot d^2 , b_1(\lambda) = \ln \cosh(d) , b_2(\lambda) = \ln \sinh(d) ;$$
 asymptotically  $b_1$  and  $b_2$  coincide.

3. Our last examples shall demonstrate that for asymptotically non-negatively curved manifolds  $M^n$  the number of ends and the sum of the Betti numbers can grow exponentially in  $n \cdot b_1(M^n)$  each. We point out that Riemannian products of the above surfaces are totally inadequate in either case. Partially this is due to the fact that the function  $\lambda$  changes when passing to products.

We are going to construct some tree-like looking objects. Roughly speaking the desired growth in  $n \cdot b_1(M^n)$  is acchieved by using building blocks of the same type only. In order to describe these pieces it is convenient to think of a hypersurface in  $\mathbb{R}^{n+1}$  which is obtained by glueing cylinders  $\mathbb{R}^+ \times \mathbb{S}^{n-1}$  perpendicular onto a hyperplane  $\mathbb{R}^n$  where appropriate balls have been removed. The curvature is kept bounded by plugging in some intermediate tubes. Again we use the "same" tube everywhere, and a packing arguement assures that the number of ends of a single building block grows exponentially in n.

# 3.1. the intermediate tubes:

We fix some  $t_0 > 0$  and consider the warped products  $Tb^n(t_0) = ([0,t_0] \times S^{n-1}, ds^2)$ , where the metric is defined by:  $ds^2 = dt^2 + \sinh^{-2}(t_0) \cdot \cosh^2(t_0 - t) \cdot d\omega^2$ 

Here  $d\omega^2$  denotes the standard metric on  $S^{n-1}$ . Properties:

i) diam 
$$Tb^{n}(t_{o}) \leq \max_{o \leq t \leq t_{o}} t + \pi \cdot \sinh^{-1}(t_{o}) \cdot \cosh(t_{o} - t)$$
  

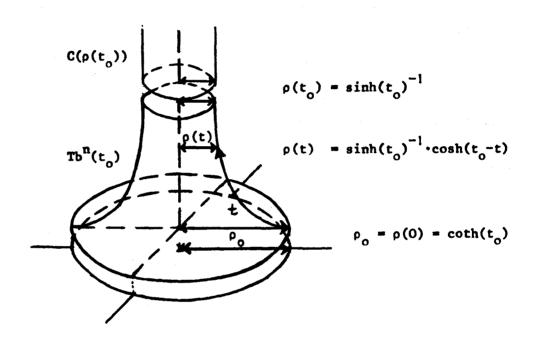
$$= \pi \cdot \coth(t_{o}) + \max\{0, t_{o} - \pi \cdot \tanh(\frac{1}{2} \cdot t_{o})\}$$

- ii) the tubes  ${
  m Tb}^n({
  m t}_0)$  can be embedded as rotationally symmetrical hypersurfaces in  ${
  m I\!R}^{n+1}$  .
- iii)  $Tb^2(t_0)$  has constant curvature equal to -1, and for n > 2 the  $Tb^n(t_0)$  have sectional curvatures  $\ge -1$ .
- iv) the boundary components  $\{0\} \times S^{n-1}$  and  $\{t_o\} \times S^{n-1}$  are spheres with constant curvature  $\tanh^2(t_o)$  and  $\sinh^2(t_o)$  respectively. (n > 2).

  As submanifolds in  $\mathrm{Th}^n(t_o)$  they have principal curvatures  $\tanh(t_o)$  and 0 respectively.
- v) the tube Tb<sup>n</sup>(t<sub>o</sub>) can be doubled in an analytical way along the

boundary component  $\{t_o\} \times S^{n-1}$ . The same boundary component of the tube can be glued isometrically to the boundary of a cylinder  $C(\sinh^{-1}(t_o)) := \sinh^{-1}(t_o) \cdot (\mathbb{R}^+ \times S^{n-1})$  with radius  $\sinh^{-1}(t_o)$ ; this time curvature is only bounded, but non-continuous.

vi) at  $\{0\} \times S^{n-1}$  the tube  $Tb^n(t_0)$  can be glued with bounded, but non-continuous curvature to  $\mathbb{R}^n \setminus B(x, \coth(t_0))$ ,  $x \in \mathbb{R}^n$  arbitrary.



# 3.2 the building blocks $A^n$ :

Let  $t_0>0$ ,  $r_0\ge 2$ ,  $\rho_0:=\coth(t_0)$ , and let  $B_0$  be the ball  $B(0,\rho_0)$  in  $\mathbb{R}^n$ . We pick a maximal family of mutually disjoint open balls  $B_1$ , ...,  $B_N$  with radius  $\rho_0$  in the subset  $B(0,(r_0+1)\cdot\rho_0) \setminus B_0$ . We remove all N+1 balls  $B_0$ , ...,  $B_N$  and - as described in 3.1vi - attach tubes  $Tb^n(t_0)$  to the boundaries  $\partial B_0$ , ...,  $\partial B_N$ . The boundary of the resulting manifold  $A^n$  consists of the spheres  $\{t_0\}\times S^{n-1}$  in the attached tubes. For later use it is convenient to single out the boundary of the central tube which has been glued to  $\partial B_0$ ; we shall call it  $a^n$ .

# Properties:

i)  $\# \{ \text{ends of } A^n \} = 1$  $\# \{ \text{boundary components of } A^n \} = N+1$  ii) in  $\mathbb{R}^n$  the enlarged balls  $2 \cdot B_j$ ,  $0 \le j \le N$ , cover  $B(0, r_0 \cdot \rho_0)$ ; hence:

$$N+1 \geq \left(\frac{1}{2} \cdot \mathbf{r}_0\right)^n$$

- iii) in  $\mathbb{R}^n$ : dist( $B_0$ ,  $B_j$ ) =  $(r_0 2) \cdot \rho_0$ ;  $1 \le j \le N$ Moreover for each j there exists a curve in  $\mathbb{R}^n \setminus \bigcup_{j \ge 0} B_j$  which joins  $\partial B_0$  and  $\partial B_j$  and which has length  $\supseteq (r_0 2) \cdot \rho_0$ .
- iv) for any point  $p \in A^n$  which is non-flat and for any point  $p \in A^n$  one has:

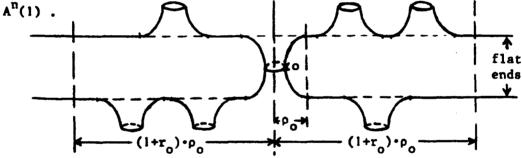
$$d(p,a^n) \leq \frac{\pi}{2} \cdot (r_0 - 2) \cdot \rho_0 + diam \ Tb^n(t_0) + t_0$$

v) the sectional curvatures of  $A^n$  are  $\geq -1$ .

# 3.3 the trees $A^{\Pi}(\mu)$ :

We use the following inductive construction:

i) We glue two copies of the manifold  $A^n$  by identifying their boundary spheres  $a^n$ . On this sphere we pick a base point o for the quotient



ii) We assume that  $A^n(\mu)$  has been constructed and that all its  $2 \cdot N^{\mu}$  boundary components are totally geodesic spheres with diametre equal to  $\pi \cdot \sinh^{-1}(t_0)$ . Then we can attach to each of these spheres the central boundary  $a^n$  of a new copy of  $A^n$ , and thus we can glue  $2 \cdot N^{\mu}$  copies of  $A^n$  to  $A^n(\mu)$ . We define this larger manifold to be the  $\mu + 1^{st}$  generation object  $A^n(\mu + 1)$ .

# 3.4 the manifolds $M^{n}(\mu)$ :

We obtain non-compact, complete Riemannian manifolds  $M^n(\mu)$  by glueing to each boundary sphere of  $A^n(\mu)$  a cylinder  $C(\sinh^{-1}(t_0))$ . Properties:

i) 
$$\# \{ \text{ ends of } \mathbb{M}^{n}(\mu) \} = 2 \cdot \frac{\mathbb{M}^{n+1} - 1}{\mathbb{N} - 1}$$

$$\beta_{n-1}(\mathbb{M}^{n}(\mu)) = \# \{ \text{ ends of } \mathbb{M}^{n}(\mu) \} - 1$$

$$\geq 2 \cdot \mathbb{M}^{n} \geq ((\frac{1}{2} \cdot r_{0})^{n} - 1)^{n}$$

ii) the sectional curvatures of  $M^{n}(\mu)$  at any point p are bounded from below by  $-\lambda_{(\mu)}(d(p,o))$ , where  $\lambda_{(\mu)}$  is the characteristic function of the interval  $[0,d_{\mu}]$ , and  $d_{\mu}$  is given by:

$$\begin{array}{rcl} d_{\mu} & := & \# \cdot \sinh^{-1}(t_{o}) + \mu \cdot (\frac{\pi}{2} \cdot r_{o} \cdot \coth(t_{o}) + t_{o} \\ & & + & \max\{0, t_{o} - \# \cdot \tanh(\frac{1}{2} \cdot t_{o})\} \end{array}) \end{array}$$

iii) for any integer  $\mu \ge 1$  the following inequalities hold:

$$b_{1}(M^{n}(\mu)) \leq d_{\mu} + \ln(1 + e^{-2}) - \ln(2)$$
  
 $\ln \beta_{n-1}(M^{n}(\mu)) \geq \mu \cdot (n \cdot \ln(\frac{r_{0}}{2}) + \ln(1 - (\frac{r_{0}}{2})^{-n})$ 

Specializing to the case  $r_0 = 7$  and  $t_0 = 2.5$ , we obtain:

$$\ln \beta_{n-1}(M^{n}(\mu)) = 1.2 \cdot n \cdot \mu = \frac{1}{12} \cdot n \cdot b_{1}(M^{n}(\mu))$$

Notice that we still have the freedom to pick  $\mu$  large. Therefore, when working in terms of the invariant  $b_1(M^n)$  and the dimension, any estimate on the number of ends or on the n-1<sup>st</sup> Betti number has to grow at least exponentially in  $n \cdot b_1(M^n)$ . Such a result has been acchieved in Theorem B.

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# LOWER CURVATURE BOUNDS, TOPONOGOV'S THEOREM, AND BOUNDED TOPOLOGY II

An upper bound on the Betti numbers of asymptotically non-negatively curved manifolds

#### Introduction

In this paper we continue studying asymptotically non-negatively curved manifolds. Our goal is to estimate their Betti numbers from above in terms of curvature decay and dimension. In special cases bounds of this type are due to Gromov [G]; he deals with non-negatively curved manifolds and with compact manifolds. Related is also the work of Berard and Gallot [BG] who have applied heat equation methods in order to get bounds for all topological invariants of compact manifolds.

We recall that a complete Riemannian manifold  $(M^n,g)$  with base point o is said to be asymptotically non-negatively curved, iff there exists a monotone function  $\lambda: [0,\infty) \longrightarrow [0,\infty)$  such that

i) 
$$b_0(\lambda) := \int_0^{\infty} r \cdot \lambda(r) dr < \infty$$

and ii) the sectional curvatures at  $p \ge -\lambda(d(o,p))$  for all  $p \in M^n$ . A detailed exposition of the analytical impact of the convergence of the integral  $b_0(\lambda)$  has been given in chapter II of part one; for instance there exists a unique solution of the Riccati equation  $u' = u^2 - \lambda$  with the property that  $u(r) \to 0$  for  $r \to \infty$ . This gives rise to another numerical invariant

$$b_1(\lambda) := \int_0^\infty u(r) dr$$

Both  $b_0$  and  $b_1$  depend on  $\lambda$  in a monotone way, and they can be regarded as invariants of the manifold  $M^n$  by taking the minimal monotone function  $\lambda$  which obeys the conditions (i) and (ii).

