# Compact polyhedral surfaces of an arbitrary genus and determinant of Laplacian 

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## 1 Introduction

Perhaps, the most elementary way to introduce a compact Riemann surface is the following: one can simply consider the boundary of a connected (but, generally, not simply connected) polyhedron in three dimensional Euclidean space. This is a polyhedral surface which carries the structure of a complex manifold (the corresponding system of holomorphic local parameters is obvious for all points except the vertices; near a vertex one should introduce the local parameter $\zeta=z^{2 \pi / \alpha}$, where $\alpha$ is the sum of the angles adjacent to the vertex). In this way the Riemann surface comes together with a conformal metric; this metric is flat and has conical singularities at the vertices. Instead of a polyhedron one can also start from some abstract simplicial complex, thinking of a polyhedral surface as glued from plane triangles.

The present paper is devoted to the spectral theory of the Laplacian on such surfaces. The main goal is to study the determinant of the Laplacian (acting in the trivial line bundle over the surface) as a functional on the space of Riemann surfaces with conformal flat conical metrics (polyhedral surfaces). The similar question for smooth conformal metrics and arbitrary holomorphic bundles was very popular in the eighties and early nineties being motivated by the string theory. The determinants of Laplacians in flat singular metrics are much less studied: among the very few appropriate references we mention [6], where the determinant of the Laplacian in conical metric was defined via some special regularization of the diverging Liouville integral and the question about the relation of such a definition with the spectrum of the Laplacian remained open, and two papers [10], [1] dealing with flat conical metrics on the Riemann sphere.

In [12] the determinant of the Laplacian was studied as a functional

$$
\mathcal{H}_{g}\left(k_{1}, \ldots, k_{M}\right) \ni(\mathcal{L}, \omega) \mapsto \operatorname{det} \Delta^{|\omega|^{2}}
$$

on the space $\mathcal{H}_{g}\left(k_{1}, \ldots, k_{M}\right)$ of equivalence classes of pairs $(\mathcal{L}, \omega)$, where $\mathcal{L}$ is a compact Riemann surface of genus $g$ and $\omega$ is a holomorphic one-form (an Abelian differential) with $M$ zeros of multiplicities $k_{1}, \ldots, k_{M}$. Here det $\Delta^{|\omega|^{2}}$ stands for the determinant of the Laplacian in the flat metric $|\omega|^{2}$

[^0]having conical singularities at the zeros of $\omega$. The flat conical metric $|\omega|^{2}$ considered in [12] is very special: the divisor of the conical points of this metric is not arbitrary (it should be the canonical one, i. e. coincide with the divisor of a holomorphic one-form) and the conical angles at the conical points are integer multiples of $2 \pi$. Later in [11] this restrictive condition has been eliminated in the case of polyhedral surfaces of genus one.

In the present paper we generalize the results of [12] and [11] to the case of polyhedral surfaces of an arbitrary genus. Moreover, we give a short and self-contained survey of some basic facts from the spectral theory of the Laplacian on flat surfaces with conical points. In particular, we discuss the theory of self-adjoint extensions of this Laplacian and study the asymptotics of the corresponding heat kernel.

## 2 Flat conical metrics on surfaces

Here following [23] and [11], we discuss flat conical metrics on compact Riemann surfaces of an arbitrary genus.

### 2.1 Troyanov's theorem

Let $\sum_{k=1}^{N} b_{k} P_{k}$ be a (generalized, i. e. the coefficients $b_{k}$ are not necessary integers) divisor on a compact Riemann surface $\mathcal{L}$ of genus $g$. Let also $\sum_{k=1}^{N} b_{k}=2 g-2$. Then, according to Troyanov's theorem (see [23]), there exists a (unique up to a homothety) conformal flat metric $\mathbf{m}$ on $\mathcal{L}$ which is smooth in $\mathcal{L} \backslash\left\{P_{1}, \ldots, P_{N}\right\}$ and has simple singularities of order $b_{k}$ at $P_{k}$. The latter means that in a vicinity of $P_{k}$ the metric $\mathbf{m}$ can be represented in the form

$$
\begin{equation*}
\mathbf{m}=e^{u(z, \bar{z})}|z|^{2 b_{k}}|d z|^{2}, \tag{2.1}
\end{equation*}
$$

where $z$ is a conformal coordinate and $u$ is a smooth real-valued function. In particular, if $\beta_{k}>-1$ the point $P_{k}$ is conical with conical angle $\beta_{k}=2 \pi\left(b_{k}+1\right)$. Here we construct the metric $\mathbf{m}$ explicitly, giving an effective proof of Troyanov's theorem (cf. [11]).

Fix a canonical basis of cycles on $\mathcal{L}$ (we assume that $g \geq 1$, the case $g=0$ is trivial) and let $E(P, Q)$ be the prime-form (see [7]). Then for any divisor $\mathcal{D}=r_{1} Q_{1}+\ldots r_{m} Q_{M}-s_{1} R_{1}-\cdots-s_{N} R_{N}$ of degree zero on $\mathcal{L}$ (here the coefficients $r_{k}, s_{k}$ are positive integers) the meromorphic differential

$$
\omega_{\mathcal{D}}=d_{z} \log \frac{\prod_{k=1}^{M} E^{r_{k}}\left(z, Q_{k}\right)}{\prod_{k=1}^{N} E^{s_{k}}\left(z, R_{k}\right)}
$$

is holomorphic outside $\mathcal{D}$ and has the first order poles at the points of $\mathcal{D}$ with residues $r_{k}$ at $Q_{k}$ and $-s_{k}$ at $R_{k}$. Since the prime-form is single-valued along the $\mathbf{a}$-cycles, all the $\mathbf{a}$-periods of the differential $\omega_{\mathcal{D}}$ vanish.

Let $\left\{v_{\alpha}\right\}_{\alpha=1}^{g}$ be the basis of holomorphic normalized differentials and $\mathbb{B}$ the corresponding matrix of $\mathbf{b}$-periods. Then all the $\mathbf{a}$ - and $\mathbf{b}$-periods of the meromorphic differential

$$
\Omega_{\mathcal{D}}=\omega_{\mathcal{D}}-2 \pi i \sum_{\alpha, \beta=1}^{g}\left((\Im \mathbb{B})^{-1}\right)_{\alpha \beta} \Im\left(\int_{s_{1} R_{1}+\ldots s_{N} R_{N}}^{r_{1} Q_{1}+\ldots r_{M} Q_{M}} v_{\beta}\right) v_{\alpha}
$$

are purely imaginary (see [7], p. 4).

Obviously, the differentials $\omega_{\mathcal{D}}$ and $\Omega_{\mathcal{D}}$ have the same structure of poles: their difference is a holomorphic 1-form.

Choose a base-point $P_{0}$ on $\mathcal{L}$ and introduce the following quantity

$$
\mathcal{F}_{\mathcal{D}}(P)=\exp \int_{P_{0}}^{P} \Omega_{\mathcal{D}} .
$$

Clearly, $\mathcal{F}_{\mathcal{D}}$ is a meromorphic section of some unitary flat line bundle over $\mathcal{L}$, the divisor of this section coincides with $\mathcal{D}$.

Now we are ready to construct the metric $\mathbf{m}$. Choose any holomorphic differential $w$ on $\mathcal{L}$ with, say, only simple zeros $S_{1}, \ldots, S_{2 g-2}$. Then one can set $\mathbf{m}=|u|^{2}$, where

$$
\begin{equation*}
u(P)=w(P) \mathcal{F}_{(2 g-2) S_{0}-S_{1}-\ldots S_{2 g-2}}(P) \prod_{k=1}^{N}\left[\mathcal{F}_{P_{k}-S_{0}}(P)\right]^{b_{k}} \tag{2.2}
\end{equation*}
$$

and $S_{0}$ is an arbitrary point.
Notice that in case $g=1$ the second factor in (2.2) is absent and the remaining part is nonsingular at the point $S_{0}$.

### 2.2 Distinguished local parameter

In a vicinity of a conical point the flat metric (2.1) takes the form

$$
\mathbf{m}=|g(z)|^{2}|z|^{2 b}|d z|^{2}
$$

with some holomorphic function $g$ such that $g(0) \neq 0$. It is easy to show (see, e. g., [23], Proposition 2) that there exists a holomorphic change of variable $z=z(x)$ such that in the local parameter $x$

$$
\mathbf{m}=|x|^{2 b}|d x|^{2}
$$

We shall call the parameter $x$ (unique up to a constant factor $c,|c|=1$ ) distinguished. In case $b>-1$ the existence of the distinguished parameter means that in a vicinity of conical point the surface $\mathcal{L}$ is isometric to the standard cone with conical angle $\beta=2 \pi(b+1)$.

### 2.3 Euclidean polyhedral surfaces.

In [23] it is proved that any compact Riemann surface with flat conformal conical metric admits a proper triangulation (i. e. each conical point is a vertex of some triangle of the triangulation). This means that any compact Riemann surface with a flat conical metric is a Euclidean polyhedral surface (see [2]) i. e. can be glued from Euclidian triangles. On the other hand as it is explained in [2] any compact Euclidean oriented polyhedral surface gives rise to a Riemann surface with a flat conical metric. Therefore, from now on we do not discern compact Euclidean polyhedral surfaces and Riemann surfaces with flat conical metrics.

## 3 Laplacians on polyhedral surfaces. Basic facts

Here claiming no originality we give a short self-contained survey of some basic facts from the spectral theory of Laplacian on compact polyhedral surfaces. We start with recalling the (slightly modified)

Carslaw construction (1909) of the heat kernel on a cone, then we describe the set of self-adjoint extensions of conical Laplacian (these results are complementary to Kondratjev's study ([13]) of elliptic equations on conical manifolds and are well-known, being in the folklore since sixties; their generalization to the case of Laplacians acting on $p$-forms can be found in [18]). Finally, we establish the precise heat asymptotics for the Friedrichs extension of the Laplacian on a compact polyhedral surface. It should be noted that more general results on the heat asymptotics for Laplacians acting on $p$-forms on piecewise flat pseudomanifolds can be found in [5].

### 3.1 The heat kernel on infinite cone

We start from the standard heat kernel

$$
\begin{equation*}
H_{2 \pi}(x, y ; t)=\frac{1}{4 \pi t} \exp \{-(x-y) \cdot(x-y) / 4 t\} \tag{3.1}
\end{equation*}
$$

in the space $\mathbb{R}^{2}$ which we consider as the cone with conical angle $2 \pi$. Introducing the polar coordinates $(r, \theta)$ and $(\rho, \psi)$ in the $x$ and $y$-planes, one can rewrite (3.1) as the contour integral

$$
\begin{equation*}
H_{2 \pi}(x, y ; t)=\frac{1}{16 \pi^{2} i t} \exp \left\{-\left(r^{2}+\rho^{2}\right) / 4 t\right\} \int_{C_{\theta, \psi}} \exp \{r \rho \cos (\alpha-\theta) / 2 t\} \cot \frac{\alpha-\psi}{2} d \alpha \tag{3.2}
\end{equation*}
$$

where $C_{\theta, \psi}$ denotes the union of a small positively oriented circle centered at $\alpha=\psi$ and the two vertical lines, $l_{1}=(\theta-\pi-i \infty, \theta-\pi+i \infty)$ and $l_{2}=(\theta+\pi+i \infty, \theta+\pi-i \infty)$, having mutually opposite orientations.

To prove (3.2) one has to notice that

1) $\Re \cos (\alpha-\theta)<0$ in vicinities of the lines $l_{1}$ and $l_{2}$ and, therefore, the integrals over these lines converge.
2)The integrals over the lines cancel due to $2 \pi$-periodicity of the integrand and the remaining integral over the circle coincides with (3.1) due to the Cauchy Theorem.