In principle  $b_0$  and  $b_1$  can be regarded as equivalent invariants:  $b_1 \leq b_0 \leq \exp(b_1) - 1$ . However,  $b_1$  is better adapted to our problem. A natural family of weighted  $L^1$ -norms on the Betti numbers of a space X are induced by the Poincaré series

$$P_t(X) := \sum_i t^i \cdot \beta_i(X)$$

#### Main Theorem:

For any asymptotically non-negatively curved manifold  $(M^n,8,0)$  the Betti numbers with respect to an arbitrary coefficient field can be bounded universally in terms of the dimension and the invariant  $b_1$ :

$$P_{t(n)^{-1}}(M^{n}) \leq C(n) \cdot \exp(\frac{15n-13}{4} \cdot b_{1}(M^{n}))$$
where
$$C(n) := \exp(5 \cdot n^{3} + 8 \cdot n^{2} + 5 \cdot n + 2)$$

and 
$$t(n) := 5^{n^2} \cdot 8^n \cdot \exp(\frac{9}{4} \cdot \frac{1}{n+1})$$

Moreover these manifolds have finitely many ends and the Betti numbers at infinity are bounded as follows:

$$\sum_{\text{ends } E} P_{t(n)^{-1}}(E) \leq C(n) \cdot \exp((n-1) \cdot b_{1}(M^{n}))$$

#### Remarks:

- i) By the examples given in chapter IV of part one it is reasonable that the bounds in both the estimates grow exponentially in  $n \cdot b_1(M^n)$ . However there is no geometric reason known so far, why the constants C(n) and  $t(n)^n$  should grow exponentially in  $n^3$ .
- ii) Notice that:

$$\frac{\text{H}}{\text{ends of }M^n}\} \leq \sum_{\text{ends}} P_1(E) \leq t(n)^{n-1} \cdot \sum_{\text{ends}} P_{t(n)^{-1}}(E)$$

Thus we have recovered a weaker version of Theorem III.3 in part one.

iii) Using the long exact homology sequence, one obtains an estimate on
the relative Betti numbers:

$$P_{t(n)^{-1}}(M^n, \bigcup_{\text{ends}} E) \leq (1+t(n)) \cdot C(n) \cdot \exp(\frac{15n-13}{4} \cdot b_1(M^n))$$

iv) Because of Poincaré duality the inequality

$$\sum_{i} \beta_{i}(M^{n}) \leq \tilde{C}(n) \cdot \exp(\frac{15n-13}{4} \cdot b_{1}(M^{n}))$$
holds with 
$$\tilde{C}(n) := 3 \cdot t(n)^{(n+1)/2} \cdot C(n)$$

$$\leq \exp(6 \cdot n^{3} + 10 \cdot n^{2} + 6 \cdot n + 3)$$

#### Special Cases:

a) Mn has non-negative sectional curvature:

$$P_{t(n)^{-1}}(M^n) \leq C(n)$$

b) the sectional curvatures of M<sup>n</sup> are bounded from below by -k<sup>2</sup> and even more are non-negative outside a ball with radius d around the base point o : (i.e.: M<sup>n</sup> compact with diametre d)

$$P_{t(n)=1}(H^n)$$
 4  $C(n) \cdot \exp(\frac{15n-13}{4} \cdot k \cdot d)$ 

### Method of Proof:

We use a modification of Gromov's direct geometric proof. The basic idea is to combine Morse theory arguments on the distance function and covering arguments. In a first step we do things locally and derive an estimate for small balls (sections 1-3). In a second step we reduce the theorem to these local bounds (sections 4 and 5).

In principal the local result is already contained in Gromov's paper (c.f. [G]); however, we shall rearrange the details in a more subtle way. Therefore our constants grow only exponentially in  $n^3$ ; they do not depend doubly exponentially on n. The key to this improvement is a non-standard packing lemma (c.f. Appendix A).

The way in which we put together the local estmates is essentially new. We use metrical annuli as intermediate objects when extending the estimate from small balls to all of the manifold  ${\tt M}^n$ .

# 1. A Topological Lemma:

In this section we are going to do the topological part of the argument. There are two reasons for avoiding the Betti numbers in the intermediate steps in the proof:

- a) Given a point  $p \in M^n$  and any number N > 0, it is easy to put a bumpy on  $M^n$  such that  $\dim H_1(B(p,1)) \ge N$ . The idea is to produce a sufficiently complicated intersection of the distance sphere  $S(p,1) \in M^n$  with the cut-locus of p.
- b) For arbitrary subsets  $X_1$ ,  $X_2 \subset M^n$  it is impossible to estimate the dimension of  $H_{\#}(X_1 \vee X_2)$  in terms of dim  $H_{\#}(X_1)$  and dim  $H_{\#}(X_2)$  only. Some pieces of information about  $X_1 \wedge X_2$  are required in addition. These obstructions towards an "obvious proof" are related, and they both can be circumvented looking at topological pairs (Y,X) where  $X < Y < M^n$  are open subsets. We consider the numbers

$$\frac{1.1}{\operatorname{rk}_{i}^{t}(Y,X)} := \operatorname{rk} (H_{i}(X) \longrightarrow H_{i}(Y))$$

$$\operatorname{rk}_{i}^{t}(Y,X) := \int_{i \ni 0} t^{i} \operatorname{rk}_{i}(Y,X)$$

It is worthwhile noticing that under the hypothesis above the numbers  $rk_i(Y,X)$  vanish for i > n.

1.2 We consider open subsets  $B_j^0 \subset B_j^1 \subset ... \subseteq B_j^{n+1}$ ,  $1 \le j \le N$ , such that

$$x \in \bigvee_{j=1, B_j^0}^{N} B_j^0$$

and

$$Y > \bigvee_{j=1}^{N} B_j^{n+1}$$

#### Lemma:

Let t>0 and suppose that any  $B_j^n$  intersects at most t distinct sets  $B_{j}^n$ ,  $j' \neq j$ ; then there holds the following inequality:

$$rk_{*}^{t-1}(Y,X) \leq rk_{*}^{t-1}(\bigcup_{j=1}^{N} B_{j}^{n+1}, \bigcup_{j=1}^{N} B_{j}^{o})$$

$$\leq (e-1)\cdot N \cdot \sup\{rk_{*}^{t-1}(B_{j_{o}}^{\sigma+1} \dots \cap B_{j_{n-\sigma}}^{\sigma+1}, B_{j_{o}}^{\sigma} \dots \cap B_{j_{n-\sigma}}^{\sigma}) \mid$$

$$0 \leq \sigma \leq n, 1 \leq j_{o} \leq \dots \leq j_{n-\sigma} \leq N \}.$$

Essentially this lemma is already contained in Gromov's paper (c.f. [G]). For the sake of completeness we include an elementary Proof:

Consider open subsets  $X_1 \subset X_2 \subset X_3$  and  $Y_1 \subset Y_2 \subset Y_3$  in  $M^n$ . The Mayer-Vietoris sequence gives raise to a commutative diagrame with exact rows:

$$\begin{array}{c} \longrightarrow_{H_{\mu}(X_{1})} \bullet_{H_{\mu}(Y_{1})} \longrightarrow_{H_{\mu}(X_{1} \circ Y_{1})} \longrightarrow_{\mu-1} (X_{1} \cap Y_{1}) \longrightarrow_{\mu-1} (X_{1} \cap Y_{1}) \longrightarrow_{\mu} (X_{2} \circ Y_{1}) \longrightarrow_{\mu} (X_{2} \circ Y_{2}) \longrightarrow_{\mu-1} (X_{2} \cap Y_{2}) \longrightarrow_{\mu-1} (X_{2} \cap Y_{2}) \longrightarrow_{\mu} (X_{3} \circ Y_{3}) \longrightarrow_{\mu} (X_{3} \circ Y_{3}) \longrightarrow_{\mu-1} (X_{3} \cap Y_{3}) \longrightarrow_{\mu} (X_{3} \circ Y_{3}) \longrightarrow_{\mu} (X_{3$$

All the vertical homomorphisms are induced by inclusions. The standard diagrame chasing technique shows that:

1.3 
$$rk(j_{\mu} \cdot i_{\mu}) \leq rk(j_{\mu,X} \bullet j_{\mu,Y}) + rk(i_{\mu-1})$$

or in different terminology:

$$\begin{split} \operatorname{rk}_{\mu}(X_{3} & \vee Y_{3}, X_{1} & \vee Y_{1}) \\ &= \operatorname{rk}_{\mu}(X_{3}, X_{2}) + \operatorname{rk}_{\mu}(Y_{3}, Y_{2}) + \operatorname{rk}_{\mu-1}(X_{2} & \wedge Y_{2}, X_{1} & \wedge Y_{1}) \end{split}$$

We apply this formula inductively to the family  $B_j^i$  and obtain:

1.4 
$$\operatorname{rk}_{i}(\bigcup_{j=1}^{N} B_{j}^{i+1+\nu}, \bigcup_{j=1}^{N} B_{j}^{\nu})$$

$$4 \sum_{\mu=0}^{i} \sum_{j_{0} < ... < j_{i-\mu}} rk_{\mu} \left( B_{j_{0}}^{\mu+\nu+1} a ... a B_{j_{i-\mu}}^{\mu+\nu+1}, B_{j_{0}}^{\mu+\nu} a ... a B_{j_{i-\mu}}^{\mu+\nu} \right) ;$$

here  $\nu$  denotes some non-negative integer which does not exceed n-i . We specialize to the case  $\nu$  = n-i and compute:

$$rk_{\bullet}^{t^{-1}}(\bigcup_{j=1}^{N} B_{j}^{n+1}, \bigcup_{j=1}^{N} B_{j}^{o})$$

$$4 \sum_{i=0}^{n} t^{-i} \cdot rk_{i}(\bigcup_{j=1}^{N} B_{j}^{n+1}, \bigcup_{j=1}^{N} B_{j}^{n-i})$$

$$4 \sum_{\nu=0}^{n} \sum_{\sigma=\nu}^{n} \sum_{j_{0} < \dots < j_{n-\sigma}} t^{\nu-n} \cdot rk_{\sigma-\nu}(B_{j_{0}}^{\sigma+1} \dots \wedge B_{j_{n-\sigma}}^{\sigma+1}, B_{j_{0}}^{\sigma} \dots \wedge B_{j_{n}}^{\sigma})$$

$$= \sum_{\sigma=0}^{n} \sum_{j_{0} < \dots < j_{n-\sigma}} t^{\sigma-n} \cdot \sum_{\nu=0}^{\sigma} t^{\nu-\sigma} \cdot rk_{\sigma-\nu} (\dots, \dots) ,$$

hence:
$$rk_{*}^{t-1}(\bigvee_{j=1}^{N}B_{j}^{n+1},\bigvee_{i=1}^{N}B_{j}^{o})$$

1.5
$$\stackrel{j=1}{\leftarrow} \sum_{\sigma=0}^{j=1} \sum_{j_0 < \dots < j_{n-\sigma}} t^{\nu-n} \cdot rk_*^{\tau-1} (B_{j_0}^{\sigma+1} \land \dots \land B_{j_{n-\sigma}}^{\sigma+1}, B_{j_0}^{\sigma} \land \dots \land B_{j_{n-\sigma}}^{\sigma}) .$$

To complete the proof, we point out that the number of non-empty intersections

$$B_{j_0}^{\sigma} \cap \dots \cap B_{j_{n-\sigma}}^{\sigma}$$

does not exceed

$$\frac{\mathbb{N}}{n-\sigma+1} \cdot \binom{t}{n-\sigma} , \quad 0 \le \sigma \le n$$

therefore the number of non-vanishing terms on the right-hand side of 1.5 is bounded from above by

$$\sum_{\sigma=0}^{n} \frac{N}{n-\sigma+1} \cdot {t \choose n-\sigma} \cdot t^{\sigma-n} \leq N \cdot \sum_{\sigma=0}^{n} \frac{1}{(n-\sigma+1)!} \leq N \cdot (e-1) .$$

In most of our applications the sets  $B_j^i$  will be open metrical balls. We shall use the notation  $\rho \cdot B(p,r) := B(p,\rho \cdot r)$ . It is convenient to draw the following

## 1.6 Corollary:

Let  $\rho > 1$ ,  $t \ge 1$  and suppose that:

i) X  $M^{n}$  is covered by open metrical balls  $B_{j}^{o}$ ,  $1 \leq j \leq N$ ,

ii) i < n and  $B_j^i \cap B_j^i \neq \emptyset \longrightarrow \rho \cdot B_j^i \subset B_j^{i+1}$ 

iii)  $\rho \cdot B_j^n \subset B_j^{n+1} \subset Y$  ,  $1 \leq j \leq N$  , and

iv) each ball  $B_j^n$  intersects at most to ther balls  $B_{ij}^n$ .