Observe that one can deform the contour $C_{\theta, \psi}$ into the union, $A_{\theta}$, of two contours lying in the open domains $\{\theta-\pi<\Re \alpha<\theta+\pi, \Im \alpha>0\}$ and $\{\theta-\pi<\Re \alpha<\theta+\pi, \Im \alpha<0\}$ respectively, the first contour goes from $\theta+\pi+i \infty$ to $\theta-\pi+i \infty$, the second one goes from $\theta-\pi-i \infty$ to $\theta+\pi-i \infty$. This leads to the following representation for the heat kernel $H_{2 \pi}$ :

$$
\begin{equation*}
H_{2 \pi}(x, y ; t)=\frac{1}{16 \pi^{2} i t} \exp \left\{-\left(r^{2}+\rho^{2}\right) / 4 t\right\} \int_{A_{\theta}} \exp \{r \rho \cos (\alpha-\theta) / 2 t\} \cot \frac{\alpha-\psi}{2} d \alpha \tag{3.3}
\end{equation*}
$$

The latter representation admits natural generalization to the case of the cone $C_{\beta}$ with conical angle $\beta, 0<\beta<+\infty$. Notice here that in case $0<\beta \leq 2 \pi$ the cone $C_{\beta}$ is isometric to the surface $z_{3}=\sqrt{\left(\frac{4 \pi^{2}}{\beta^{2}}-1\right)\left(z_{1}^{2}+z_{2}^{2}\right)}$.

Namely, introducing the polar coordinates on $C_{\beta}$, we see that the following expression represents the heat kernel on $C_{\beta}$ :

$$
\begin{equation*}
H_{\beta}(r, \theta, \rho, \psi ; t)=\frac{1}{8 \pi \beta i t} \exp \left\{-\left(r^{2}+\rho^{2}\right) / 4 t\right\} \int_{A_{\theta}} \exp \{r \rho \cos (\alpha-\theta) / 2 t\} \cot \frac{\pi(\alpha-\psi)}{\beta} d \alpha \tag{3.4}
\end{equation*}
$$

Clearly, expression (3.4) is symmetric with respect to $(r, \theta)$ and $(\rho, \psi)$ and is $\beta$-periodic with respect to the angle variables $\theta, \psi$. Moreover, it satisfies the heat equation on $C_{\beta}$. Therefore, to verify that $H_{\beta}$ is in fact the heat kernel on $C_{\beta}$ it remains to show that $H_{\beta}(\cdot, y, t) \longrightarrow \delta(\cdot-y)$ as $t \rightarrow 0+$. To this end
deform the contour $A_{\psi}$ into the union of the lines $l_{1}$ and $l_{2}$ and (possibly many) small circles centered at the poles of $\cot \frac{\pi(\cdot-\psi)}{\beta}$ in the strip $\theta-\pi<\Re \alpha<\theta+\pi$. The integrals over all the components of this union except the circle centered at $\alpha=\psi$ vanish in the limit as $t \rightarrow 0+$, whereas the integral over the latter circle coincides with $H_{2 \pi}$.

### 3.1.1 The heat asymptotics near the vertex

Proposition 1 Let $R>0$ and $C_{\beta}(R)=\left\{x \in C_{\beta}: \operatorname{dist}(x, \mathcal{O})<R\right\}$. Let also dx denote the area element on $C_{\beta}$. Then for some $\epsilon>0$

$$
\begin{equation*}
\int_{C_{\beta}(R)} H_{\beta}(x, x ; t) d x=\frac{1}{4 \pi t} \operatorname{Area}\left(C_{\beta}(R)\right)+\frac{1}{12}\left(\frac{2 \pi}{\beta}-\frac{\beta}{2 \pi}\right)+O\left(e^{-\epsilon / t}\right) \tag{3.5}
\end{equation*}
$$

as $t \rightarrow 0+$.
Proof (cf. [9], p. 1433). Make in (3.4) the change of variable $\gamma=\alpha-\psi$ and deform the contour $A_{\theta-\psi}$ into the contour $\Gamma_{\theta-\psi}^{-}-\cup \Gamma_{\theta-\psi}^{+} \cup\{|\gamma|=\delta\}$, where the oriented curve $\Gamma_{\theta-\psi}^{-}$goes from $\theta-\psi-\pi-i \infty$ to $\theta-\psi-\pi+i \infty$ and intersects the real axis at $\gamma=-\delta$, the oriented curve $\Gamma_{\theta-\psi}^{+}$goes from $\theta-\psi+\pi+i \infty$ to $\theta-\psi+\pi-i \infty$ and intersects the real axis at $\gamma=\delta$, the circle $\{|\gamma|=\delta\}$ is positively oriented and $\delta$ is a small positive number. Calculating the integral over the circle $\{|\gamma|=\delta\}$ via the Cauchy Theorem, we get
$H_{\beta}(x, y ; t)-H_{2 \pi}(x, y ; t)=\frac{1}{8 \pi \beta i t} \exp \left\{-\left(r^{2}+\rho^{2}\right) / 4 t\right\} \int_{\Gamma_{\theta-\psi}^{-} \cup \Gamma_{\theta-\psi}^{+}} \exp \{r \rho \cos (\gamma+\psi-\theta) / 2 t\} \cot \frac{\pi \gamma}{\beta} d \gamma$
and

$$
\begin{equation*}
\int_{C_{\beta}(R)}\left(H_{\beta}(x, x ; t)-\frac{1}{4 \pi t}\right) d x=\frac{1}{8 \pi i t} \int_{0}^{R} d r r \int_{\Gamma_{0}^{-} \cup \Gamma_{0}^{+}} \exp \left\{-\frac{r^{2} \sin ^{2}(\gamma / 2)}{t}\right\} \cot \left(\frac{\pi \gamma}{\beta}\right) d \gamma \tag{3.7}
\end{equation*}
$$

The integration over $r$ can be done explicitly and the right hand side of (3.7) reduces to

$$
\begin{equation*}
\frac{1}{16 \pi i} \int_{\Gamma_{0}^{-} \cup \Gamma_{0}^{+}} \frac{\cot \left(\frac{\pi \gamma}{\beta}\right)}{\sin ^{2}(\gamma / 2)} d \gamma+O\left(e^{-\epsilon / t}\right) \tag{3.8}
\end{equation*}
$$

(One can assume that $\Re \sin ^{2}(\gamma / 2)$ is positive and separated from zero when $\gamma \in \Gamma_{0}^{-} \cup \Gamma_{0}^{+}$.) The contour of integration in (3.8) can be changed for a negatively oriented circle centered at $\gamma=0$. Since $\operatorname{Res}\left(\frac{\cot \left(\frac{\pi \gamma}{3}\right)}{\sin ^{2}(\gamma / 2)}, \gamma=0\right)=\frac{2}{3}\left(\frac{\beta}{2 \pi}-\frac{2 \pi}{\beta}\right)$, we arrive at (3.5).

Remark 1 The Laplacian $\Delta$ corresponding to the flat conical metric $(d \rho)^{2}+r^{2}(d \theta)^{2}, 0 \leq \theta \leq \beta$ on $C_{\beta}$ with domain $C_{0}^{\infty}\left(C_{\beta} \backslash \mathcal{O}\right)$ has infinitely many self-adjoint extensions. Analyzing the asymptotics of (3.4) near the vertex $\mathcal{O}$, one can show that for any $y \in C_{\beta}, t>0$ the function $H_{\beta}(\cdot, y ; t)$ belongs to the domain of the Friedrichs extension $\Delta_{F}$ of $\Delta$ and does not belong to the domain of any other extension. Moreover, using Hankel transform, it is possible to get an explicit spectral representation of $\Delta_{F}$ (this operator has absolutely continuous spectrum of infinite multiplicity) and to show that the Schwartz kernel of the operator $e^{t \Delta_{F}}$ coincides with $H_{\beta}(\cdot, \cdot ; t)$ (see, e. g., [22] formula (8.8.30) together with [4], p. 370.)

### 3.2 Heat asymptotics for compact polyhedral surfaces

### 3.2.1 Self-adjoint extensions of conical Laplacian

Let $\mathcal{L}$ be a compact polyhedral surface with vertices (conical points) $P_{1}, \ldots, P_{N}$. The Laplacian $\Delta$ corresponding to the natural flat conical metric on $\mathcal{L}$ with domain $C_{0}^{\infty}\left(\mathcal{L} \backslash\left\{P_{1}, \ldots, P_{N}\right\}\right)$ (we remind the reader that the Riemannian manifold $\mathcal{L}$ is smooth everywhere except the vertices) is not essentially self-adjoint and one has to fix one of its self-adjoint extensions. We are to discuss now the choice a self-adjoint extension.

This choice is defined by the prescription of some particular asymptotical behavior near the conical points to functions from the domain of the Laplacian; it is sufficient to consider a surface with only one conical point $P$ of the conical angle $\beta$. More precisely, assume that $\mathcal{L}$ is smooth everywhere except the point $P$ and that some vicinity of $P$ is isometric to a vicinity of the vertex $\mathcal{O}$ of the standard cone $C_{\beta}$ (of course, now the metric on $\mathcal{L}$ no more can be flat everywhere in $\mathcal{L} \backslash P$ unless the genus $g$ of $\mathcal{L}$ is greater than one and $\beta=2 \pi(2 g-1))$.

For $k \in \mathbb{N}_{0}$ introduce the functions $V_{ \pm}^{k}$ on $C_{\beta}$ by

$$
\begin{gathered}
V_{ \pm}^{k}(r, \theta)=r^{ \pm \frac{2 \pi k}{\beta}} \exp \left\{i \frac{2 \pi k \theta}{\beta}\right\} ; \quad k>0, \\
V_{+}^{0}=1, \quad V_{-}^{0}=\log r .
\end{gathered}
$$

Clearly, these functions are formal solutions to the homogeneous problem $\Delta u=0$ on $C_{\beta}$. Notice that the functions $V_{-}^{k}$ grow near the vertex but are still square integrable in its vicinity if $k<\frac{\beta}{2 \pi}$.

Let $\mathcal{D}_{\text {min }}$ denote the graph closure of $C_{0}^{\infty}(\mathcal{L} \backslash P)$, i. e.

$$
U \in \mathcal{D}_{\min } \Leftrightarrow \exists u_{m} \in C_{0}^{\infty}(\mathcal{L} \backslash P), W \in L_{2}(\mathcal{L}): u_{m} \rightarrow U \text { and } \Delta u_{m} \rightarrow W \text { in } L_{2}(\mathcal{L}) .
$$

Define the space $H_{\delta}^{2}\left(C_{\beta}\right)$ as the closure of $C_{0}^{\infty}\left(C_{\beta} \backslash \mathcal{O}\right)$ with respect to the norm

$$
\left\|u ; H_{\delta}^{2}\left(C_{\beta}\right)\right\|^{2}=\sum_{|\alpha| \leq 2} \int_{C_{\beta}} r^{2(\delta-2+|\alpha|)}\left|D_{x}^{\alpha} u(x)\right|^{2} d x .
$$

Then for any $\delta \in \mathbb{R}$ such that $\delta-1 \neq \frac{2 \pi k}{\beta}, k \in \mathbb{Z}$ one has the a priori estimate

$$
\begin{equation*}
\left\|u ; H_{\delta}^{2}\left(C_{\beta}\right)\right\| \leq c\left\|\Delta u ; H_{\delta}^{0}\left(C_{\beta}\right)\right\| \tag{3.9}
\end{equation*}
$$

for any $u \in C_{0}^{\infty}\left(C_{\beta} \backslash \mathcal{O}\right)$ and some constant $c$ being independent of $u$ (see, e. g., [19], Chapter 2).
It follows from Sobolev's imbedding theorem that for functions from $u \in H_{\delta}^{2}\left(C_{\beta}\right)$ one has the point-wise estimate

$$
\begin{equation*}
r^{\delta-1}|u(r, \theta)| \leq c\left\|v ; H_{\delta}^{2}\left(C_{\beta}\right)\right\| . \tag{3.10}
\end{equation*}
$$

Applying estimates (3.9) and (3.10) with $\delta=0$, we see that functions $u$ from $\mathcal{D}_{\text {min }}$ must obey the asymptotics $u(r, \theta)=O(r)$ as $r \rightarrow 0$.

Now the description of the set of all self-adjoint extensions of $\Delta$ looks as follows. Let $\chi$ be a smooth function on $\mathcal{L}$ which is equal to 1 near the vertex $P$ and such that in a vicinity of the support of $\chi \mathcal{L}$ is isometric to $C_{\beta}$. Denote by $\mathfrak{M}$ the linear subspace of $L_{2}(\mathcal{L})$ spanned by the functions $\chi V_{ \pm}^{k}$ with $0 \leq k<\frac{\beta}{2 \pi}$. The dimension, $2 d$, of $\mathfrak{M}$ is even. To get a self-adjoint extension of $\Delta$ one chooses a subspace $\mathfrak{N}$ of $\mathfrak{M}$ of dimension $d$ such that

$$
(\Delta u, v)_{L_{2}(\mathcal{L})}-(u, \Delta v)_{L_{2}(\mathcal{L})}=\lim _{\epsilon \rightarrow 0+} \oint_{r=\epsilon}\left(u \frac{\partial v}{\partial r}-v \frac{\partial u}{\partial r}\right)=0
$$

for any $u, v \in \mathfrak{N}$. To any such subspace $\mathfrak{N}$ there corresponds a self-adjoint extension $\Delta_{\mathfrak{N}}$ of $\Delta$ with domain $\mathfrak{N}+\mathcal{D}_{\text {min }}$.

The extension corresponding to the subspace $\mathfrak{N}$ spanned by the functions $\chi V_{+}^{k}, 0 \leq k<\frac{\beta}{2 \pi}$ coincides with the Friedrichs extension of $\Delta$. The functions from the domain of the Friedrichs extension are bounded near the vertex.

From now on we denote by $\Delta$ the Friedrichs extension of the Laplacian on the polyhedral surface $\mathcal{L}$; other extensions will not be considered here.

### 3.2.2 Heat asymptotics

Theorem 1 Let $\mathcal{L}$ be a compact polyhedral surface with vertices $P_{1}, \ldots, P_{N}$ of conical angles $\beta_{1}, \ldots, \beta_{N}$. Let $\Delta$ be the Friedrichs extension of the Laplacian defined on functions from $C_{0}^{\infty}\left(\mathcal{L} \backslash\left\{P_{1}, \ldots, P_{N}\right\}\right)$. Then

1. The spectrum of the operator $\Delta$ is discrete, all the eigenvalues of $\Delta$ have finite multiplicity.
2. Let $\mathcal{H}(x, y ; t)$ be the heat kernel for $\Delta$. Then for some $\epsilon>0$

$$
\begin{equation*}
\operatorname{Tr} e^{t \Delta}=\int_{\mathcal{L}} \mathcal{H}(x, x ; t) d x=\frac{\operatorname{Area}(\mathcal{L})}{4 \pi t}+\frac{1}{12} \sum_{k=1}^{N}\left\{\frac{2 \pi}{\beta_{k}}-\frac{\beta_{k}}{2 \pi}\right\}+O\left(e^{-\epsilon / t}\right), \tag{3.11}
\end{equation*}
$$

as $t \rightarrow 0+$.
3. The counting function, $N(\lambda)$, of the spectrum of $\Delta$ obeys the asymptotics $N(\lambda)=O(\lambda)$ as $\lambda \rightarrow+\infty$.

Proof. 1) The proof of the first statement is a standard exercise (cf. [10]). We indicate only the main idea leaving all the details to the reader. Introduce the closure, $H^{1}(\mathcal{L})$, of the $C_{0}^{\infty}\left(\mathcal{L} \backslash\left\{P_{1}, \ldots, P_{N}\right\}\right.$ with respect to the norm $\|\|u\|\|=\left\|u ; L_{2}\right\|+\left\|\nabla u ; L_{2}\right\|$. It is sufficient to prove that any bounded set $S$ in $H^{1}(\mathcal{L})$ is precompact in $L_{2}$-topology (this will imply the compactness of the self-adjoint operator $(I-\Delta)^{-1}$ ). Moreover, one can assume that the supports of functions from $S$ belong to a small ball $B$ centered at a conical point $P$. Now to prove the precompactness of $S$ it is sufficient to make use of the expansion with respect to eigenfunctions of the Dirichlet problem in $B$ and the diagonal process.
2)Let $\mathcal{L}=\cup_{j=0}^{N} K_{j}$, where $K_{j}, j=1, \ldots, N$ is a neighborhood of the conical point $P_{j}$ which is isometric to $C_{\beta_{j}}(R)$ with some $R>0$, and $K_{0}=\mathcal{L} \backslash \cup_{j=1}^{N} K_{j}$.

Let also $K_{j}^{\epsilon_{1}} \supset K_{j}$ and $K_{j}^{\epsilon_{1}}$ is isometric to $C_{\beta_{j}}\left(R+\epsilon_{1}\right)$ with some $\epsilon_{1}>0$ and $j=1, \ldots, N$.
Fixing $t>0$ and $x, y \in K_{j}$ with $j>0$, one has

$$
\begin{gather*}
\int_{0}^{t} d s \int_{K_{j}^{\epsilon_{1}}}\left(\psi\left\{\Delta_{z}-\partial_{s}\right\} \phi-\phi\left\{\Delta_{z}+\partial_{s}\right\} \psi\right) d z=  \tag{3.12}\\
\int_{0}^{t} d s \int_{\partial K_{j}^{\epsilon_{1}}}\left(\phi \frac{\partial \psi}{\partial n}-\psi \frac{\partial \phi}{\partial n}\right) d l(z)-\int_{K_{j}^{\epsilon_{1}}}(\phi(z, t) \psi(z, t)-\phi(z, 0) \psi(z, 0)) d z
\end{gather*}
$$

with $\phi(z, t)=\mathcal{H}(z, y ; t)-H_{\beta_{j}}(z, y ; t)$ and $\psi(z, t)=H_{\beta_{j}}(z, x ; t-s)$. (Here it is important that we are working with the heat kernel of the Friedrichs extension of the Laplacian, for other extensions the
heat kernel has growing terms in the asymptotics near the vertex and the right hand side of (3.12) gets extra terms.) Therefore,

$$
\begin{gathered}
H_{\beta_{j}}(x, y ; t)-\mathcal{H}(x, y ; t)=\int_{0}^{t} d s \int_{\partial K_{j}^{\epsilon_{1}}}\left(\mathcal{H}(y, z ; s) \frac{\partial H_{\beta_{j}}(x, z ; t-s)}{\partial n(z)}-H_{\beta_{j}}(z, x ; t-s) \frac{\partial \mathcal{H}(z, y ; s)}{\partial n(z)}\right) d l(z) \\
=O\left(e^{-\epsilon_{2} / t}\right)
\end{gathered}
$$

with some $\epsilon_{2}>0$ as $t \rightarrow 0+$ uniformly with respect to $x, y \in K_{j}$. This implies that

$$
\begin{equation*}
\int_{K_{j}} \mathcal{H}(x, x ; t) d x=\int_{K_{j}} H_{\beta_{j}}(x, x ; t) d x+O\left(e^{-\epsilon_{2} / t}\right) . \tag{3.13}
\end{equation*}
$$

Since the metric on $\mathcal{L}$ is flat in a vicinity of $K_{0}$, one has the asymptotics

$$
\int_{K_{0}} \mathcal{H}(x, x ; t) d x=\frac{\operatorname{Area}\left(K_{0}\right)}{4 \pi t}+O\left(e^{-\epsilon_{3} / t}\right)
$$

with some $\epsilon_{3}>0$ (cf. [17]). Now (3.11) follows from (3.5).
3) The third statement of the theorem follows from the second one due to the standard Tauberian arguments.

## 4 Determinant of Laplacian: Analytic surgery and Polyakov's type formulas

Theorem 1 opens a way to define the determinant, $\operatorname{det} \Delta$, of the Laplacian on a compact polyhedral surface via the standard Ray-Singer regularization. Namely introduce the operator $\zeta$-function

$$
\begin{equation*}
\zeta_{\Delta}(s)=\sum_{\lambda_{k}>0} \frac{1}{\lambda_{k}^{s}}, \tag{4.1}
\end{equation*}
$$

where the summation goes over all strictly positive eigenvalues $\lambda_{k}$ of the operator $-\Delta$ (counting multiplicities). Due to the third statement of Theorem 1, the function $\zeta_{\Delta}$ is holomorphic in the half-plane $\{\Re s>1\}$. Moreover, due to the equality

$$
\begin{equation*}
\zeta_{\Delta}(s)=\frac{1}{\Gamma(s)} \int_{0}^{\infty}\left\{\operatorname{Tr} e^{t \Delta}-1\right\} t^{s-1} d t \tag{4.2}
\end{equation*}
$$

and asymptotics (3.11), one has the equality

$$
\begin{equation*}
\zeta_{\Delta}(s)=\frac{1}{\Gamma(s)}\left\{\frac{\operatorname{Area}(\mathcal{L})}{4 \pi(s-1)}+\left[\frac{1}{12} \sum_{k=1}^{N}\left\{\frac{2 \pi}{\beta_{k}}-\frac{\beta_{k}}{2 \pi}\right\}-1\right] \frac{1}{s}+e(s)\right\} \tag{4.3}
\end{equation*}
$$

where $e(s)$ is an entire function. Thus, $\zeta_{\Delta}$ is regular at $s=0$ and one can define the $\zeta$-regularized determinant of the Laplacian via usual $\zeta$-regularization (cf. [21]):

$$
\begin{equation*}
\operatorname{det} \Delta:=\exp \left\{-\zeta_{\Delta}^{\prime}(0)\right\} \tag{4.4}
\end{equation*}
$$

Moreover, (4.3) and the relation $\sum_{k=1}^{N} b_{k}=2 g-2 ; b_{k}=\frac{\beta_{k}}{2 \pi}-1$ yield

$$
\begin{equation*}
\zeta_{\Delta}(0)=\frac{1}{12} \sum_{k=1}^{N}\left\{\frac{2 \pi}{\beta_{k}}-\frac{\beta_{k}}{2 \pi}\right\}-1=\left(\frac{\chi(\mathcal{L})}{6}-1\right)+\frac{1}{12} \sum_{k=1}^{N}\left\{\frac{2 \pi}{\beta_{k}}+\frac{\beta_{k}}{2 \pi}-2\right\} \tag{4.5}
\end{equation*}
$$

where $\chi(\mathcal{L})=2-2 g$ is the Euler characteristics of $\mathcal{L}$.
It should be noted that the term $\frac{\chi(\mathcal{L})}{6}-1$ at the right hand side of (4.5) coincides with the value at zero of the operator $\zeta$-function of the Laplacian corresponding to an arbitrary smooth metric on $\mathcal{L}$ (see, e. g., [20], p. 155).