Then the following estimate holds:

$$rk_{*}^{t-1}(Y,X) \le rk_{*}^{t-1}(\bigcup_{j=1}^{N} B_{j}^{n+1}, \bigcup_{j=1}^{N} B_{j}^{0})$$

$$\le (e-1)\cdot N \cdot \sup \{ rk_{*}^{t-1}(\rho \cdot B_{j}^{i}, B_{j}^{i}) \mid 0 \le i \le n, 1 \le j \le N \}$$

## Remark:

Condition (ii) is obviously met , if all the balls  $B_j^o$  have equal radii and if  $B_j^i=(2+\rho)^i\cdot B_j^o$  ,  $0\le i\le n$  ,  $1\le j\le N$  .

## 2. The Morse Theory of the Distance Function

Any point  $p \in M$  gives raise to a function  $d_p : M \longrightarrow \mathbb{R}$  defined by  $d_p(\tilde{p}) := d(p, \tilde{p})$ .  $\tilde{p} \in M$  is called a critical point of  $d_p$ , iff for any  $v \in T_{\tilde{p}}M$  there is a minimizing geodesic segment  $\gamma$  which joins  $\tilde{p} = \gamma(0)$  to p, and which obeys  $\langle v, \gamma'(0) \rangle \geq 0$ .  $\mathfrak{I}_p := \{ \text{critical points of } d_p \}$  is said to be the singular set of  $d_p$ . Notice that  $\tilde{p}$  is non-critical for  $d_p$ , iff the initial vectors of all minimizing geodesics joining  $\tilde{p}$  to p lie in an open half-space of  $T_{\tilde{p}}M$ . Hence for any non-critical point  $\tilde{p}$ , there is an open neighborhood U and a continuous non-vanishing vector fiel  $v_U$  which is defined on U and has an acute angle with the initial vector of any minimizing geodesic joining a point in U to p. As  $\mathfrak{I}_p$  is closed one can reason in the standard way and obtain:

#### 2.1 Lemma:

For any  $p \in M$  there exists a smooth vector field  $v_p: M \longrightarrow TM$  , which obeys  $\langle v_p|_{\gamma(0)}$  ,  $\gamma'(0) \rangle > 0$  for all minimizing geodesics  $\gamma$  which join some point  $\gamma(0) \in M \cap S_p$  to p .

We shall use the vector field  $\mathbf{v}_p$  in order to construct retraction maps; we point out that  $\mathbf{d}_p$  is monotone decreasing along the integral curv of  $\mathbf{v}_p$ . Under some suitable hypothesis this tool even gives raise to isotopies rather than homotopy equivalences. (c.f. [G], [GS].)

In order to establish a Morse theory on  $d_p$ , it is moreover necessa to determine how the topology of M changes at the critical points of  $d_p$  and to count the strata of the singular set  $\mathcal{S}_p$  in a reasonable manner. A  $d_p$  is not differentiable at the cut-locus of p, both these problems canno be tackled in the usual way.

2.2 However, it is possible to bound in some sense the number of critica points of  $d_p$ : let L>1; we consider  $p_1, \dots, p_k \in M$  such that

i) 
$$d_p(p_{i-1}) \ge L \cdot d_p(p_i)$$

and ii) p<sub>i</sub> is critical for d<sub>p</sub> , 2≤i≤k

Such a sequence  $(p_i)_{i=1}^k$  will be called a metrical  $(k;L_1,L,L_k)$  - frame of p provided  $L_1$  and  $L_k$  are positive real numbers which satisfy  $\ell_1:=d_p(p_1)^2$  and  $\ell_k:=d_p(p_k)^2L_k$ . We shall say that a subset X < M is  $(k;L_1,L,L_k)$ -frame iff for each  $p \in X$  there exists a metrical  $(k;L_1,L,L_k)$ -frame.

# 2.3 <u>Lemma</u>:

i) In a manifold  $(M^n,g,o)$  which has asymptotically non-negative curvature any metrical  $(k;L_1,L,L_k)$  - frame of the base point o obeys:

$$k \le 2 \cdot \pi^{n-1} \cdot (\frac{L}{L-1})^{2n-2} \cdot \exp((2n-2) \cdot b_1)$$

ii) Let p be any point in an arbitrary Piemannian manifold, and suppose that the sectional curvatures in the ball  $B(p, (1+L^{-1}) \cdot L_1)$  are bounded from below by  $-n^2$ ,  $n \ge 0$ . If moreover

$$3 \cdot (1 + \sqrt{2})^{n-1} \cdot \eta \cdot L_1 \cdot \coth(\eta \cdot L_1)$$
 4 L

then  $k \leq 2 n$  holds for any metrical  $(k; L_1, L, L_k)$  - frame of p.

#### Remark:

The lemma relates the parameter k to the dimension n of  $M^n$ , and thus it justifies the terminology, although the word "frame" might be a little misleading. In a similar context Gromov heuristically speaks of the "number of essential directions in  $M^n$ ".

## Proof:

We fix minimizing geodesics  $\gamma_i$  which join p with  $p_i$ ; their initial vectors in  $T_pM$  will be denoted by  $v_i$ . We head towards a lower bound on the angle between any two of these vectors and then make use of some packing arguements: let  $1 \le i < j \le k$  and study the geodesic triangle  $\Delta = (p_i, p, p_j)$  with edges  $\gamma_i$ ,  $\gamma_j$ , and a minimizing geodesic  $\gamma_{ij}$ . We observe that  $p_j$  is critical for  $d_p$ , and thus  $\gamma_j$  can be replaced by another minmizing geodesic  $\tilde{\gamma}_j$  such that the angle at  $p_j$  in the modified triangle  $\tilde{\Delta}$  does not exceed  $\frac{\pi}{2}$ . The data on  $\Delta$  and  $\tilde{\Delta}$  are turned into inequalities by means of the (generalized) Toponogov theorem. We start with  $\tilde{\Delta}$ :

i) Proposition III.1ii applies with  $\varepsilon = \frac{L-1}{L}$ , and in the limit  $a \longrightarrow 1$  it yields:

 $d_p(p_i) = d(p_i, p_i) + d_p(p_i) \cdot \sqrt{1 - (\frac{L-1}{L})^2 \cdot \exp(-2 \cdot b_i)}$ 

ii) Obviously a minimizing geodesic which joins  $p_i$  to any point on  $\gamma_j$  is not longer than  $d_p(p_i) + d_p(p_j)$ , and therefore it is contained in the ball  $B(p_i, d_p(p_i)) + d_p(p_j) < B(p_i, (1+L^{-1})\cdot L_1)$ . Hence the hyperbolic plane with curvature  $-\eta^2$  is an admissible model. We deform the Alexandrov

triangle such that  $\bar{l}_i \ge d_p(p_i)$ ,  $\bar{l}_j = d_p(p_j)$ ,  $\bar{l} = d(p_i, p_j)$ , and  $\bigstar$  at  $\bar{p}_j = \frac{\pi}{2}$ ; then the Law of Cosines yields:

$$\cosh \eta \cdot \overline{\mathbf{i}} = \frac{\cosh \eta \cdot \overline{\mathbf{i}}_{\mathbf{i}}}{\cosh \eta \cdot \mathbf{d}_{\mathbf{p}}(\mathbf{p}_{\mathbf{i}})} \stackrel{\cosh \eta \cdot \mathbf{d}_{\mathbf{p}}(\mathbf{p}_{\mathbf{i}})}{\cosh \eta \cdot \mathbf{d}_{\mathbf{p}}(\mathbf{p}_{\mathbf{j}})}$$

Using the above estimates we can treat the triangle  $\Delta$  in a similar way: i) Reversing the implication in Proposition III.1i, we obtain:

$$\cos \frac{1}{2}(v_i, v_j) < \sqrt{1 - (\frac{L-1}{L})^4 \cdot \exp(-4 \cdot b_{\lambda})}$$
or: 
$$|\frac{1}{2}(v_i, v_j)| \ge |\sin \frac{1}{2}(v_i, v_j)| > (\frac{L-1}{L})^2 \cdot \exp(-2 \cdot b_{\lambda})$$

In this case the claim immediately follows from the standard packing estimate, which has been stated in Lemma III.3.1 for instance.

ii) Here we apply the Law of Cosines directly to the Alexandrov triangle:  $\bar{\ell}_i = d_p(p_i)$ ,  $\bar{\ell}_j = d_p(p_j)$ ,  $\bar{\ell} = d(p_i, p_j)$ , and A at  $\bar{p} \leq A$  at  $p = A(v_i, v_j)$  we obtain the inequality:

$$\cos \langle \langle \mathbf{v}_{i}, \mathbf{v}_{j} \rangle \rangle \leq \eta^{2} \cdot \frac{\cosh(\eta \cdot \overline{\ell}_{i}) \cdot \cosh(\eta \cdot \overline{\ell}_{j}) - \cosh(\eta \cdot \overline{\ell})}{\sinh(\eta \cdot \overline{\ell}_{i}) \cdot \sinh(\eta \cdot \overline{\ell}_{j})}$$

$$\leq \frac{\eta^{2} \cdot \coth(\eta \cdot \overline{\ell}_{i})}{\sinh(\eta \cdot \overline{\ell}_{j})} \cdot \left(\coth(\eta \cdot \overline{\ell}_{j}) - \frac{1}{\coth(\eta \cdot \overline{\ell}_{i})}\right)$$

$$= \coth(\eta \cdot \overline{\ell}_{i}) \cdot \tanh(\eta \cdot \overline{\ell}_{j})$$

$$\leq \frac{\bar{\ell}_{i}}{\bar{\ell}_{i}} \cdot \eta \cdot \bar{\ell}_{i} \cdot \coth(\eta \cdot \bar{\ell}_{i})$$

hence:  $\cos \langle (v_i, v_i) \rangle = L^{-1} \cdot \eta \cdot L_1 \cdot \coth(\eta \cdot L_1)$ 

By assumption the packing arguement given in appendix A applies.

# 3. Morse Theory and Coverings

We have no idea how to control in which way the topology of  $M^{n}$  changes at the critical strata of  $d_p$ ; thus the gluing arguements have to be eliminated from the Morse theory. We are going to use covering arguements along the lines of section 1 instead. The idea of deformation will be applied to reduce to special covering situations which we know quite a lot about. For this purpose we introduce some more language:

# 3.1 Definition:

Given  $\rho > 1$ ; a ball B = B(p,r) in  $M^n$  is said to be  $\rho$ -compressible to  $\tilde{B} = B(\tilde{p},\tilde{r})$ , if and only if:

$$i) \quad \tilde{\mathbf{r}} \leq (1 - \rho^{-1}) \cdot \mathbf{r}$$

and iii)  $\tilde{B}$  is a deformation retract of some subset  $X \subset \rho \cdot B$ , which also contains B.

B is called p-incompressible, iff there does not exist a ball  $\tilde{B}$  as above.

The injectivity radius is a continuous positive function on  $M^n$ , which has a positive lower bound  $r_0$  on  $\rho \cdot B$ .  $\rho$ -Compressing the given ball B repeatedly, one will therefore arrive at a  $\rho$ -incompressible ball or at a topological ball within finitely many steps. Thus it is natural to try and reduce to incompressible balls, when bounding the invariant  $rk_{\perp}^{t-1}(\rho \cdot B, B)$ .

#### 3.2 Lemma:

If 
$$t>0$$
, and if the ball B is  $\rho$ -compressible to  $\widetilde{B}$ , then: 
$$rk_*^{t-1}(\rho \cdot B, B) \leq rk_*^{t-1}(\rho \cdot \widetilde{B}, \widetilde{B})$$

# Proof:

The claim is an immediate consequence of the following commutative diagrame, where the graded maps are induced by inclusion:

$$H_{\bullet}(\widetilde{B}) \xrightarrow{\text{deformation}} H_{\bullet}(X) \longleftarrow H_{\bullet}(B)$$

$$\downarrow \text{deformation}$$

$$retract \qquad \downarrow$$

$$H_{\bullet}(\rho \cdot \widetilde{B}) \longrightarrow H_{\bullet}(\rho \cdot B)$$

Moreover incompressible balls allow for some statements about the critical points of several distance functions.

#### 3.3 Lemma:

If B=B(p,r) is p-incompressible, then for any  $\tilde{p}\in\frac{p-1}{2}\cdot B$  there is a critical point  $p_c$  of  $d_{\tilde{p}}$  such that:

$$\min \{ (1-\rho^{-1}) \cdot r, r-\rho^{-1} \cdot d(p,\tilde{p}) \} \le d(\tilde{p},p_c) \le r+d(p,\tilde{p}) \le \frac{1+\rho}{2} \cdot r$$

#### Proof:

Conversely, let us assume that there is no critical point  $p_c$  of  $d_{\tilde{p}}$  which obeys the above inequalities. We put:

$$\tilde{\mathbf{r}} := \min \{ (1-\rho^{-1}) \cdot \mathbf{r}, \mathbf{r} - \rho^{-1} \cdot \mathbf{d}(\mathbf{p}, \tilde{\mathbf{p}}) \}$$

and consider the balls  $\tilde{B} := B(\tilde{p},\tilde{r})$  and  $X := B(\tilde{p},r+d(p,\tilde{p}))$ . We point out that  $r+2 \cdot d(p,\tilde{p}) \neq \rho \cdot r$ , hence  $B \vee \tilde{B} \leq X \leq B(p,r+2 \cdot d(p,\tilde{p})) \leq \rho \cdot B$  and  $\rho \cdot \tilde{B} \leq \rho \cdot B$ . Lemma 2.1 gives raise to a vector field  $v_{\tilde{p}}$  which does not vanish on the closed annulus  $X \setminus \tilde{B}$ . As  $d_{\tilde{p}}$  is monotone decreasing along the integral curves of  $v_{\tilde{p}}$ , we obtain a retraction map, and in contrast to the hypothesis B turns out to be  $\rho$ -compressible to  $\tilde{B}$ .

We proceed and consider the covering situation in some more detail.

3.4 Assumptions:

Let  $\xi$ ,  $\tilde{\xi}$ , L, and L, be some positive real numbers; define functions  $\rho$ , q, t, and N, by

$$\rho := 3 + 2 \cdot L^{-1}$$

$$q := (2 + 3 \cdot L)^{-1}$$

$$t_{o} := \left(\frac{2L}{\tilde{\xi} \cdot L_{1}} \cdot \sinh \frac{\tilde{\xi} \cdot L_{1}}{2L}\right)^{n-1} \cdot \left(1 + 8 \cdot \left(5 + \frac{2}{L}\right)^{n}\right)^{n}$$
and  $N_{o} := \left(\frac{L}{\tilde{\xi} \cdot L_{1}} \cdot \sinh \frac{\tilde{\xi} \cdot L_{1}}{L}\right)^{n-1} \cdot \left(1 + 4 \cdot \left(2 + 3L\right) \cdot \left(5 + \frac{2}{L}\right)^{n}\right)^{n}$ 

We suppose that:

- i) the ball  $\rho \cdot B$  associated to B = B(p,r) is  $(k;L_1,L,(l+2L)\cdot r)$ -framed.
- ii) the curvatures in  $\rho \cdot B$  are bounded from below by  $-\tilde{\xi}^2$  .
- iii) the curvatures in  $B(p, (1+L^{-1})\cdot L_1)$  are bounded from below by  $-\xi^2$ .

Furthermore it is useful to introduce the notation:

$$cont_*^{t-1}(L_1, L, \tilde{\xi}) := \sup\{rk_*^{t-1}(\rho \cdot B, B) \mid \text{the ball } B \text{ meets the conditions } 3.4i \text{ and } 3.4ii \}$$

# 3.5 Lemma:

i) Suppose that the assumptions 3.4 hold; then for any  $t \ge t_0$  there is the estimate:

$$\operatorname{rk}_{*}^{t-1}(\rho \circ B, B) \leq (e-1) \circ N_{O} \circ \sup \{\operatorname{rk}_{*}^{t-1}(\rho \circ \widetilde{B}, \widetilde{B}) \mid \widetilde{B} = B(\widetilde{p}, \widetilde{r}) \text{ where}$$

$$\widetilde{r} \leq q \circ r \text{ and } \widetilde{p} \text{ lies in } B \}$$

ii) If moreover B is  $\rho$ -incompressible, then all the balls  $\rho \cdot \tilde{B}$  on the right-hand side of the above estimate are  $(k+1; L_1, L, (1+2L) \cdot q \cdot r)$ -framed.

iii) If 
$$t = t_o(L_1, L, \tilde{\xi})$$
, then:

$$cont_{k}^{t-1}(L_{1}, L, \tilde{\xi}) \leq max\{1, (e-1) \cdot N_{0} \cdot cont_{k+1}^{t-1}(L_{1}, L, \tilde{\xi})\}$$

iv) If condition 3.4iii holds and if  $L \ge \sqrt{1+\xi^2 \cdot L_1^2} \cdot 3 \cdot (1+\sqrt{2})^{n-1}$  then:  $\cot \frac{t^{-1}}{2}(L_1, L, \tilde{\xi}) = 1$ 

#### Proof:

i) We put  $\rho_i := (2+\rho)^i$  for  $0 \le i \le n$  and  $\rho_{n+1} := \rho \cdot \rho_n$ . We pick a maximal set of pairwise disjoint metrical balls  $B_j^{-1}$ ,  $1 \le j \le N$ , whose centres lie in B and whose radii equal  $r_{-1} := 0.5 \cdot q \cdot \rho_n^{-1} \cdot r$ . Obviously for  $0 \le i \le n$  the families  $B_j^i := 2 \cdot \rho_i \cdot B_j^{-1}$ ,  $1 \le j \le N$ , cover B. Since  $1+q \cdot \rho = 1+L^{-1} < \rho$ , we conclude that the balls  $B_j^{n+1}$  are contained in  $\rho \cdot B$ . Therefore the estimate is a consequence of corollary 1.6, provided that a)  $N_0 \ge N$  and that b) to bounds from above the number of balls  $B_j^{n+1}$ , which intersect any fixed  $B_j^n$ . In order to verify both the conditions, we point out that the  $B_j^{-1}$  are disjoint, and that:

a) 
$$B_{j}^{-1} < (1 + \frac{q}{2 \cdot \rho_{n}}) \cdot B < (1 + 4 \cdot \rho_{n} \cdot q^{-1}) \cdot B_{j}^{-1} < (3 + \frac{q}{2 \cdot \rho_{n}}) \cdot B$$

b) 
$$B_{\mathbf{j}'}^{\mathbf{n}} \wedge B_{\mathbf{j}}^{\mathbf{n}} \neq \emptyset \longrightarrow B_{\mathbf{j}'}^{-1} < (2 + \frac{1}{2 \cdot \rho_{\mathbf{n}}}) \cdot B_{\mathbf{j}}^{\mathbf{n}} < (4 + \frac{1}{2 \cdot \rho_{\mathbf{n}}}) \cdot B_{\mathbf{j}'}^{\mathbf{n}}$$

$$< (1 + 4 \cdot \mathbf{q} + \frac{\mathbf{q}}{2 \cdot \rho_{\mathbf{n}}}) \cdot B$$

These inclusions yield:

a) 
$$N \leq \sup_{j} \frac{\text{vol } (1+0.5 \cdot q \cdot \rho_{n}^{-1}) \cdot B}{\text{vol } B_{j}^{-1}} \leq \sup_{j} \frac{\text{vol } (1+4 \cdot \rho_{n} \cdot q^{-1}) \cdot B_{j}^{-1}}{\text{vol } B_{j}^{-1}}$$

b) 
$$\# \{B_{j'}^n | B_{j'}^n \land B_{j}^n \neq \emptyset\} \leq \sup_{j'} \frac{\text{vol } (1 + 8 \cdot \rho_n) \cdot B_{j'}^{-1}}{\text{vol } B_{j'}^{-1}}$$

Since all the balls are contained in  $\rho \cdot B$ , the right-hand sides of these inequalities can be evaluated by means of. the volume comparison theorem for concentric metrical balls (c.f. [BC]); we may use model spaces with constant curvature  $-\tilde{\xi}^2$ , and we compute:

a) 
$$N \leq \frac{1+4\rho_{n}/q}{\int_{0}^{1} \sinh{(\tilde{\xi} \cdot \sigma \cdot r_{-1})^{n-1} d\sigma}}$$

$$\leq (1+\frac{4}{q} \cdot \rho_{n}) \cdot \sup{\{\frac{\sinh{\tilde{\xi} \cdot \sigma \cdot (1+\frac{4}{q} \cdot \rho_{n}) \cdot r_{-1}}{\sinh{\tilde{\xi} \cdot \sigma \cdot r_{-1}}} \mid 0 \leq \sigma \leq 1\}}$$

$$\leq (1+\frac{4}{q} \cdot \rho_{n})^{n} \cdot (\frac{\sinh{\tilde{\xi} \cdot (1+\frac{4}{q} \cdot \rho_{n}) \cdot r_{-1}}}{\tilde{\xi} \cdot (1+\frac{4}{q} \cdot \rho_{n}) \cdot r_{-1}})^{n-1} \leq N_{0}$$

The last step is due to the fact that:

$$(1 + \frac{4}{q} \circ \rho_{n}) \circ r_{-1} = (2 + \frac{q}{2 \circ \rho_{n}}) \circ r \leq (2 + L^{-1}) \circ r \leq L_{1}/L$$
and  $\rho_{n} \circ q^{-1} = (2 + 3L) \circ (5 + \frac{2}{L})^{n}$ 

$$\int_{1+8\rho_{n}}^{n} \sinh (\tilde{\xi} \circ \sigma \circ r_{-1})^{n-1} d\sigma$$
b)  $\lim_{n \to \infty} \{B_{j}^{n} \mid B_{j}^{n} \wedge B_{j}^{n} \neq \emptyset\} \leq \frac{1}{2} \int_{0}^{n} \sinh (\tilde{\xi} \circ \sigma \circ r_{-1})^{n-1} d\sigma$ 

$$\leq (1 + 8 \circ \rho_{n})^{n} \circ (\frac{\sinh \tilde{\xi} \circ (1 + 8\rho_{n}) \circ r_{-1}}{\tilde{\xi} \circ (1 + 8\rho_{n}) \circ r_{-1}})^{n-1} \leq 1$$

This time the last estimate is due to the fact that:

$$(1 + 8 \cdot \rho_n) \cdot r_{-1} = (4 + \frac{1}{2 \cdot \rho_n}) \cdot q \cdot r \leq \frac{9}{2} \cdot (2 + 3L)^{-1} \cdot (1 + 2L)^{-1} \cdot L_1$$

$$\leq \frac{L_1}{2 \cdot L}$$

ii) It follows from lemma 3.3 that for any point  $\tilde{p} \ll (1 + q \cdot \rho) \cdot B$  there exists a critical point  $p_c$  of  $d_{\tilde{p}}$ , which obeys:

$$L \cdot d(p_{\mathbf{c}}, \tilde{p}) \leq L \cdot (2 + q \cdot \rho) \cdot r = (1 + 2L) \cdot r$$
and
$$d(p_{\mathbf{c}}, \tilde{p}) \geq (1 - \rho^{-1} \cdot (1 + q \cdot \rho)) \cdot r = q \cdot (\rho \cdot L - L - 1) \cdot r$$

$$= q \cdot (1 + 2L) \cdot r$$

therefore the set  $(1+q \cdot \rho) \cdot B$  as well as the subballs  $\rho \cdot \tilde{B}$  are  $(k+1; L_1, L, (1+2L) \cdot q \cdot r)$  - framed.