Let $\mathbf{m}$ and $\tilde{\mathbf{m}}=\kappa \mathbf{m}, \kappa>0$ be two homothetic flat metrics with the same conical points with conical angles $\beta_{1}, \ldots, \beta_{N}$. Then (4.1), (4.4) and (4.5) imply the following rescaling property of the conical Laplacian:

$$
\begin{equation*}
\operatorname{det} \Delta^{\tilde{\mathbf{m}}}=\kappa^{-\left(\frac{\chi(\mathcal{L})}{6}-1\right)-\frac{1}{12} \sum_{k=1}^{N}\left\{\frac{2 \pi}{\beta_{k}}+\frac{\beta_{k}}{2 \pi}-2\right\}} \operatorname{det} \Delta^{\mathbf{m}} \tag{4.6}
\end{equation*}
$$

### 4.1 Analytic surgery

Let $\mathbf{m}$ be an arbitrary smooth metric on $\mathcal{L}$ and denote by $\Delta^{\mathbf{m}}$ the corresponding Laplacian. Consider $N$ nonoverlapping connected and simply connected domains $D_{1}, \ldots, D_{N} \subset \mathcal{L}$ bounded by closed curves $\gamma_{1}, \ldots, \gamma_{N}$ and introduce also the domain $\Sigma=\mathcal{L} \backslash \cup_{k=1}^{N} D_{k}$ and the contour $\Gamma=\cup_{k=1}^{N} \gamma_{k}$.

Define the Neumann jump operator $R: C^{\infty}(\Gamma) \rightarrow C^{\infty}(\Gamma)$ by

$$
\left.R(f)\right|_{\gamma_{k}}=\partial_{\nu}\left(V_{k}^{-}-V_{k}^{+}\right),
$$

where $\nu$ is the outward normal to $\gamma_{k}=\partial D_{k}$, the functions $V_{k}^{-}$and $V^{+}$are the solutions of the boundary value problems $\Delta^{\mathrm{m}} V_{k}^{-}=0$ in $D_{k},\left.V^{-}\right|_{\partial D_{k}}=f$ and $\Delta^{\mathrm{m}} V^{+}=0$ in $\Sigma,\left.V^{+}\right|_{\Gamma}=f$. The Neumann jump operator is an elliptic pseudodifferential operator of order 1, and it is known that one can define its determinant via the standard $\zeta$-regularization.

In what follows it is crucial that the Neumann jump operator does not change if we vary the metric within the same conformal class.

Let $\left(\Delta^{\mathrm{m}} \mid D_{k}\right)$ and $\left(\Delta^{\mathrm{m}} \mid \Sigma\right)$ be the operators of the Dirichlet boundary problem for $\Delta^{\mathrm{m}}$ in domains $D_{k}$ and $\Sigma$ respectively, the determinants of these operators also can be defined via the $\zeta$-regularization.

Due to Theorem $B^{*}$ from [3], we have

$$
\begin{equation*}
\operatorname{det} \Delta^{\mathbf{m}}=\left\{\prod_{k=1}^{N} \operatorname{det}\left(\Delta^{\mathbf{m}} \mid D_{k}\right)\right\} \operatorname{det}\left(\Delta^{\mathbf{m}} \mid \Sigma\right) \operatorname{det} R\{\operatorname{Area}(\mathcal{L}, \mathbf{m})\}\{l(\Gamma)\}^{-1}, \tag{4.7}
\end{equation*}
$$

where $l(\Gamma)$ is the length of the contour $\Gamma$ in the metric $\mathbf{m}$
Remark 2 We have excluded the zero modes of an operator from the definition of its determinant, so we are using the same notation $\operatorname{det} A$ for the determinants of operators $A$ with and without zero modes. In [3] the determinant of an operator $A$ with zero modes is always equal to zero, and what we call here $\operatorname{det} A$ in [3] is called the modified determinant and denoted by $\operatorname{det}^{*} A$. .

Analogous statement holds for flat conical metric. Namely let $\mathcal{L}$ be a compact polyhedral surface with vertices $P_{1}, \ldots, P_{N}$ and $g$ be a corresponding flat metric with conical singularities. Choose the domains $D_{k}, k=1, \ldots, N$ being (open) nonoverlapping disks centered at $P_{k}$ and let $\left(\Delta \mid D_{k}\right)$ be the Friedrichs extension of the Laplacian with domain $C_{0}^{\infty}\left(D_{k} \backslash P_{k}\right)$ in $L_{2}\left(D_{k}\right)$. Then formula (4.7) is still valid with $\Delta^{\mathrm{m}}=\Delta$ (cf. [12] or see recent paper [16] for a more general result).

### 4.2 Polyakov's formula

We state this result in the form given in ([8], p. 62). Let $\mathbf{m}_{0}=\rho_{0}^{-2}(z, \bar{z}) \widehat{d z}$ and $\mathbf{m}_{1}=\rho_{1}^{-2}(z, \bar{z}) \widehat{d z}$ be two smooth conformal metrics on $\mathcal{L}$ and let $\operatorname{det} \Delta^{\mathbf{m}_{0}}$ and $\operatorname{det} \Delta^{\mathbf{m}_{0}}$ be the determinants of the corresponding Laplacians (defined via the standard Ray-Singer regularization). Then

$$
\begin{equation*}
\frac{\operatorname{det} \Delta^{\mathbf{m}_{1}}}{\operatorname{det} \Delta^{\mathbf{m}_{0}}}=\frac{\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{1}\right)}{\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{0}\right)} \exp \left\{\frac{1}{3 \pi} \int_{\mathcal{L}} \log \frac{\rho_{1}}{\rho_{0}} \partial_{z \overline{\mathcal{L}}}^{2} \log \left(\rho_{1} \rho_{0}\right) \widehat{d z}\right\} . \tag{4.8}
\end{equation*}
$$

### 4.3 Analog of Polyakov's formula for a pair of flat conical metrics

Proposition 2 Let $a_{1}, \ldots, a_{M}$ and $b_{1}, \ldots, b_{N}$ be real numbers which are greater than -1 and satisfy $a_{1}+\cdots+a_{M}=b_{1}+\cdots+b_{N}=2 g-2$. Let also $T$ be a connected $C^{1}$-manifold and let

$$
T \ni t \mapsto \mathbf{m}_{1}(t), \quad T \ni t \mapsto \mathbf{m}_{2}(t)
$$

be two $C^{1}$-families of flat conical metrics on $\mathcal{L}$ such that

1. For any $t \in T$ the metrics $\mathbf{m}_{1}(t)$ and $\mathbf{m}_{2}(t)$ define the same conformal structure on $\mathcal{L}$,
2. $\mathbf{m}_{1}(t)$ has conical singularities at $P_{1}(t), \ldots, P_{N}(t) \in \mathcal{L}$ with conical angles $2 \pi\left(b_{1}+1\right), \ldots$, $2 \pi\left(b_{N}+1\right)$.
3. $\mathbf{m}_{2}(t)$ has conical singularities at $Q_{1}(t), \ldots, Q_{M}(t) \in L$ with conical angles $2 \pi\left(a_{1}+1\right), \ldots$, $2 \pi\left(a_{M}+1\right)$,
4. For any $t \in T$ the sets $\left\{P_{1}(t), \ldots, P_{N}(t)\right\}$ and $\left\{Q_{1}(t), \ldots, Q_{M}(t)\right\}$ do not intersect.

Let $x_{k}$ be distinguished local parameter for $\mathbf{m}_{1}$ near $P_{k}$ and $y_{l}$ be distinguished local parameter for $\mathbf{m}_{2}$ near $Q_{l}$ (we omit the argument $t$ ).

Introduce the functions $f_{k}, g_{l}$ and the complex numbers $\mathbf{f}_{\mathbf{k}}, \mathbf{g}_{\mathbf{1}}$ by

$$
\begin{aligned}
\mathbf{m}_{2}=\left|f_{k}\left(x_{k}\right)\right|^{2}\left|d x_{k}\right|^{2} \quad \text { near } \quad P_{k} ; & \mathbf{f}_{\mathbf{k}}:=f_{k}(0) \\
\mathbf{m}_{1}=\left|g_{l}\left(y_{l}\right)\right|^{2}\left|d y_{l}\right|^{2} \quad \text { near } \quad Q_{l} ; & \mathbf{g}_{1}:=g_{l}(0)
\end{aligned}
$$

Then the following equality holds true

$$
\begin{equation*}
\frac{\operatorname{det} \Delta^{\mathbf{m}_{1}}}{\operatorname{det} \Delta^{\mathbf{m}_{2}}}=C \frac{\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{1}\right)}{\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{2}\right)} \frac{\prod_{l=1}^{M}\left|\mathbf{g}_{\mathbf{l}}\right|^{a_{l} / 6}}{\prod_{k=1}^{N}\left|\mathbf{f}_{\mathbf{k}}\right|^{b_{k} / 6}}, \tag{4.9}
\end{equation*}
$$

where the constant $C$ is independent of $t \in T$.
Proof. Take $\epsilon>0$ and introduce the disks $D_{k}(\epsilon), k=1, \ldots, M+N$ centered at the points $P_{1}, \ldots, P_{N}$, $Q_{1}, \ldots, Q_{M} ; D_{k}(\epsilon)=\left\{\left|x_{k}\right| \leq \epsilon\right\}$ for $k=1, \ldots, N$ and $D_{N+l}=\left\{\left|y_{l}\right| \leq \epsilon\right\}$ for $l=1, \ldots, M$. Let $h_{k}: \mathbb{R}_{+} \rightarrow \mathbb{R}, k=1, \ldots, N+M$ be smooth positive functions such that
1.

$$
\int_{0}^{1} h_{k}^{2}(r) r d r= \begin{cases}\int_{0}^{1} r^{2 b_{k}+1} d r=\frac{1}{2 b_{k}+2}, & \text { if } k=1, \ldots, N \\ \int_{0}^{1} r^{2 a_{l}+1} d r=\frac{1}{2 a_{l}+2}, & \text { if } k=N+l, l=1, \ldots, M\end{cases}
$$

2. 

$$
h_{k}(r)=\left\{\begin{array}{ll}
r^{b_{k}} & \text { for } r \geq 1 \text { if } k=1, \ldots, N \\
r^{a_{l}} & \text { for } r \geq 1
\end{array} \text { if } k=N+l, l=1, \ldots, M ~ \$ ~ l\right.
$$

Define two families of smooth metrics $\mathbf{m}_{1}^{\epsilon}, \mathbf{m}_{2}^{\epsilon}$ on $\mathcal{L}$ via

$$
\begin{gathered}
\mathbf{m}_{1}^{\epsilon}(z)= \begin{cases}\epsilon^{2 b_{k}} h_{k}^{2}\left(\left|x_{k}\right| / \epsilon\right)\left|d x_{k}\right|^{2}, & z \in D_{k}(\epsilon), \quad k=1, \ldots, N \\
\mathbf{m}(z), & z \in \mathcal{L} \backslash \cup_{k=1}^{N} D_{k}(\epsilon),\end{cases} \\
\mathbf{m}_{2}^{\epsilon}(z)=\left\{\begin{array}{l}
\epsilon^{2 a_{k}} h_{N+l}^{2}\left(\left|y_{l}\right| / \epsilon\right)\left|d y_{l}\right|^{2}, \quad z \in D_{N+l}(\epsilon), \quad l=1, \ldots, M \\
\mathbf{m}(z), \\
\cup_{l=1}^{M} D_{N+l}(\epsilon) .
\end{array}\right.
\end{gathered}
$$

The metrics $\mathbf{m}_{1,2}^{\epsilon}$ converge to $\mathbf{m}_{1,2}$ as $\epsilon \rightarrow 0$ and

$$
\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{1,2}^{\epsilon}\right)=\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{1,2}\right)
$$

Lemma 1 Let $\partial_{t}$ be the differentiation with respect to one of the coordinates on $T$ and let $\operatorname{det} \Delta^{\mathbf{m}_{1,2}}$ be the standard $\zeta$-regularized determinant of the Laplacian corresponding to the smooth metric $\mathbf{m}_{1,2}^{\epsilon}$. Then

$$
\begin{equation*}
\partial_{t} \log \operatorname{det} \Delta^{\mathbf{m}_{1,2}}=\partial_{t} \log \operatorname{det} \Delta^{\mathbf{m}_{1,2}^{\epsilon}} \tag{4.10}
\end{equation*}
$$

To establish the lemma consider for definiteness the pair $\mathbf{m}_{1}$ and $\mathbf{m}_{1}(\epsilon)$. Due to the analytic surgery formulas from section 4.1 one has

$$
\begin{align*}
& \operatorname{det} \Delta^{\mathbf{m}_{1}}=\left\{\prod_{k=1}^{N} \operatorname{det}\left(\Delta^{\mathbf{m}_{1}} \mid D_{k}(\epsilon)\right)\right\} \operatorname{det}\left(\Delta^{\mathbf{m}_{1}} \mid \Sigma\right) \operatorname{det} R\left\{\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{1}\right)\right\}\{l(\Gamma)\}^{-1},  \tag{4.11}\\
& \operatorname{det} \Delta^{\mathbf{m}_{1}^{\epsilon}}=\left\{\prod_{k=1}^{N} \operatorname{det}\left(\Delta^{\mathbf{m}_{1}^{\epsilon}} \mid D_{k}(\epsilon)\right)\right\} \operatorname{det}\left(\Delta^{\mathbf{m}_{1}^{\epsilon}} \mid \Sigma\right) \operatorname{det} R\left\{\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{1}^{\epsilon}\right)\right\}\{l(\Gamma)\}^{-1}, \tag{4.12}
\end{align*}
$$

with $\Sigma=\mathcal{L} \backslash \cup_{k=1}^{N} D_{k}(\epsilon)$.
Notice that the variations of the logarithms of the first factors in right hand sides of (4.11) and (4.12) vanish (these factors are independent of $t$ ) whereas the variations of logarithms of all the remaining factors coincide. This leads to (4.10).