- iii) Obviously  $\operatorname{rk}_{*}^{\mathsf{t}^{-1}}(\rho \cdot B, B) = 1$ , if the metrical ball B is a topological ball as well. Therefore lemma 3.2 reduces the proof to the case where B is a  $\rho$ -incompressible ball. The estimate given in (i) holds, and the property (ii) allows to bound the right-hand side as desired.
- iv) Suppose B were a  $\rho$ -incompressible ball which obeyed the conditions 3.4i, ii, and iii) with k=2n; then by means of (ii) there would exist (2n+1; L, , L, 0)-framed balls. As by hypothesis

L 
$$\geq \sqrt{1 + \xi^2 \cdot L_1^2} \cdot 3 \cdot (1 + \sqrt{2})^{n-1}$$
  
 $\geq \xi \cdot L_1 \cdot \coth(\xi \cdot L_1) \cdot 3 \cdot (1 + \sqrt{2})^{n-1}$ 

the above conclusion contradicts to lemma 2.3ii .

# 3.6 Proposition:

Suppose that the ball B=B(p,r) obeys the conditions 3.4ii and iii with  $L>\sqrt{1+\xi^2\cdot L_1^{\,2'}}\cdot 3\cdot (1+\sqrt{2})^{n-1}$  ; moreover assume that the boundary of  $B(p,L_1)$  in  $M^n$  is non-empty and that  $L_1 \cong 2r\cdot (L+2+L^{-1})$  . Then for any  $t \cong t_0(L_1\,,L\,,\tilde{\xi})$  , one has:

$$rk_{m}^{t-1}(\rho \cdot B, B) = (e^{-1})^{2n-1} \cdot N_{0}(L_{1}, L, \tilde{\xi})^{2n-1}$$

# Proof:

We fix a point  $p_1$  on the boundary of  $B(p,L_1)$ ; it is easy to verify that  $\rho \cdot B = (3 + 2 \cdot L^{-1}) \cdot B$  is  $(1; L_1, L, (1+2L) \cdot r)$  - framed. We apply lemma 3.5iii inductively and use 3.5iv in order to stop at k = 2n.

Heuristically speaking, the proposition bounds the topology of small metrical balls B in a Riemannian manifold  $M^{\rm R}$ . All the conditions can be formulated in terms of curvature, the diametre of  $M^{\rm R}$ , and the radius of the ball B. No assumption on the injectivity radius is required.

# 3.7 Corollary: (c.f. Gromov)

If  $M^n$  is non-negatively curved, non-compact, and connected, and if  $t \ge 2^{1/n} \cdot 8^n \cdot 5^{n^2}$ , then for any ball B = B(p,r) in  $M^n$  the following estimate holds:

$$rk_{*}^{t-1}(M^{n}, B) \le rk_{*}^{t-1}(3.3 \cdot B, B) \le exp(5 \cdot n^{3} + 3.5 \cdot n^{2})$$

#### Proof:

We put  $\xi := \tilde{\xi} := 0$ ,  $L := 3 \cdot (1 + \sqrt{2})^{n-1}$ , and  $L_1 := 2r \cdot L \cdot (4 + L^{-1})^2$ . Then the proposition applies; to make things more explicit, we make use of the following computations:

$$t_{o} = (1 + 8.5^{n} \cdot (1 + \frac{2}{5L})^{n})^{n} \le 8^{n} \cdot 5^{n^{2}} \cdot \exp(\frac{2n^{2}}{5 \cdot L} + \frac{n}{8} \cdot 5^{-n})$$

$$\le 2^{1/n} \cdot 8^{n} \cdot 5^{n^{2}}$$

and

$$N_{o} = (1 + 12 \cdot L \cdot 5^{n} \cdot (1 + \frac{2}{5L})^{n} \cdot (1 + \frac{2}{3L}))^{n}$$

$$\leq (12 \cdot L)^{n} \cdot 5^{n^{2}} \cdot \exp(\frac{2n^{2}}{5L} + \frac{2n}{3L} + \frac{n}{12 \cdot L} \cdot 5^{-n})$$

i.e.

$$((e-1) \cdot N_0)^{2n-1} \leq (5 \cdot (1 + \sqrt{2}))^{n^2 \cdot (2n-1)} \cdot (\frac{36 \cdot \sqrt{e-1}}{1 + \sqrt{2}})^{n \cdot (2n-1)} \cdot \exp(\frac{n \cdot (2n-1)}{L} \cdot (\frac{2n}{5} + \frac{2}{3} + \frac{1}{12} \cdot 5^{-n}))$$

$$\leq (5 \cdot (1 + \sqrt{2}))^{(n^2 + 1 \cdot 2 \cdot n) \cdot (2n-1)} \cdot 5$$

$$\leq 5 \cdot \exp(5 \cdot n^3 + 3 \cdot 5 \cdot n^2 - 3 \cdot n)$$

# Metrical Annuli in Asymptotically Non-negatively Curved Manifolds

Most of the preceding results are valid for arbitrary Riemannian manifolds; especially proposition 3.6 holds in general. In this section we are going to specialize to asymptotically non-negatively curved manifolds (Mn, g, o). Our goal is to get rid of the assumption on the diametre of  $M^n$  . Towards this purpose it is natural to consider metrical annuli

$$A(R_1, R_2) := \overline{B(o, R_2)} \setminus B(o, R_1)$$

around the base point o of Mn . We want to bound from above

$$\operatorname{rk}_{*}^{t-1}(A((1-\varepsilon)\cdot R_{1},(1+\varepsilon)\cdot R_{2}),A(R_{1},R_{2}))$$

provided t and & are sufficiently large. The idea is to cover the annuli by balls of a very special type: a metrical ball B = B(p,r) in  $M^n$  is said to be  $\delta$ -small  $(\delta > 0)$ , iff  $r = \delta \cdot d_o(p)$ .

We recall that by lemma II.1.1 the curvatures at a point  $p \in M^n$  are bounded from below by

$$-2 \cdot b_o \cdot f(d_o(p)) \cdot d_o(p)^{-2}$$

here  $r \mapsto f(r)$  denotes a monotone non-increasing error function which takes values in [0,1] and converges to 0 for  $r + \infty$ .

# 4.1 Assumptions:

Let  $L_o := 3 \cdot (1 + \sqrt{2})^{n-1}$  and let  $\eta < (1 + \sqrt{b_o \cdot f(\frac{R_1}{2L_o})})^{-1}$  be some positive number; we put:

L := 
$$L_o \cdot \sqrt{1 + 2 \cdot b_o \cdot f(\frac{R_1}{2L_o}) \cdot (\frac{\eta}{1-\eta})^2}$$
  
 $\rho := 3 + 2 \cdot L^{-1}$   
 $\varepsilon_n := \frac{1}{2} \cdot L^3 \cdot (1 + L)^{-4} \cdot \eta$ 

and

$$\frac{4.2 \text{ Lemma :}}{\lambda} \quad L_0 \quad 4 \quad L \quad 4 \quad \sqrt{3} \cdot L_0 \quad 4 \quad 2 \cdot L_0 - 1$$

$$\epsilon_n \quad 4 \quad \frac{\eta}{2 \cdot (L+4)} \quad 4 \quad \frac{\eta}{22}$$

$$\rho \cdot \epsilon_n \quad 4 \quad \min \left\{ \frac{\eta}{2 \cdot (L+3)}, \frac{\eta}{7} \right\}$$

ii) If  $0 < \delta \le \epsilon_n$  and B = B(p,r) is any  $\delta$ -small ball in  $M^n$  with centre p in  $A(R_1, R_2)$ , then the estimate  $rk_{\perp}^{-1}(\rho \cdot B, B) \leq (e^{-1})^{2n-1} \cdot \tilde{N}_0^{2n-1}$ 

holds for 
$$\tilde{N}_{o} := (12 \cdot L)^{n} \cdot 5^{n^{2}} \cdot \exp(\frac{n}{L} \cdot (\frac{2n}{5} + \frac{2}{3} + \frac{1}{12} \cdot 5^{-n}) + \frac{\sqrt{2} \cdot (n-1)}{L+2})$$
 and for all  $t \ge \tilde{t}_{o}(n) := 8^{n} \cdot 5^{n^{2}} \cdot \exp(\frac{2n^{2}}{5L} + \frac{n-1}{\sqrt{2} \cdot (L+2)} + \frac{n}{8} \cdot 5^{-n})$ 

### Proof:

- i) The estimates are obvious conequences of the definitions.
- ii) We define  $L_1 := 2L \cdot (1+L^{-1})^2 \cdot \epsilon_n \cdot d_0(p) = (\frac{L}{L+1})^2 \cdot \eta \cdot d_0(p)$ . It is easy to verify that:
- a) the curvatures in B(p,(1+L<sup>-1</sup>)·L<sub>1</sub>)  $\subset$  B(p,  $\frac{L \cdot \eta}{L+1} \cdot d_0(p)$ ) are bounded from below by  $-\xi^2$ , where

$$\xi := \sqrt{2 \cdot b_0 \cdot f(\frac{R_1}{L+1})} \cdot (1 - \frac{L \cdot \eta}{L+1})^{-1} \cdot d_0(p)^{-1}$$

i.e.: 
$$L = \sqrt{2 \cdot b_0 \cdot f(\frac{R_1}{L+1})} \cdot \frac{\eta}{1-\eta}$$

c) the curvatures in the ball  $\rho \cdot B \subset B(p, \rho \cdot \varepsilon_n \cdot d_o(p)) \subset B(p, \frac{\eta}{7} \cdot d_o(p))$  are bounded from below by  $-\tilde{\xi}^2$ , where

$$\tilde{\xi} := \sqrt{2 \cdot b_0 \cdot f(\frac{R_1}{L+1})} \cdot (1 - \frac{\eta}{7})^{-1} \cdot d_0(p)^{-1}$$

Therefore proposition 3.6 applies ; it remains to compute  $N_0(L_1,L,\tilde{\xi})$  and  $t_0(L_1,L,\tilde{\xi})$ . Since

$$\frac{2 \cdot (1 + L^{-1})^{2} \cdot \epsilon_{n}}{1 - \frac{\eta}{7}} = \frac{L}{(1 + L)^{2}} \cdot \frac{\eta}{1 - \frac{\eta}{7}} \neq \frac{1}{L + 2} \cdot \frac{\eta}{1 - \eta}$$

we see that:

$$\frac{\tilde{\xi} \cdot L_1}{L} = \frac{1}{L+2} \cdot \frac{\eta}{1-\eta} \cdot \sqrt{2 \cdot b_0 \cdot f(\frac{R_1}{L+1})} \leq \frac{\sqrt{2}}{L+2}$$

Because of the inequality

$$\frac{\sinh(x)}{x} \le \cosh(x) \le \exp(|x|)$$

we obtain that:

$$t_0 \le \exp(\frac{n-1}{\sqrt{2^*(L+2)}}) \cdot (1+8\cdot(5+\frac{2}{L})^n)^n \le \tilde{t}_0(n)$$

and 
$$N_0 \le \exp(\frac{\sqrt{2}(n-1)}{L+2}) \cdot (1+12\cdot L\cdot (1+\frac{2}{3L})\cdot (5+\frac{2}{L})^n)^n \le \tilde{N}_0$$
.

## 4.3 Construction:

and

There is a sequence of numbers  $0 < \epsilon_{-1} < \epsilon_0 < ... < \epsilon_n < \epsilon_{n+1} < 1$ , uniquely determined by the following conditions:

 $\epsilon_n$  is the number given in 4.1,

$$\varepsilon_{n+1} := \rho \cdot \varepsilon_{n}$$

$$\varepsilon_{i+1} = (2 + \rho \cdot (1 + \varepsilon_{i})) \cdot (1 - \varepsilon_{i})^{-1} \cdot \varepsilon_{i}, \quad 0 \le i < n,$$

$$\varepsilon_{0} := 2 \cdot \varepsilon_{-1} \cdot (1 - \varepsilon_{-1})^{-1}$$

$$\varepsilon_{-1} = \varepsilon_{0} \cdot (2 + \varepsilon_{0})^{-1}.$$

We put  $\rho_i := \varepsilon_i \cdot \varepsilon_0^{-1}$  for  $-1 \le i \le n+1$ .

We pick a maximal family of disjoint  $\epsilon_{-1}$ -small balls  $B_j^{-1}$ ,  $1 \le j \le N$ , whose centres  $p_j$  lie in  $A(R_1, R_2)$ . Moreover we shall consider all balls

$$B_j^i := \rho_i \cdot (2+\epsilon_0) \cdot B_j^{-1}$$
,  $1 \le j \le N$ ,  $0 \le i \le n+1$ 

# 4.4 Immediate Consequences:

i) 
$$p \in B_j^i \longrightarrow (1-\epsilon_i) \cdot d_o(p_j) \leq d_o(p) \leq (1+\epsilon_i) \cdot d_o(p_j)$$

ii) 
$$B_{j}^{i} \wedge B_{j}^{i} \neq \emptyset$$
  $\longrightarrow$   $P_{j}^{i} \in 2 \cdot (1-\epsilon_{i})^{-1} \cdot B_{j}^{i}$  and  $\sigma \cdot B_{j}^{i} \in (2 + \sigma \cdot (1+\epsilon_{i})) \cdot (1-\epsilon_{i})^{-1} \cdot B_{j}^{i}$  for all  $\sigma > 0$ .

iii) the balls  $B_{j}^{o}$ ,  $1 \le j \le N$ , cover the annulus  $A(R_{1}, R_{2})$ .

In order to prove (iii) , let us assume that there is some  $p_{N+1} \in A(R_1,R_2) \setminus V\{B_j^o \mid 1 \le j \le N\}$ ; it is a consequence of (ii) that the ball  $B_{N+1}^{-1} := B(p_{N+1},\epsilon_{-1} \cdot d_o(p_{N+1}))$  is disjoint from the other  $B_j^{-1}$ . This conclusion contradicts the maximality of the family  $(B_j^{-1})_{j=1}^N$ .

We point out that for sufficiently large t the corollary 1.6 gives raise to an upper bound on

$$rk_{*}^{t-1}(A((1-\epsilon_{n+1})\cdot R_{1},(1+\epsilon_{n+1})\cdot R_{2}),A(R_{1},R_{2}))$$

in terms of the quantities  $rk_*^{t-1}(\rho \cdot B_j^i, B_j^i)$ ,  $0 \le i \le n$ ,  $1 \le j \le N$ , which in turn have already been controlled in lemma 4.3.

We continue listing some inequalities which will be used in the subsequent computations.

#### 4.5 Lemma:

The number of balls  $B_{j}^{n}$ , which intersect a given ball  $B_{j}^{n}$  is bounded from above by

$$t_1(n) = 5^{n^2} \cdot 8^n \cdot \exp(\frac{9}{4 \cdot (n+1)})$$

# Proof:

Since by construction the balls  $B_{i}^{-1}$  are disjoint, we can deduce from

4.4vi that:

$$\frac{1}{n} \left\{ B_{j'}^{n} \mid B_{j'}^{n} \cap B_{j}^{n} \neq \emptyset \right\} \leq \sup_{j'} \frac{\operatorname{vol} \tau_{n} \cdot B_{j'}^{n}}{\operatorname{vol} B_{j'}^{-1}}$$
 (\*)

The curvatures in the ball  $\tau_n \cdot B_i^n$  are bounded from below by  $-\xi_{i}^2$ where

$$\xi_{j'} := \sqrt{2 \cdot b_o \cdot f(\frac{R_1}{L+1})} \cdot (1 - \tau_n \cdot \varepsilon_n)^{-1} \cdot d_o(p_{j'})^{-1}$$

$$\frac{\tau_n \cdot \varepsilon_n}{1 - \tau_n \cdot \varepsilon_n} \quad \stackrel{\text{d}}{=} \quad \frac{2}{L+3} \cdot \frac{\eta}{1 - \eta}$$

and since  $p_i \in A(R_1, R_2)$ , it follows that:

$$\xi_{j'} \cdot \tau_n \cdot \varepsilon_n \cdot d_o(p_{j'}) \leq \frac{2}{L+3}$$

Therefore the volume comparison for concentric metrical balls yields:

$$\frac{\text{vol } \tau_{n} \cdot B_{ji}^{n}}{\text{vol } B_{ji}^{-1}} \geq \frac{\int_{0}^{\tau_{n} \cdot G_{0}(p_{ji})} \sinh(\xi_{ji} \cdot \sigma)^{n-1} d\sigma}{\int_{0}^{\varepsilon_{-1} \cdot G_{0}(p_{ji})} \sinh(\xi_{ji} \cdot \sigma)^{n-1} d\sigma}$$

$$\leq \left(\frac{\tau_{n} \cdot \varepsilon_{n}}{\varepsilon_{-1}}\right)^{n} \cdot \left(\frac{\sinh(\xi_{ji} \cdot \tau_{n} \cdot \varepsilon_{n} \cdot G_{0}(p_{ji}))}{\xi_{ji} \cdot \tau_{n} \cdot \varepsilon_{n} \cdot G_{0}(p_{ji})}\right)^{n-1}$$

$$\leq \left(\frac{\tau_{n} \cdot \varepsilon_{n}}{\varepsilon_{-1}}\right)^{n} \cdot \exp\left(\frac{2n-2}{L+3}\right)$$

We plug this estimate into (\*) and obtain by means of 4.4ix that:

# { 
$$B_{j'}^{n} \mid B_{j'}^{n} \land B_{j}^{n} \neq \emptyset$$
 }  $4 \cdot 8^{n} \cdot 5^{n^{2}} \cdot \exp(\frac{2n^{2}}{5L} + \frac{3n-2}{L+3} + \frac{7n}{8} \cdot 5^{-n-1})$ 

In order to bound the number N of balls  $B_{i}^{o}$  in the covering, we look at the pulled back situation under  $exp_0:T_0M \longrightarrow M$ . We pick a family of vectors  $v_i \in T_0M$  such that

i) 
$$\exp_{o}(\mathbf{v}_{j})$$
 is the centre  $\mathbf{p}_{j}$  of  $\mathbf{B}_{j}^{o}$ ;  
ii)  $\|\mathbf{v}_{j}\| = \mathbf{d}_{o}(\mathbf{p}_{j})$ , i.e. the curve  $t \longmapsto \exp_{o}(t \cdot \mathbf{v}_{j})$ ,  $t \in [0,1]$ , is minimizing.

Given numbers  $0 < \zeta_1$ ,  $\zeta_2$ ,  $\zeta_3 < 1$  and a non-zero vector  $w \in T_0M$ , we consider the sets

$$\text{AC}(w; \zeta_1, \zeta_2, \zeta_3) := \{ v < T_0 M \mid | \not \leq (v, w) | \leq \zeta_1 \cdot \zeta_3 \cdot \exp(-b_1) \text{ and }$$
 
$$(1 - \zeta_1) \cdot (1 - \zeta_2) \cdot |w| \leq |v| \leq (1 - \zeta_1) \cdot (1 + \zeta_2) \cdot |w| \} .$$

# 4.6 Lemma:

i) If 
$$1-\epsilon_{-1} \leq (1-\zeta_1) \cdot (\sqrt{1-\zeta_3^2} - \zeta_2)$$
, then  $\exp_0$  maps the set  $AC(v_j; \zeta_1, \zeta_2, \zeta_3)$  into  $B_j^{-1}$  for all  $j$ .

ii) The number of disjoint sets  $AC(w;\zeta_1,\zeta_2,\zeta_3)$  in the annulus

$$A := \{ v \in T_0 M \mid (1-\zeta_1) \cdot (1-\zeta_2) \cdot R_1 \leq |v| \leq (1-\zeta_1) \cdot (1+\zeta_2) \cdot R_2 \}$$

is bounded from above by

$$(2+\zeta_2^{-1}\cdot \ln\frac{R_2}{R_1})\cdot \pi^{n-1}\cdot (2\cdot \zeta_1\cdot \zeta_3)^{1-n}\cdot \exp((n-1)\cdot b_1)$$

iii) The number N of distinct balls  $B_j^{-1}$  in  $M^n$  is bounded from above by

$$N_{1} := \left(\frac{5^{-n}}{8L+32} + \ln \frac{R_{2}}{R_{1}}\right) \cdot 16 \cdot \left(16 \cdot \pi\right)^{n-1} \cdot \sqrt{\frac{5^{n} \cdot L}{\eta}}^{3n-1} \cdot \exp\left(\frac{3n-1}{L} \cdot \left(\frac{n}{5} + \frac{17}{8}\right)\right) \cdot \exp\left((n-1) \cdot b_{1}\right)$$

#### Proof:

i) It is sufficient to show that  $\exp_0$  maps the sets  $AC(v_j;\zeta_1,0,\zeta_3)$  into the  $(\varepsilon_{-1}-\zeta_2\cdot(1-\zeta_1))$  - small balls  $(1-\zeta_2\cdot(1-\zeta_1)\cdot\varepsilon_{-1}^{-1}\cdot B_j^{-1})$ . This amounts to studying the generalized geodesic triangle  $\Delta=(p_j,p,o)$ , where p is the image under  $\exp_0$  of any vector  $v \in AC(v_j;\zeta_1,0,\zeta_3)$ . Thus, in the notation of proposition M.1, we have:

$$\begin{array}{l}
\boldsymbol{\ell}_{1} = d_{o}(\mathbf{p}_{j}) \\
\boldsymbol{\ell}_{o} = d_{o}(\mathbf{p}) \leq (1-\zeta_{1}) \cdot \boldsymbol{\ell}_{1} \\
\cos(\star \mathbf{at} \ o) \geq \sqrt{1-\zeta_{1}^{2} \cdot \zeta_{3}^{2} \cdot \exp(-2 \cdot \mathbf{b}_{1})}
\end{array}$$

Hence, the proposition applies and yields the desired inequality:

$$d(p,p_{j}) \neq t_{1} - t_{0} \cdot \sqrt{1-\zeta_{3}^{2}}$$

$$\neq (1 - (1-\zeta_{1}) \cdot \sqrt{1-\zeta_{3}^{2}}) \cdot d_{0}(p_{j})$$

$$\neq (\varepsilon_{-1} - \zeta_{2} \cdot (1-\zeta_{1})) \cdot d_{0}(p_{j})$$

ii) We make use of the diffeomorphism  $\Phi:T_0M\setminus\{0\}\longrightarrow S^{n-1}\times\mathbb{R}$ ,  $v\longmapsto (|v|^{-1}\cdot v, \ln|v|)$  and the canonical volume form on  $S^{n-1}\times\mathbb{R}$ , and we

compute -  $B^{S}(r)$  will denote a ball of radius r in  $S^{n+1}$  -:

++ disjoint sets AC(w; $\zeta_1,\zeta_2,\zeta_3$ ) in A

$$\sup_{\mathbf{w}} \frac{\text{vol } \phi(\mathbf{A})}{\text{vol } \phi(\mathbf{AC}(\mathbf{w};\zeta_1,\zeta_2,\zeta_3))}$$