By virtue of Lemma 1 one has the relation

$$
\begin{equation*}
\partial_{t}\left\{\log \frac{\operatorname{det} \Delta^{\mathbf{m}_{1}}}{\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{1}\right)}-\log \frac{\operatorname{det} \Delta^{\mathbf{m}_{2}}}{\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{2}\right)}\right\}=\partial_{t}\left\{\log \frac{\operatorname{det} \Delta^{\mathbf{m}_{1}^{\epsilon}}}{\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{1}^{\epsilon}\right)}-\log \frac{\operatorname{det} \Delta^{\mathbf{m}_{2}^{\epsilon}}}{\operatorname{Area}\left(\mathcal{L}, \mathbf{m}_{2}^{\epsilon}\right)}\right\} . \tag{4.13}
\end{equation*}
$$

By virtue of Polyakov's formula the r. h. s. of (4.13) can be rewritten as

$$
\begin{equation*}
\sum_{k=1}^{N} \frac{1}{3 \pi} \partial_{t} \int_{D_{k}(\epsilon)}\left(\log H_{k}\right)_{x_{k} \bar{x}_{k}} \log \left|f_{k}\right| \widehat{d x_{k}}-\sum_{l=1}^{M} \frac{1}{3 \pi} \partial_{t} \int_{D_{N+l}(\epsilon)}\left(\log H_{N+l}\right)_{y_{l}, \bar{y}_{l}} \log \left|g_{l}\right| \widehat{d y_{l}}, \tag{4.14}
\end{equation*}
$$

where $H_{k}\left(x_{k}\right)=\epsilon^{-b_{k}} h_{k}^{-1}\left(\left|x_{k}\right| / \epsilon\right), k=1, \ldots, N$ and $H_{N+l}\left(y_{l}\right)=\epsilon^{-a_{l}} h_{N+l}^{-1}\left(\left|y_{l}\right| / \epsilon\right), l=1, \ldots, M$. Notice that for $k=1, \ldots, N$ the function $H_{k}$ coincides with $\left|x_{k}\right|^{-b_{k}}$ in a vicinity of the circle $\left\{\left|x_{k}\right|=\epsilon\right\}$ and the Green formula implies that

$$
\int_{D_{k}(\epsilon)}\left(\log H_{k}\right)_{x_{k} \bar{x}_{k}} \log \left|f_{k}\right| \widehat{d w_{k}}=\frac{i}{2}\left\{\oint_{\left|x_{k}\right|=\epsilon}\left(\log \left|x_{k}\right|^{-b_{k}}\right)_{\bar{x}_{k}} \log \left|f_{k}\right| d \bar{x}_{k}+\right.
$$

$$
\left.+\oint_{\left|x_{k}\right|=\epsilon} \log \left|x_{k}\right|^{-b_{k}}\left(\log \left|f_{k}\right|\right)_{x_{k}} d x_{k}+\int_{D_{k}(\epsilon)}\left(\log \left|f_{k}\right|\right)_{x_{k} \bar{x}_{k}} \log H_{k} d x_{k} \wedge d \bar{x}_{k}\right\}
$$

and, therefore,

$$
\begin{equation*}
\partial_{t} \int_{D_{k}(\epsilon)}\left(\log H_{k}\right)_{x_{k} \bar{x}_{k}} \log \left|f_{k}\right| \widehat{d x_{k}}=-\frac{b_{k} \pi}{2} \partial_{t} \log \left|\mathbf{f}_{k}\right|+o(1) \tag{4.15}
\end{equation*}
$$

as $\epsilon \rightarrow 0$. Analogously

$$
\begin{equation*}
\partial_{t} \int_{D_{N+l}(\epsilon)}\left(\log H_{N+l}\right)_{y_{l} \bar{y}_{l}} \log \left|g_{l}\right| \widehat{d y_{l}}=-\frac{a_{k} \pi}{2} \partial_{t} \log \left|\mathbf{g}_{l}\right|+o(1) \tag{4.16}
\end{equation*}
$$

as $\epsilon \rightarrow 0$.
Formula (4.9) follows from (4.13), (4.15) and (4.16).

## 5 Polyhedral tori

Here we establish a formula for the determinant of the Laplacian on a polyhedral torus, i. e. a Riemann surface of genus one with flat conical metric. We do it comparing this determinant with the determinant of the Laplacian corresponding to the smooth flat metric on the same torus. For the latter Laplacian the spectrum is easy to find and the determinant is explicitly known (it is given by Ray-Singer formula stated below).

In this section $\mathcal{L}$ is an elliptic curve and it is assumed that $\mathcal{L}$ is the quotient of the complex plane $\mathbb{C}$ by the lattice generated by 1 and $\sigma$, where $\Im \sigma>0$. The differential $d z$ on $\mathbb{C}$ gives rise to a holomorphic differential $v_{0}$ on $\mathcal{L}$ with periods 1 and $\sigma$.

### 5.0.1 Ray-Singer formula

Let $\Delta$ be the Laplacian on $\mathcal{L}$ corresponding to the flat smooth metric $\left|v_{0}\right|^{2}$. The following formula for $\operatorname{det} \Delta$ was proved in [21]:

$$
\begin{equation*}
\operatorname{det} \Delta=C|\Im \sigma|^{2}|\eta(\sigma)|^{4} \tag{5.1}
\end{equation*}
$$

where $C$ is a $\sigma$-independent constant and $\eta$ is the Dedekind eta-function.

### 5.1 Determinant of the Laplacian on a polyhedral torus

Let $\sum_{k=1}^{N} b_{k} P_{k}$ be a generalized divisor on $\mathcal{L}$ with $\sum_{k=1}^{N} b_{k}=0$ and assume that $b_{k}>-1$ for all $k$. Let $\mathbf{m}$ be a flat conical metric corresponding to this divisor via Troyanov's theorem. Clearly, it has a finite area and is defined uniquely when this area is fixed. Fixing numbers $b_{1}, \ldots, b_{N}>-1$ such that $\sum_{k=1}^{N} b_{k}=0$, we define the space $\mathcal{M}\left(b_{1}, \ldots, b_{N}\right)$ as the moduli space of pairs $(\mathcal{L}, \mathbf{m})$, where $\mathcal{L}$ is an elliptic curve and $\mathbf{m}$ is a flat conformal metric on $\mathcal{L}$ having $N$ conical singularities with conical angles $2 \pi\left(b_{k}+1\right), k=1, \ldots, N$. The space $\mathcal{M}\left(b_{1}, \ldots, b_{N}\right)$ is a connected orbifold of the real dimension $2 N+3$.

We are going to give an explicit formula for the function

$$
\mathcal{M}\left(\beta_{1}, \ldots, \beta_{N}\right) \ni(\mathcal{L}, \mathbf{m}) \mapsto \operatorname{det} \Delta^{\mathrm{m}}
$$

Write the normalized holomorphic differential $v_{0}$ on the elliptic curve $\mathcal{L}$ in the distinguished local parameter $x_{k}$ near the conical point $P_{k}(k=1, \ldots, N)$ as

$$
v_{0}=f_{k}\left(x_{k}\right) d x_{k}
$$

and define

$$
\begin{equation*}
\mathbf{f}_{k}:=\left.f_{k}\left(x_{k}\right)\right|_{x_{k}=0}, k=1, \ldots, N . \tag{5.2}
\end{equation*}
$$

Theorem 2 The following formula holds true

$$
\begin{equation*}
\operatorname{det} \Delta^{\mathrm{m}}=C|\Im \sigma| \operatorname{Area}(\mathcal{L}, \mathbf{m})|\eta(\sigma)|^{4} \prod_{k=1}^{N}\left|\mathbf{f}_{k}\right|^{-b_{k} / 6} \tag{5.3}
\end{equation*}
$$

where $C$ is a constant depending only on $b_{1}, \ldots, b_{N}$.
Proof. The theorem immediately follows from (5.1) and (4.9).

## 6 Polyhedral surfaces of higher genus

Here we generalize the results of the previous section to the case of polyhedral surfaces of an arbitrary genus. Among all polyhedral surfaces of genus $g \geq 1$ we distinguish flat surfaces with trivial holonomy. In our calculation of the determinant of the Laplacian it is this class of surfaces which plays the role played in genus one by smooth flat tori. For flat surfaces with trivial holonomy we find an explicit expression for the determinant of the Laplacian which generalizes the Ray-Singer formula (5.1) for smooth flat tori. Then, as we did in genus one, comparing two determinants of the Laplacians by means of Proposition 2, we derive a formula for the determinant of the Laplacian on a general polyhedral surface.

### 6.1 Flat surfaces with trivial holonomy and moduli spaces of holomorphic differentials on Riemann surfaces

We follow [14] and Zorich's survey [24]. Outside the vertices a Euclidean polyhedral surface $\mathcal{L}$ is locally isometric to a Euclidean plane and one can define the parallel transport along paths on the punctured surface $\mathcal{L} \backslash\left\{P_{1}, \ldots, P_{N}\right\}$. The parallel transport along a homotopically nontrivial loop in $\mathcal{L} \backslash\left\{P_{1}, \ldots, P_{N}\right\}$ is generally nontrivial. If, e. g., a small loop encircles a conical point $P_{k}$ with conical angle $\beta_{k}$ then a tangent vector to $\mathcal{L}$ turns by $\beta_{k}$ after the parallel transport along this loop.

A Euclidean polyhedral surface $\mathcal{L}$ is called $a$ surface with trivial holonomy if the parallel transport along any loop in $\mathcal{L} \backslash\left\{P_{1}, \ldots, P_{N}\right\}$ does not change tangent vectors to $\mathcal{L}$.

All the conical points of a surface with trivial holonomy must have conical angles which are integer multiples of $2 \pi$.

A flat conical metric $g$ on a compact real oriented two-dimensional manifold $\mathcal{L}$ provides $\mathcal{L}$ with the structure of a compact Riemann surface, if this metric has trivial holonomy then it necessarily has the form $g=|w|^{2}$, where $w$ is a holomorphic differential on the Riemann surface $\mathcal{L}$ (see [24]). The holomorphic differential $w$ has zeros at the conical points of the metric $g$. The multiplicity of the zero at the point $P_{m}$ with the conical angle $2 \pi\left(k_{m}+1\right)$ is equal to $k_{m}{ }^{1}$.

The holomorphic differential $w$ is defined up to a unitary complex factor, this ambiguity can be avoided if the surface $\mathcal{L}$ is provided with a distinguished direction (see [24]) and it is assumed that $w$

[^1]is real along this distinguished direction. In what follows we always assume that surfaces with trivial holonomy are provided with such a direction.

Thus, to a Euclidean polyhedral surface of genus $g$ with trivial holonomy we put into correspondence a pair $(\mathcal{L}, w)$, where $\mathcal{L}$ is a compact Riemann surface and $\omega$ is a holomorphic differential on this surface. This means that we get an element of the moduli space, $\mathcal{H}_{g}$, of holomorphic differentials over Riemann surfaces of genus $g$ (see [14]).

The space $\mathcal{H}_{g}$ is stratified according to the multiplicities of zeros of $w$.
Denote by $\mathcal{H}_{g}\left(k_{1}, \ldots, k_{M}\right)$ the stratum of $\mathcal{H}_{g}$, consisting of differentials $w$ which have $M$ zeros on $\mathcal{L}$ of multiplicities $\left(k_{1}, \ldots, k_{M}\right)$. Denote the zeros of $w$ by $P_{1}, \ldots, P_{M}$; then the divisor of differential $w$ is given by $(w)=\sum_{m=1}^{M} k_{m} P_{m}$. Let us choose a canonical basic of cycles ( $a_{\alpha}, b_{\alpha}$ ) on the Riemann surface $\mathcal{L}$ and cut $\mathcal{L}$ along these cycles starting at the same point to get the fundamental polygon $\hat{\mathcal{L}}$. Inside of $\hat{\mathcal{L}}$ we choose $M-1$ ( homology classes of) paths $l_{m}$ on $\mathcal{L} \backslash(w)$ connecting the zero $P_{1}$ with other zeros $P_{m}$ of $w, m=2, \ldots, M$. Then the local coordinates on $\mathcal{H}_{g}\left(k_{1}, \ldots, k_{M}\right)$ can be chosen as follows [15]:

$$
\begin{equation*}
A_{\alpha}:=\oint_{a_{\alpha}} w, \quad B_{\alpha}:=\oint_{b_{\alpha}} w, \quad z_{m}:=\int_{l_{m}} w, \quad \alpha=1, \ldots, g ; m=2, \ldots, M . \tag{6.1}
\end{equation*}
$$

The area of the surface $\mathcal{L}$ in the metric $|w|^{2}$ can be expressed in terms of these coordinates as follows:

$$
\operatorname{Vol}(\mathcal{L})=\Im \sum_{\alpha=1}^{g} A_{\alpha} \overline{B_{\alpha}} .
$$

If all zeros of $w$ are simple, we have $M=2 g-2$; therefore, the dimension of the highest stratum $\mathcal{H}_{g}(1, \ldots, 1)$ equals $4 g-3$.

The Abelian integral $z(P)=\int_{P_{1}}^{P} w$ provides a local coordinate in a neighborhood of any point $P \in \mathcal{L}$ except the zeros $P_{1}, \ldots, P_{M}$. In a neighborhood of $P_{m}$ the local coordinate can be chosen to be $\left(z(P)-z_{m}\right)^{1 /\left(k_{m}+1\right)}$.

Remark 3 The following construction helps to visualize these coordinates in the case of the highest stratum $H_{g}(1, \ldots, 1)$.

Consider $g$ parallelograms $\Pi_{1}, \ldots, \Pi_{g}$ in the complex plane with coordinate $z$ having the sides $\left(A_{1}, B_{1}\right), \ldots,\left(A_{g}, B_{g}\right)$. Provide these parallelograms with a system of cuts

$$
\left[0, z_{2}\right], \quad\left[z_{3}, z_{4}\right], \quad \ldots, \quad\left[z_{2 g-3}, z_{2 g-2}\right]
$$

(each cut should be repeated on two different parallelograms). Identifying the opposite sides of the parallelograms and gluing the obtained $g$ tori along the cuts we get a compact Riemann surface $\mathcal{L}$ of genus $g$. Moreover, the differential $d z$ on the complex plane gives rise to a holomorphic differential $w$ on $\mathcal{L}$ which has $2 g-2$ zeros at the ends of the cuts. Thus, we get a point $(\mathcal{L}, w)$ from $\mathcal{H}_{g}(1, \ldots, 1)$. It can be shown that any generic point of $\mathcal{H}_{g}(1, \ldots, 1)$ can be obtained via this construction; more sophisticated gluing is required to represent points of other strata, or non generic points of the stratum $\mathcal{H}_{g}(1, \ldots, 1)$.

To shorten the notations it is convenient to consider the coordinates $\left\{A_{\alpha}, B_{\alpha}, z_{m}\right\}$ altogether. Namely, in the sequel we shall denote them by $\zeta_{k}, k=1, \ldots, 2 g+M-1$, where

$$
\begin{equation*}
\zeta_{\alpha}:=A_{\alpha}, \quad \zeta_{g+\alpha}:=B_{\alpha}, \quad \alpha=1, \ldots, g, \quad \zeta_{2 g+m}:=z_{m+1} \quad m=1, \ldots, M-1 \tag{6.2}
\end{equation*}
$$

Let us also introduce corresponding cycles $s_{k}, k=1, \ldots, 2 g+M-1$, as follows:

$$
\begin{equation*}
s_{\alpha}=-b_{\alpha}, \quad s_{g+\alpha}=a_{\alpha}, \quad \alpha=1, \ldots, g ; \tag{6.3}
\end{equation*}
$$

the cycle $s_{2 g+m}, m=1, \ldots, M-1$ is defined to be the small circle with positive orientation around the point $P_{m+1}$.

### 6.1.1 Variational formulas on the spaces of holomorphic differentials

In the previous section we introduced the coordinates on the space of surfaces with trivial holonomy and fixed type of conical singularities. Here we study the behavior of basic objects on these surfaces under the change of the coordinates. In particular, we derive variational formulas of the Rauch type for the matrix of b-periods of the underlying Riemann surfaces. We also give variational formulas for the Green function, individual eigenvalues, and the determinant of the Laplacian on these surfaces.

Rauch formulas on the spaces of holomorphic differentials. For any compact Riemann surface $\mathcal{L}$ we introduce the prime-form $E(P, Q)$ and the canonical meromorphic bidifferential

$$
\begin{equation*}
\mathbf{w}(P, Q)=d_{P} d_{Q} \log E(P, Q) \tag{6.4}
\end{equation*}
$$

(see [8]). The bidifferential $\mathbf{w}(P, Q)$ has the following local behavior as $P \rightarrow Q$ :

$$
\begin{equation*}
\mathbf{w}(P, Q)=\left(\frac{1}{(x(P)-x(Q))^{2}}+\frac{1}{6} S_{B}(x(P))+o(1)\right) d x(P) d x(Q) \tag{6.5}
\end{equation*}
$$

where $x(P)$ is a local parameter. The term $S_{B}(x(P))$ is a projective connection which is called the Bergman projective connection (see [8]).

Denote by $v_{\alpha}(P)$ the basis of holomorphic 1-forms on $\mathcal{L}$ normalized by $\int_{a_{\alpha}} v_{\beta}=\delta_{\alpha \beta}$.
The matrix of $\mathbf{b}$-periods of the surface $\mathcal{L}$ is given by $\mathbf{B}_{\alpha \beta}:=\oint_{b_{\alpha}} v_{\beta}$.
Proposition 3 Let a pair $(\mathcal{L}, w)$ belong to the space $\mathcal{H}_{g}\left(k_{1}, \ldots, k_{M}\right)$. Under variations of the coordinates on $\mathcal{H}_{g}\left(k_{1}, \ldots, k_{M}\right)$ the normalized holomorphic differentials and the matrix of $\mathbf{b}$-periods of the surface $\mathcal{L}$ behaves as follows:

$$
\begin{gather*}
\left.\frac{\partial v_{\alpha}(P)}{\partial \zeta_{k}}\right|_{z(P)}=\frac{1}{2 \pi i} \oint_{s_{k}} \frac{v_{\alpha}(Q) \mathbf{w}(P, Q)}{w(Q)},  \tag{6.6}\\
\frac{\partial \mathbf{B}_{\alpha \beta}}{\partial \zeta_{k}}=\oint_{s_{k}} \frac{v_{\alpha} v_{\beta}}{w} \tag{6.7}
\end{gather*}
$$

where $k=1, \ldots, 2 g+M-1$; we assume that the local coordinate $z(P)=\int_{P_{1}}^{P} w$ is kept constant under differentiation.

We sketch a proof for $k=g+1, \ldots 2 g$. Consider some point $P_{0} \in \mathcal{L}$ such that $z_{0}:=z\left(P_{0}\right)$ is independent of the moduli $\left\{A_{\beta}, B_{\beta}, z_{m}\right\}$. Let us dissect the surface $\mathcal{L}$ along the basic cycles started at $P_{0}$ to get the fundamental polygon $\hat{\mathcal{L}}$. Denote the images of the different shores of the basic cycles in $z$-plane by $a_{\beta}^{-}, a_{\beta}^{+}, b_{\beta}^{-}$and $b_{\beta}^{+}$. The endpoints of these contours coincide with the points $z_{0}, z_{0}+A_{\beta}$, $z_{0}+B_{\beta}$ and $z_{0}+A_{\beta}+B_{\beta}$. Let us write down the differential $v_{\alpha}$ in terms of the local parameter $z$ as follows: $v_{\alpha}(P)=f_{\alpha}(z) d z$, where $z=z(P)$.

The function $f_{\alpha}(z)$ is the same on the different shores of the cuts $a_{\beta}^{-}$and $a_{\beta}^{+}$i.e. $f_{\alpha}\left(z+B_{\beta}\right)=f_{\alpha}(z)$ for $z \in a_{\beta}^{-}$. Differentiating this relation with respect to $B_{\beta}$, we get

$$
\frac{\partial f_{\alpha}}{\partial B_{\beta}}\left(z+B_{\beta}\right)=\frac{\partial f_{\alpha}}{\partial B_{\beta}}(z)-\frac{\partial f_{\alpha}}{\partial z}(z) ;
$$

obviously, this is the only discontinuity of the differential $\left.\frac{\partial v_{\alpha}(P)}{\partial B_{\beta}}\right|_{z(P)}$ on $\mathcal{L}$. Therefore, the differential $\left.\frac{\partial v_{\alpha}(P)}{\partial B_{\beta}}\right|_{z(P)}$ has all vanishing $a$-periods and the jump $-\frac{\partial f_{\alpha}}{\partial z}(z(P)) d z(P)$ on the contour $a_{\beta}^{-}$; outside of the cycle $a_{\beta}$ this differential is holomorphic (in other words, it solves the scalar Riemann-Hilbert problem on the contour $a_{\beta}$ ). Such a differential can be easily written (see, e.g., [25]) in terms of the canonical bidifferential $\mathbf{w}(P, Q)$ as a contour integral over $a_{\beta}$ as in (6.6) (in terms of coordinate $z(P)$ we have $w(Q)=d z(Q))$. Now to get (6.7) one has to integrate (6.6) over the $b$-cycles, change the order of integration and make use of the relation

$$
\int_{\mathbf{b}_{j}} \mathbf{w}(P, \cdot)=2 \pi i v_{j}(P) .
$$

Variation of the resolvent kernel and eigenvalues. For a pair $(\mathcal{L}, w)$ from $\mathcal{H}_{g}\left(k_{1}, \ldots, k_{M}\right)$ introduce the Laplacian $\Delta:=\Delta^{|w|^{2}}$ in flat conical metric $|w|^{2}$ on $\mathcal{L}$ (recall that we always deal with the Friedrichs extensions). The corresponding resolvent kernel $G(P, Q ; \lambda), \lambda \in \mathbb{C} \backslash \operatorname{sp}(\Delta)$

- satisfies $\left(\Delta_{P}-\lambda\right) G(P, Q ; \lambda)=\left(\Delta_{Q}-\lambda\right) G(P, Q ; \lambda)=0$ outside the diagonal $\{P=Q\}$,
- is bounded near the conical points i. e. for any $P \in \mathcal{L} \backslash\left\{P_{1}, \ldots, P_{M}\right\}$

$$
G(P, Q ; \lambda)=O(1)
$$

as $Q \rightarrow P_{k}, k=1, \ldots, M$,

- obeys the asymptotics

$$
G(P, Q ; \lambda)=\frac{1}{2 \pi} \log |x(P)-x(Q)|+O(1)
$$

as $P \rightarrow Q$, where $x(\cdot)$ is an arbitrary (holomorphic) local parameter near $P$.
The following proposition is an analog of the classical Hadamard formula for the variation of the Green function of the Dirichlet problem in a plane domain.