4 
$$\ln \frac{(1+\zeta_2) \cdot R_2}{(1-\zeta_2) \cdot R_1} \cdot \left( \ln \frac{1+\zeta_2}{1-\zeta_2} \right)^{-1} \cdot \frac{\text{vol } S^{n+1}}{\text{vol } B^{\$}(\zeta_1 \cdot \zeta_3 \cdot \exp(-b_1))}$$

$$4 \left(1 + \left(\ln \frac{1+\zeta_2}{1-\zeta_2}\right)^{-1} \cdot \ln \frac{R_2}{R_1}\right) \cdot 2 \cdot \pi^{n-1} \cdot \left(2 \cdot \zeta_1 \cdot \zeta_3 \cdot \exp(-b_1)\right)^{1-n}$$

This inequality immediately yields the claimed bound, as it is known that  $\ln(1+\zeta_2) - \ln(1-\zeta_2) \ge 2\zeta_2$  for all  $\zeta_2 \ge 0$ .

iii) If  $\zeta_1 + \zeta_2 + \zeta_3^2 = \varepsilon_{-1}$ , then the hypothesis of (i) are meet, the sets  $AC(v_j; \zeta_1, \zeta_2, \zeta_3)$  are disjoint, and part (ii) yields the required control on N. We put  $\zeta_1 = 2 \cdot \zeta_2 = 2 \cdot \zeta_3^2 = 0.5 \cdot \varepsilon_{-1}$  and obtain the estimate:

$$N = (2 \cdot \epsilon_{-1} + 4 \cdot \ln \frac{R_2}{R_1}) \cdot (2 \cdot \pi)^{n-1} \cdot \sqrt{\epsilon_{-1}}^{-(3n-1)} \cdot \exp((n-1) \cdot b_1)$$

Using the estimates given in 4.4, one easily verifies that the right-hand side is dominated by  $N_1$ .

# 4.7 Proposition:

Assume like in 4.1 that  $0 < R_1 \le R_2$  and that  $n \le (1 + \sqrt{b_0 \cdot f(\frac{R_1}{2L_0})})^{-1}$ If moreover  $t \ge t_1(n) := 5^n \cdot 8^n \cdot exp(\frac{9}{4 \cdot (n+1)})$ 

the following estimates hold:

where 
$$C_a(n) := (e-1)^{2n} \cdot (5 \cdot (1+\sqrt{2}))^{c_a(n)}$$
  
and  $c_a(n) := 2 \cdot n^3 + \frac{19}{6} \cdot n^2 + \frac{5}{12} \cdot n + \frac{3}{4}$ 

ii) 
$$\lim_{R_1 \to \infty} \operatorname{rk}_{*}^{\mathsf{t}^{-1}} (A(\frac{6}{7}, R_1, \frac{8}{7}, R_1), A(R_1, R_1)) \leq C_{\mathsf{e}}(n) \cdot \exp((n-1) \cdot b_1)$$

where 
$$C_e(n) := (5 \cdot (1 + \sqrt{2}))^{\tilde{c}_e(n)}$$
  
and  $\tilde{c}_e(n) := 2 \cdot n^3 + \frac{19}{6} \cdot n^2 - \frac{1}{3} \cdot n - \frac{1}{3}$ 

#### Remark:

We point out that

$$\frac{1}{\sqrt{2}} \cdot (1 + \sqrt{b_0 \cdot f(\frac{R_2}{R_1})}) \leq \frac{1}{\sqrt{2}} \cdot (1 + \sqrt{b_0}) \leq \sqrt{1 + b_0}$$

Since by lemma II.2.1 the last term does not exceed  $\exp(\frac{1}{2} \cdot b_3)$ , it is admissible to pick:

$$\frac{1}{\sqrt{2} \cdot n} := \exp(\frac{1}{2} \cdot b_3)$$

#### Proof:

By continuity it is sufficient to treat the case  $\eta < (1+v_0 \cdot f(\frac{R_1}{2L_0}))^{-1}$ . We are going to consider the covering constructed in 4.3. One easily verifies that  $t_1(n) \ge \tilde{t}_0(n)$ ; hence it is possible to apply corollary 1.6 and lemma 4.2ii:

$$rk_{*}^{t^{-1}} (A(\frac{6}{7} \cdot R_{1}, \frac{8}{7} \cdot R_{2}), A(R_{1}, R_{2}))$$

$$= (e-1) \cdot N_{1} \cdot \sup \{ rk_{*}^{t^{-1}} (\rho \cdot B, B) \mid B \text{ is } \delta \text{-small with } \delta \leq \epsilon_{n}$$
and has centre in the set  $A(R_{1}, R_{2}) \}$ 

$$= (e-1)^{2n} \cdot \tilde{N}_{0}^{2n-1} \cdot N_{1}$$

$$= (e-1)^{2n} \cdot c_{1} \cdot c_{2} \cdot (\frac{5^{-n}}{8L+32} + \ln \frac{R_{2}}{R_{1}}) \cdot \sqrt{n}^{1-3n} \cdot \exp((n-1) \cdot b_{1})$$

Here we have used the abbreviations:

$$c_1 := ((12 \cdot L)^n \cdot 5^n^2)^{2n-1} \cdot \sqrt{5^n \cdot L}^{3n-1} \cdot (16 \cdot \pi)^{n-1} \cdot 16$$
and 
$$c_2 := \exp(\frac{2n^2 - n}{L} \cdot (\frac{2n}{5} + \frac{8+5^{-n}}{12}) + \frac{3n-1}{L} \cdot (\frac{n}{5} + \frac{17}{8}) + \frac{(2n-1) \cdot (n-1) \cdot \sqrt{2}}{L+2})$$

Since  $L \ge 3 \cdot (1+\sqrt{2})^{n-1}$ , we have  $c_2 \le 36$  for all  $n \ge 2$ .

i) Observing that  $\frac{5^{-n}}{8L+32} \le \frac{1}{2000}$ , it is sufficient to show that

$$\sqrt{2}^{3n-1} \cdot c_1 \cdot c_2 \leftarrow c_a(n)$$

Obviously 
$$\sqrt{2}^{3n-1} \cdot c_1 = (5 \cdot (1+\sqrt{2}))^{n^2 \cdot (2n-1) + n \cdot (3n-1)/2} \cdot (\frac{36 \cdot \sqrt{3}}{1+\sqrt{2}})^{n \cdot (2n-1)} \cdot (\frac{3 \cdot \sqrt{6}}{1+\sqrt{2}})^{(3n-1)/2} \cdot (16 \cdot \pi)^{n-1} \cdot 16$$

and the result is due to the inequalities:

$$\frac{36 \cdot \sqrt{3}}{1+\sqrt{2}} \leq \left(5 \cdot (1+\sqrt{2})\right)^{4/3} , \quad \left(\frac{3 \cdot \sqrt{6}}{1+\sqrt{2}}\right)^{3/2} \cdot 16 \cdot \pi \leq \left(5 \cdot (1+\sqrt{2})\right)^{9/4} ,$$

and 
$$\frac{3 \cdot \sqrt{6}}{1 + \sqrt{2}} \cdot 16 \cdot c_2 \le (5 \cdot (1 + \sqrt{2}))^3$$
.

ii) Since the error function f converges to zero for  $R_1^{\to\infty}$ , it is possible to pick a function  $\eta(R_1)$  which converges to 1 for  $R_1^{\to\infty}$ . Thus one is reduced to checking that

$$(e^{-1})^{2n} \cdot c_1 \cdot c_2 \cdot \frac{5^{-n}}{8 \cdot L} \neq c_e(n)$$

This can be done calculating in a similar way as above.

#### 5. The Global Estimates

The special case of non-negative curvature has been treated in corollary 3.7, and the Betti numbers of the ends of M<sup>n</sup> have been bounded in proposition 4.7ii. It remains to consider the general case and piece together the estimates on metrical annuli in an arbitrary asymptotically non-negatively curved manifold.

We look at a sequence of critical points  $p_1$ ,...,  $p_k$  of the distance function  $d_0$  such that:

$$d_{o}(p_{i}) \ge e \cdot d_{o}(p_{i+1})$$
 ,  $1 \le i \le k$  ,

and that its length k is maximal. In the terminology of 2.2 this is a metrical (k;∞,e,0)-frame of the base point o . It is useful to consider the annuli

$$A_i := A(e^{-1} \cdot d_o(p_i), e \cdot d_o(p_i))$$
,  $l \le i \le k$ .

# 5.1 Immediate Consequences:

i) 
$$k \le 2 \cdot \pi^{n-1} \cdot (\frac{e}{e-1})^{2n-2} \cdot \exp((2n-2) \cdot b_1)$$
 [lemma 2.3].

ii) M<sup>n</sup> VA; does not contain a critical point of do; therefore lemma 2.1 gives raise to a vector field vo which does not vanish on this set.

There are numbers  $0 < x_{\overline{K}} < y_{\overline{K}} < ... < x_2 < y_2 < x_1 < y_1 < x_0 := \infty$  such that:

iii) 
$$\bigvee_{i=1}^{k} A_{i} \subset \bigvee_{i=1}^{k} A(\frac{6}{7} \cdot e^{-1} \cdot d_{o}(\rho_{i}), \frac{8}{7} \cdot e \cdot d_{o}(\rho_{i}))$$

$$= \bigvee_{j=1}^{\tilde{k}} A(\frac{6}{7} \cdot x_{j}, \frac{8}{7} \cdot y_{j})$$

iv) the annuli  $A(\frac{6}{7} \cdot x_j, \frac{8}{7} \cdot y_j)$  are disjoint.

It is convenient to also introduce the annuli  $\tilde{A}_j$  which are defined as follows:

$$\tilde{A}_{j} := \Lambda(\frac{3}{4} \cdot x_{j}, x_{j-1})$$
,  $1 \le j < \tilde{k}$ ,  
 $\tilde{A}_{\tilde{k}} := \overline{B(o, x_{\tilde{k}-1})} \setminus \{o\}$ 

# 5.2 Observations:

i) 
$$\sum_{j=1}^{k} (\ln \frac{4}{3} + \ln \frac{y_j}{x_j}) \leq k \cdot (2 + \ln \frac{4}{3})$$
.

ii) 
$$M^n \setminus \{0\} = \bigvee_{j=1}^{\tilde{k}} \tilde{A}_j$$

iii) 
$$\tilde{A}_{j} \cap \tilde{A}_{j+1} = A(\frac{3}{4} \cdot x_{j}, x_{j})$$
 ,  $1 \le j < \tilde{k}$ , and  $\tilde{A}_{j} \cap \tilde{A}_{j} = \emptyset$  , if  $|j-j^{\dagger}| \ge 2$ 

iv) the Mayer - Vietoris sequence yields estimates on the values of the Poincaré series (for positive t):

$$P_{t}(M^{n} \setminus \{o\}) \leq \sum_{j=1}^{\tilde{k}} P_{t}(\tilde{A}_{j}) + \sum_{j=1}^{\tilde{k}-1} P_{t}(A(\frac{3}{4} \cdot x_{j}, x_{j}))$$

$$P_{t}(M^{n}) \leq \sum_{j=1}^{\tilde{k}} (P_{t}(\tilde{A}_{j}) + P_{t}(A(\frac{3}{4} \cdot x_{j}, x_{j})))$$

v) the inclusions

$$A(x_{j}, y_{j}) \longleftrightarrow A(\frac{6}{7} \cdot x_{j}, \frac{8}{7} \cdot y_{j}) \longleftrightarrow \widetilde{A}_{j}$$
 and 
$$A(\frac{7}{8} \cdot x_{j}, \frac{7}{8} \cdot x_{j}) \longleftrightarrow A(\frac{3}{4} \cdot x_{j}, x_{j})$$

allow for deformation retracts along the vector field  $\mathbf{v}_{o}$  as has been mentioned above.

vi) 
$$P_{t-1}(M^n) \leq \sum_{j=1}^{\tilde{k}} (rk_*^{t-1}(A(\frac{6}{7} \cdot x_j, \frac{8}{7} \cdot y_j), A(x_j, y_j)) + rk_*^{t-1}(A(\frac{3}{4} \cdot x_j, x_j), A(\frac{7}{8} \cdot x_j, \frac{7}{8} \cdot x_j)))$$

vii) if  $t \ge t_2(n)$  the right hand side of the previous formula can be estimated by means of proposition 4.7:

$$P_{t-1}(M^n) \leq \sum_{j=1}^{\tilde{k}} \left( \frac{1}{1000} + \ln \frac{y_j}{x_j} \right) \cdot C_a(n) \cdot \exp\left( \frac{7n-5}{4} \cdot b_j \right)$$

We use 5.1i and 5.2i in order to compute the bound. This gives us the following result:

# 5.3 Proposition:

Let  $M^n$  be an asymptotically non-negatively curved manifold,  $b_1$  be its curvature invariant (as above), and let t be some number

greater than:

$$t_1(n) := 5^{n^2} \cdot 8^n \cdot \exp(\frac{9}{4} \cdot \frac{1}{n+1})$$

then:

$$P_{t-1}(M^n) \leq (5 \cdot (1+\sqrt{2}))^{c(n)} \cdot \exp(\frac{15n-13}{4} \cdot b_1(M^n))$$

where:

c(n) := 
$$2 \cdot n^3 + \frac{19}{6} \cdot n^2 + \frac{9}{5} \cdot n + \frac{3}{5}$$

#### Remarks:

- i) Up to this point all the numerical estimates done in order to get a simple explicit bound have been chosen in such a way that they do not spoil the leading order terms of c(n) and t<sub>1</sub>(n). As far as c(n) is concerned both the factors in the basis directly stem from the geometric constructions: the Fibonacci number 5 reflects the geometry in the local covering argument (c.f. corollary 1.6), and the number 1+12 is due to the packing argument in appendix A.
- ii) The lower order terms have not been treated that carefully; they could even be improved easily by changing the geometric details in the argument. For instance one could make use of the fact that the critical points of the distance function dp cannot lie everywhere in an incompressible ball B(p,r); they are contained in a rather small subset, and lemma 3.5 could be modified accordingly.

## Appendix A

A Packing Problem in  $S^{n-1} \subset \mathbb{R}^n$ 

We define sequences  $\binom{a}{n}_{n\geq 1}$  and  $\binom{\alpha}{n}_{n\geq 1}$  of real numbers in (0,1] resp.  $(0,\frac{\pi}{2}]$  by:

$$a_1 := 1$$
 $a_n = a_{n-1} \cdot (1 - a_n) \cdot (1 + \sqrt{\frac{2}{1 + a_n}})^{-1}$ ,  $n \ge 2$ 
 $\alpha_n := \arcsin(a_n)$ ,  $n \ge 1$ 

Proposition:

Let  $A_n$  be the collection of all subsets  $A < s^{n-1}$  which obey the condition

(\*) 
$$p, q \in A$$
,  $p \neq q \longrightarrow d(p,q) > \frac{\pi}{2} - \alpha_n$ 

Then:

and

$$\max \left\{ \frac{1}{n} A \mid A \in A_n \right\} = 2n$$

#### Remarks:

- i) We point out that  $a_2 = \sin(\frac{\pi}{10})$ , and  $\frac{\pi}{2} \alpha_2 = \frac{2\pi}{5}$ , which is the centriangle of the regular 5 gon.
- ii) As explained in example I in appendix B, there is the estimate:

$$\frac{1}{3} \cdot (1 + \sqrt{2})^{1-n} \leq a_n \leq (1 + \sqrt{2})^{1-n}$$
,  $n \geq 2$ .

iii) We may view  $\alpha_n$  as a lower bound on the angle  $\tilde{\alpha}_n$  defined by

$$\frac{\pi}{2} - \tilde{\alpha}_n = 2 \cdot \sup \{ \rho \mid \text{there exist } 2n+1 \text{ disjoint }$$
  
balls of radius  $\rho$  in  $S^{n-1} \}$ 

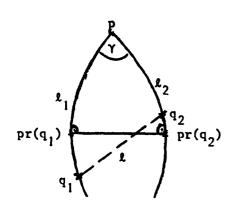
In principal such a bound could also have been obtained computing the packing densities of n balls of radius p mutually touching each other with respect to the simplex spanned by their centres. (c.f. [Bö].) Proof:

The vertices of the generalized octahedron in  $\mathbb{R}^n$  define a set  $A \leqslant A_n$ . This proves ">". The opposite inequality is shown by induction: We take some  $A \leqslant A_n$ , If A contains no more than 2 elements, we are done; else we pick 2 points p,  $\tilde{p} \leqslant A$  such that their distance  $d(p,\tilde{p})$  is maximal. To finish the proof, we construct a projection of  $A' := A \setminus \{p,\tilde{p}\}$  onto some set in  $A_{n-1}$ :

i) The estimate  $\frac{\pi}{2} - \alpha_n < d(p,q) < \frac{3\pi}{4} + \frac{1}{2} \cdot \alpha_n$  holds for all  $q \in A^*$ .
Assuming the converse, one concludes that q and  $\vec{p}$  both lie in the ball

of radius  $\frac{\pi}{4} - \frac{1}{2} \cdot \alpha_n$  around the antipodal point of p. This observation immediately yields a contradiction to property (\*).

ii) The projection  $pr: A' \longrightarrow s^{n-2} = \{x \in s^{n-1} \mid d(p,x) = \frac{\pi}{2} \}$  along the great circles through p can be controlled by means of spherical trigonometry:



Suppose that  $q_1, q_2$  are two distinct points in A'; put:  $\gamma := d(pr(q_1), pr(q_2))$ 

The Law of Cosines may be written as follows:

(\*\*) 
$$\cos \gamma = \frac{\cos \ell - \cos \ell_1 \cdot \cos \ell_2}{\sin \ell_1 \cdot \sin \ell_2}$$

It is elementary analysis to verify that under the constraints

$$\frac{\pi}{2} - \alpha_n \leq \ell_2 \leq \ell_1 \leq \frac{3\pi}{4} + \frac{1}{2} \cdot \alpha_n \qquad , \qquad \frac{\pi}{2} - \alpha_n \leq \ell$$

the right-hand side of (\*\*) has a unique maximum, which is acchieved at:

$$\ell = \ell_2 = \frac{\pi}{2} - \alpha_n$$
,  $\ell_1 = \frac{3\pi}{4} + \frac{1}{2} \cdot \alpha_n$ 

Therefore, if  $q_1, q_2 \in A^1$ , we conclude:

$$\cos \gamma > \cot \left(\frac{\pi}{2} - \alpha_{n}\right) \cdot \frac{1 - \cos \left(\frac{3\pi}{4} + \frac{1}{2} \cdot \alpha_{n}\right)}{\sin \left(\frac{3\pi}{4} + \frac{1}{2} \cdot \alpha_{n}\right)}$$

$$= \tan \alpha_{n} \cdot \frac{1 + \sqrt{\frac{1}{2} \cdot (1 - \cos \left(\frac{\pi}{2} + \alpha_{n}\right))}}{\sqrt{\frac{1}{2} \cdot (1 + \cos \left(\frac{\pi}{2} + \alpha_{n}\right))}}$$

$$= \frac{a_{n}}{\sqrt{1 - a_{n}^{2}}} \cdot \frac{\sqrt{2} + \sqrt{1 + a_{n}}}{\sqrt{1 - a_{n}}}$$

$$= \frac{a_{n}}{1 - a_{n}} \cdot \left(1 + \sqrt{\frac{2}{1 + a_{n}}}\right) = a_{n-1}$$

hence:

$$\cos \gamma > \cos (\frac{\pi}{2} - \alpha_{n-1})$$

## Appendix B

A Lemma on Recursively Defined Sequences:

Let  $\phi: [0,1) \longrightarrow [a,\infty)$  be a monotone function such that  $\phi(0) = a > 1$ . Then  $f: [0,1) \longrightarrow [0,\infty)$ ,  $x \longmapsto x \cdot \phi(x)$  is invertible. For any  $x \in (0,1]$  there is a unique sequence of real numbers  $(x \cap x \in \mathbb{N})$  defined by:

$$x_n = f(x_{n+1})$$
 ,  $x_{n+1} \in (0,1]$ 

#### Lemma:

$$\overrightarrow{i}$$
  $x_{n+1} \leq a^{-1} \cdot x_n \leq a^{-n} \cdot x_1$ 

If moreover  $\phi(x) \leq a \cdot (1+x)/(1-x)$  for all  $x \in [0,1)$ , there are also lower bounds for the  $x_n$ :

$$ii$$
)  $x_{n+1}/x_n = \phi(x_{n+1})^{-1} \ge \phi(a^{-n} \cdot x_1)^{-1}$ 

iii) 
$$x_n/x_0 \ge a^{-n} \cdot (\frac{1-x_1}{1+x_1})^{\frac{a}{a-1}} \ge a^{-n} \cdot (\frac{a-x_0}{a+x_0})^{\frac{a}{a-1}}$$
;  $n \ge 1$ 

<u>Proof:</u> (i) and (ii) are obvious. In order to prove the last claim, notice that by induction:

(\*) 
$$x_n/x_0 = \prod_{j=0}^{n-1} \phi(a^{-j} \cdot x_1)^{-1} = a^{-n} \cdot \prod_{j=0}^{n-1} \frac{1-a^{-j} \cdot x_1}{1+a^{-j} \cdot x_1}$$

We compute:

$$\sum_{j=0}^{n-1} \ln \left( \frac{1 - a^{-j} \cdot x_1}{1 + a^{-j} \cdot x_1} \right) = -2 \cdot \sum_{j=0}^{n-1} \sum_{k=0}^{\infty} \frac{1}{2k+1} \cdot a^{-j \cdot (2k+1)} \cdot x_1^{2k+1}$$

$$= -2 \cdot \sum_{k=0}^{\infty} \frac{1}{2k+1} \cdot \frac{1}{1 - a^{-2k-1}} \cdot x_1^{2k+1}$$

$$= \frac{a}{a-1} \cdot \ln \left( \frac{1 - x_1}{1 + x_1} \right)$$

Combining this inequality with (\*) gives the required estimate.

#### Examples:

1.) 
$$\phi(x) = (1 + \sqrt{\frac{2}{1+x}}) / (1-x)$$
;  $x_0 = 1$ :

Clearly  $a = 1 + \sqrt{2}$  and  $x_1 = \sin(\frac{\pi}{10})$ ; therefore one has:

 $x_n = \frac{1}{3} \cdot (1 + \sqrt{2})^{-n}$ , provided  $n \ge 1$ .

2.) 
$$\phi(x) = (2 + \rho \cdot (1+x)) / (1-x)$$
, where  $2 + \rho = 5 + 2 \cdot L^{-1}$ ,  $L > 0$ ;  $x_0 \le \frac{1}{2 \cdot (L+4)}$ 

Clearly  $a = 2 + \rho$ , and one easily computes that:

$$\left(\frac{a+x_{o}}{a-x_{o}}\right)^{a/a-1} \leq \left(\frac{5+\frac{2}{L}+\frac{1}{2\cdot(L+4)}}{5+\frac{2}{L}-\frac{1}{2\cdot(L+4)}}\right)^{5/4}$$

$$\leq \left(1+\frac{1}{5\cdot(L+4)}\right)^{5/4} \leq \exp\left(\frac{1}{4\cdot(L+4)}\right)$$

Therefore

$$5^n \leq \frac{x_0}{x_n} \leq 5^n \cdot \exp(\frac{2n}{5L} + \frac{1}{4 \cdot (L+4)})$$

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