Proposition 4 There are the following variational formulas for the resolvent kernel $G(P, Q ; \lambda)$ :

$$
\begin{gather*}
\frac{\partial G(P, Q ; \lambda)}{\partial A_{\alpha}}=2 i \int_{b_{\alpha}} \omega(P, Q ; \lambda)  \tag{6.8}\\
\frac{\partial G(P, Q ; \lambda)}{\partial B_{\alpha}}=-2 i \int_{a_{\alpha}} \omega(P, Q ; \lambda), \tag{6.9}
\end{gather*}
$$

where

$$
\omega(P, Q ; \lambda)=G(P, z ; \lambda) G_{z \bar{z}}(Q, z ; \lambda) \bar{d} z+G_{z}(P, z ; \lambda) G_{z}(Q, z ; \lambda) d z
$$

is a closed 1 -form and $\alpha=1, \ldots, g$;

$$
\begin{equation*}
\frac{\partial G(P, Q ; \lambda)}{\partial z_{m}}=-2 i \lim _{\epsilon \rightarrow 0} \oint_{\left|z-z_{m}\right|=\epsilon} G_{z}(z, P ; \lambda) G_{z}(z, Q ; \lambda) d z \tag{6.10}
\end{equation*}
$$

where $m=2, \ldots, M$. It is assumed that the coordinates $z(P)$ and $z(Q)$ are kept constant under variation of the moduli $A_{\alpha}, B_{\alpha}, z_{m}$.

Remark 4 One can unite the formulas (6.8-6.10) in a single formula:

$$
\begin{equation*}
\frac{\partial G(P, Q ; \lambda)}{\partial \zeta_{k}}=-2 i\left\{\int_{s_{k}} \frac{G(R, P ; \lambda) \partial_{R} \overline{\partial_{R}} G(R, Q ; \lambda)+\partial_{R} G(R, P ; \lambda) \partial_{R} G(R, Q ; \lambda)}{w(R)}\right\} \tag{6.11}
\end{equation*}
$$

where $k=1, \ldots, 2 \mathrm{~g}+\mathrm{M}-1$.
Proof. We start with the following integral representation of a solution $u$ to the homogeneous equation $\Delta u-\lambda u=0$ inside the fundamental polygon $\hat{\mathcal{L}}$ :

$$
\begin{equation*}
u(\xi, \bar{\xi})=-2 i \int_{\partial \hat{\mathcal{L}}} G(z, \bar{z}, \xi, \bar{\xi} ; \lambda) u_{\bar{z}}(z, \bar{z}) d \bar{z}+G_{z}(z, \bar{z}, \xi, \bar{\xi} ; \lambda) u(z, \bar{z}) d z \tag{6.12}
\end{equation*}
$$

Cutting the surface $\mathcal{L}$ along the basic cycles, we notice that the function $\dot{G}(P, \cdot ; \lambda)=\frac{\partial G(P, \cdot ; \lambda)}{\partial B_{\beta}}$ is a solution to the homogeneous equation $\Delta u-\lambda u=0$ inside the fundamental polygon (the singularity of $G(P, Q ; \lambda)$ at $Q=P$ disappears after differentiation) and that the functions $G(P, \cdot ; \lambda)$ and $G_{\bar{z}}(P, \cdot ; \lambda)$ have the jumps $G_{z}(P, \cdot ; \lambda)$ and $G_{z \bar{z}}(P, \cdot ; \lambda)$ on the cycle $\mathbf{a}_{\beta}$. Applying (6.12) with $u=\dot{G}(P, \cdot ; \lambda)$, we get (6.9). Formula (6.8) can be proved in the same manner.

The relation $d \omega(P, Q ; \lambda)=0$ immediately follows from the equality $G_{z \bar{z}}(z, \bar{z}, P ; \lambda)=\frac{\lambda}{4} G(z, \bar{z}, P ; \lambda)$.
Let us prove (6.10). From now on we assume for simplicity that $k_{m}=1$, where $k_{m}$ is the multiplicity of the zero $P_{m}$ of the holomorphic differential $w$.

Applying Green formula (6.12) to the domain $\hat{\mathcal{L}} \backslash\left\{\left|z-z_{m}\right|<\epsilon\right\}$ and $u=\dot{G}=\frac{\partial G}{\partial z_{m}}$, one gets

$$
\begin{equation*}
\dot{G}(P, Q ; \lambda)=2 i \lim _{\epsilon \rightarrow 0} \oint_{\left|z-z_{m}\right|=\epsilon} \dot{G}_{\bar{z}}(z, \bar{z}, Q ; \lambda) G(z, \bar{z}, P ; \lambda) \bar{d} z+\dot{G}(z, \bar{z}, Q ; \lambda) G_{z}(z, \bar{z}, P ; \lambda) d z . \tag{6.13}
\end{equation*}
$$

Observe that the function $x_{m} \mapsto G\left(x_{m}, \bar{x}_{m}, P ; \lambda\right)$ (defined in a small neighborhood of the point $x_{m}=0$ ) is a bounded solution to the elliptic equation

$$
\frac{\partial^{2} G\left(x_{m}, \bar{x}_{m}, P ; \lambda\right)}{\partial x_{m} \partial \bar{x}_{m}}-\lambda\left|x_{m}\right|^{2} G\left(x_{m}, \bar{x}_{m}, P ; \lambda\right)=0
$$

with real analytic coefficients and, therefore, is real analytic near $x_{m}=0$.
From now on we write $x$ instead of $x_{m}=\sqrt{z-z_{m}}$. Differentiating the expansion

$$
\begin{equation*}
G(x, \bar{x}, P ; \lambda)=a_{0}(P, \lambda)+a_{1}(P, \lambda) x+a_{2}(P, \lambda) \bar{x}+a_{3}(P, \lambda) x \bar{x}+\ldots \tag{6.14}
\end{equation*}
$$

with respect to $z_{m}, z$ and $\bar{z}$, one gets the asymptotics

$$
\begin{gather*}
\dot{G}(z, \bar{z}, Q ; \lambda)=-\frac{a_{1}(Q, \lambda)}{2 x}+O(1),  \tag{6.15}\\
\dot{G}_{\bar{z}}(z, \bar{z}, Q ; \lambda)=\frac{\dot{a}_{2}(Q, \lambda)}{2 \bar{x}}-\frac{a_{3}(Q, \lambda)}{4 x \bar{x}}+O(1), \tag{6.16}
\end{gather*}
$$

$$
\begin{equation*}
G_{z}(z, \bar{z}, P ; \lambda)=\frac{a_{1}(P, \lambda)}{2 x}+O(1) \tag{6.17}
\end{equation*}
$$

Substituting (6.15), (6.16) and (6.17) into (6.13), we get the relation

$$
\dot{G}(P, Q, \lambda)=2 \pi a_{1}(P, \lambda) a_{1}(Q, \lambda)
$$

On the other hand, calculation of the right hand side of formula (6.10) via (6.17) leads to the same result.

Now we give a variation formula for an eigenvalue of the Laplacian on a flat surface with trivial holonomy.

Proposition 5 Let $\lambda$ be an eigenvalue of $\Delta$ (for simplicity we assume it to have multiplicity one) and let $\phi$ be the corresponding normalized eigenfunction. Then

$$
\begin{equation*}
\frac{\partial \lambda}{\partial \zeta_{k}}=2 i \int_{s_{k}}\left(\frac{(\partial \phi)^{2}}{w}+\frac{1}{4} \lambda \phi^{2} \bar{w}\right) \tag{6.18}
\end{equation*}
$$

where $k=1, \ldots, 2 g+M-1$.
Proof. For brevity we give the proof only for the case $k=g+1, \ldots, 2 g$. One has

$$
\begin{aligned}
\iint_{\hat{L}} \phi \dot{\phi}= & \frac{1}{\lambda} \iint_{\hat{\mathcal{L}}} \Delta \phi \dot{\phi}=\frac{1}{\lambda}\left\{2 i \int_{\partial \hat{\mathcal{L}}}\left(\phi_{\bar{z}} \dot{\phi} d \bar{z}+\phi \dot{\phi}_{z} d z\right)+\iint_{\hat{\mathcal{L}}} \phi(\lambda \phi)^{\cdot}\right\}= \\
& \frac{1}{\lambda}\left\{2 i \int_{\mathbf{a}_{\beta}}\left(\phi_{\bar{z}} \phi_{z} d \bar{z}+\phi \phi_{z z} d z\right)+\dot{\lambda}+\lambda \iint_{\hat{\mathcal{L}}} \phi \dot{\phi}\right\}
\end{aligned}
$$

This implies (6.18) after integration by parts (one has to make use of the relation $d\left(\phi \phi_{z}\right)=\phi_{z}^{2} d z+$ $\left.\phi \phi_{z z} d z+\phi_{\bar{z}} \phi_{z} d \bar{z}+\frac{1}{4} \lambda \phi^{2} d \bar{z}\right)$.

Variation of the determinant of the Laplacian. For simplicity we consider only the flat surfaces with trivial holonomy having $2 g-2$ conical points with conical angles $4 \pi$. (The results concerning the general case can be found in [12]).

Proposition $6 \operatorname{Let}(\mathcal{L}, w) \in \mathcal{H}_{g}(1, \ldots, 1)$. Introduce the notation

$$
\begin{equation*}
\mathbb{Q}\left(\mathcal{L},|w|^{2}\right):=\left\{\frac{\operatorname{det} \Delta^{|w|^{2}}}{\operatorname{Area}\left(\mathcal{L},|w|^{2}\right) \operatorname{det} \Im \mathbf{B}}\right\} \tag{6.19}
\end{equation*}
$$

where $\mathbf{B}$ is the matrix of $\mathbf{b}$-periods of the surface $\mathcal{L}$ and $\operatorname{Area}\left(\mathcal{L},|w|^{2}\right)$ denotes the area of $\mathcal{L}$ in the metric $|w|^{2}$.

The following variational formulas hold

$$
\begin{equation*}
\frac{\partial \log \mathbb{Q}\left(\mathcal{L},|w|^{2}\right)}{\partial \zeta_{k}}=-\frac{1}{12 \pi i} \oint_{s_{k}} \frac{S_{B}-S_{w}}{w} \tag{6.20}
\end{equation*}
$$

where $k=1, \ldots, 4 g-3 ; S_{B}$ is the Bergman projective connection, $S_{w}$ is the projective connection given by the Schwarzian derivative $\left\{\int^{P} w, x(P)\right\} ; S_{B}-S_{w}$ is a meromorphic quadratic differential with poles of the second order at the zeroes $P_{m}$ of $w$.

Proof. The following proof is based on the ideas of J. Fay applied in the context of flat metrics with conical singularities (cf. the proof of Theorem 3.7 in [8]). In this case the calculations get shorter and more elementary (in particular, the Ahlfors-Teichmüller theory is not used here).

Due to Theorem 1 one has

$$
\begin{equation*}
\operatorname{Tr} e^{t \Delta}=\frac{c_{0}}{t}+c_{1}+O\left(t^{N}\right) \tag{6.21}
\end{equation*}
$$

as $t \rightarrow 0+$, where $N$ is an arbitrary real number, $c_{0}=\frac{A}{4 \pi}$, where

$$
A:=\operatorname{Area}\left(\mathcal{L},|w|^{2}\right)=-\frac{1}{2 i} \sum_{\alpha=1}^{g}\left(A_{\alpha} \bar{B}_{\alpha}-\bar{A}_{\alpha} B_{\alpha}\right)
$$

is the area of the surface $\mathcal{L}$ and $c_{1}=-\frac{M}{8}$. Notice that the coefficient $c_{1}$ is moduli independent and the coefficient $c_{0}$ is independent of the moduli $z_{2}, \ldots, z_{M}$.

Following [8], consider the expression

$$
J(\lambda, s)=\frac{1}{s \Gamma(s)} \int_{0}^{+\infty} e^{-\lambda t} t^{s-1} h(t) d t
$$

where

$$
h(t)=\operatorname{Tr} e^{t \Delta}-\left(1-e^{-t^{2}}\right)-\frac{e^{-t}}{t}\left[(1+t) c_{0}+t c_{1}\right] .
$$

Notice that $h(t)=O\left(t^{-N}\right)$ as $t \rightarrow+\infty$ with any $N>0$ and (6.21) implies that $h(t)=O(t)$ as $t \rightarrow 0+$. Thus,

$$
\left.\frac{d}{d \lambda} J(\lambda, s)\right|_{s=0}=-\int_{0}^{+\infty} e^{-\lambda t} h(t) d t=O\left(\frac{1}{\lambda^{2}}\right)
$$

as $\lambda \rightarrow+\infty$. From the calculations on p. 42 of [8] it follows that
$J(\lambda, s)=\left.\frac{d}{d s} \zeta_{\Delta}(s ; \lambda)\right|_{s=0}+\frac{\gamma}{2}-\int_{0}^{\lambda} \int_{0}^{+\infty} e^{-t^{2}-\lambda t} d t d \lambda+c_{0}(1+\lambda-\lambda \log (\lambda+1))+c_{1} \log (1+\lambda)+O(s)$,
as $s \rightarrow 0$, where $\gamma$ is the Euler constant and

$$
\zeta_{\Delta}(s ; \lambda)=\sum_{\lambda_{n} \in \operatorname{sp} \Delta \backslash\{0\}} \frac{1}{\left(\lambda-\lambda_{n}\right)^{s}} .
$$

This implies the relation

$$
-\left.\int_{0}^{+\infty} \frac{d}{d \lambda} J(\lambda, s)\right|_{s=0} d \lambda=J(0,0)=\zeta_{\Delta}^{\prime}(0)+\frac{\gamma}{2}+c_{0}
$$

and, therefore, one has

$$
\begin{equation*}
-\zeta_{\Delta}^{\prime}(0)=\frac{\gamma}{2}+c_{0}-\int_{0}^{+\infty} d \lambda \int_{0}^{+\infty} e^{-\lambda t}\left[\operatorname{Tr} e^{t \Delta}-\left(1-e^{-t^{2}}\right)-\frac{e^{-t}}{t}\left((1+t) c_{0}+t c_{1}\right)\right] d t \tag{6.22}
\end{equation*}
$$

Consider the variation of (6.22) with respect to $A_{\alpha}$. (In what follows for any differentiable function $F$ of moduli $\left\{z_{m}, A_{\alpha}, B_{\alpha}\right\}$ we denote by $\dot{F}$ the derivative $\frac{\partial F}{\partial A_{\alpha}}$.)

Using the formulas $\dot{c_{1}}=0, \dot{c_{0}}=-\frac{\bar{B}_{\alpha}}{8 \pi i}$ and the relation

$$
\left[\iint_{\mathcal{L}} F(P) d A(P)\right]=\iint_{\mathcal{L}} \dot{F}(P) d A(P)+\frac{i}{2} \oint_{b_{\alpha}} F(z, \bar{z}) \overline{d z}
$$

where $d A(P)$ is the area element defined by the metric $|w|^{2}$, we get

$$
\begin{align*}
{\left[-\zeta_{\Delta}^{\prime}(0)\right]=-\frac{\bar{B}_{\alpha}}{8 \pi i}-} & \int_{0}^{+\infty} d \lambda \int_{0}^{+\infty} d t e^{-\lambda t}\left\{\iint_{\mathcal{L}}\left(\dot{\mathcal{H}}(P, P, t)+\frac{\dot{A}}{A^{2}}\left(1-e^{-t^{2}}\right)\right) d A(P)+\right.  \tag{6.23}\\
& \left.\frac{i}{2} \oint_{b_{\alpha}}\left[\mathcal{H}(z, z, t)-\frac{1}{A}\left(1-e^{-t^{2}}\right)-\frac{e^{-t}}{4 \pi t}(1+t)\right] \overline{d z}\right\}
\end{align*}
$$

Using the standard relation

$$
G(x, y ; \lambda)=-\int_{0}^{+\infty} e^{-\lambda t} \mathcal{H}(x, y, t) d t
$$

between the resolvent and the heat kernels, we rewrite the right hand side of (6.23) as

$$
\begin{equation*}
-\frac{\bar{B}_{\alpha}}{8 \pi i}+\int_{0}^{+\infty} d \lambda\left\{\iint_{\mathcal{L}} \dot{G}(P, P ; \lambda) d A(P)-\frac{\dot{A}}{A} I(\lambda)-\frac{i}{2} \oint_{b_{\alpha}} \hat{G}(z, z ; \lambda) \overline{d z}\right\} \tag{6.24}
\end{equation*}
$$

where

$$
I(\lambda)=\frac{1}{\lambda}-e^{\lambda^{2} / 4} \int_{\lambda / 2}^{+\infty} e^{-t^{2}} d t
$$

as in $([8],(2.34))$ and $\hat{G}(z, z ; \lambda)$ is Fay's modified resolvent

$$
\begin{equation*}
\hat{G}(z, z ; \lambda)=\int_{0}^{+\infty} e^{-\lambda t}\left(\mathcal{H}(z, z, t)-\frac{1}{A}\left(1-e^{-t^{2}}\right)-\frac{e^{-t}}{4 \pi t}(1+t)\right) d t \tag{6.25}
\end{equation*}
$$

(See [8]: the last formula on page 42, formulas (2.34-2.35) on p. 38 and the first two lines on p. 39. One has to make use of the fact that the metric $|w|^{2}$ is Euclidean in a vicinity of the cycle $b_{\alpha}$ and, therefore, the coefficients $H_{0}$ and $H_{1}$ in Fay's formulas are 1 and 0 .) For future reference notice that according to ([8], p. 38) one has the relation

$$
\begin{equation*}
\hat{G}\left(z_{1}, z_{2} ; \lambda\right)=G\left(z_{1}, z_{2} ; \lambda\right)+\frac{1}{A} I(\lambda)-\frac{1}{2 \pi}\left[\log \left|z_{1}-z_{2}\right|+\gamma+\log \frac{\sqrt{\lambda+1}}{2}-\frac{1}{2(\lambda+1)}\right], \tag{6.26}
\end{equation*}
$$

where the right hand side of (6.26) is nonsingular at the diagonal $z_{1}=z_{2}$. Now (6.8) implies

$$
\begin{gathered}
\iint_{\mathcal{L}} \dot{G}(P, P ; \lambda) d A(P)=\frac{i}{2} \oint_{b_{\alpha}} \overline{d z} \iint_{\mathcal{L}} \lambda G(z, P ; \lambda) G(z, P ; \lambda) d A(P)+ \\
2 i \iint_{\mathcal{L}} d A(P) \oint_{b_{\alpha}} G_{z}(z, P ; \lambda) G_{z}(z, P ; \lambda) d z
\end{gathered}
$$

The interior contour integral in the last term has $\delta$-type singularity as $P$ approaches to the contour $b_{\alpha}$ and using Stokes formula and the (logarithmic) asymptotics of the resolvent kernel at the diagonal, it is easy to show that
$\iint_{\mathcal{L}} d A(P) \oint_{b_{\alpha}} G_{z}(z, P ; \lambda) G_{z}(z, P ; \lambda) d z=\frac{2 \pi i}{16 \pi^{2}} \oint_{b_{\alpha}} \overline{d z}+\oint_{b_{\alpha}} d z \mathrm{p} . \mathrm{v} . \iint G_{z}(z, P ; \lambda) G_{z}(z, P ; \lambda) d A(P)$.
Now from the resolvent identity

$$
\begin{equation*}
\frac{G(Q, P ; \lambda)-G(Q, P ; \mu)}{\lambda-\mu}=\iint_{\mathcal{L}} G(P, R ; \lambda) G(Q, R ; \mu) d A(R) \tag{6.27}
\end{equation*}
$$

it follows that

$$
\begin{equation*}
\iint_{\mathcal{L}} G(z, P ; \lambda) G(z, P ; \lambda) d A(P)=\frac{\partial}{\partial \lambda} G(z, z ; \lambda) . \tag{6.28}
\end{equation*}
$$

Moreover, according to Lemma 3.3 from [8] one has
$\iint_{\mathcal{L}} G_{z^{\prime}}\left(z^{\prime}, P ; \lambda\right) G_{z}(z, P ; \lambda) d A(P)=-\frac{1}{16 \pi} \frac{\overline{z^{\prime}-z}}{z^{\prime}-z}+$ p.v. $\iint_{\mathcal{L}} G_{z}(z, P ; \lambda) G_{z}(z, P ; \lambda) d A(P)+O\left(z^{\prime}-z\right)$,
and the resolvent identity (6.27) implies the relation

$$
\begin{equation*}
\text { p.v. } \iint G_{z}(z, P ; \lambda) G_{z}(z, P ; \lambda) d A(P)=\left.\frac{\partial}{\partial \lambda}\left\{G_{z^{\prime} z}\left(z^{\prime}, z ; \lambda\right)-\frac{1}{4 \pi} \frac{1}{\left(z^{\prime}-z\right)^{2}}+\frac{\lambda}{16 \pi} \frac{\overline{z^{\prime}-z}}{z^{\prime}-z}\right\}\right|_{z^{\prime}=z} . \tag{6.29}
\end{equation*}
$$

Thus, (6.24) can be rewritten as

$$
\begin{gather*}
-\frac{\bar{B}_{\alpha}}{8 \pi i}+\frac{i}{2} \int_{0}^{+\infty} d \lambda \oint_{b_{\alpha}} \overline{d z}\left[\lambda \frac{\partial}{\partial \lambda} G(z, z ; \lambda)-\frac{1}{4 \pi}+\hat{G}(z, z ; \lambda)-\frac{1}{A} I(\lambda)\right]+  \tag{6.30}\\
\left.2 i \int_{0}^{+\infty} \oint_{b_{\alpha}} d z \frac{\partial}{\partial \lambda}\left\{G_{z^{\prime} z}\left(z^{\prime}, z ; \lambda\right)-\frac{1}{4 \pi} \frac{1}{\left(z^{\prime}-z\right)^{2}}+\frac{\lambda}{16 \pi} \frac{\overline{z^{\prime}-z}}{z^{\prime}-z}\right\}\right|_{z^{\prime}=z}
\end{gather*}
$$

Using (6.26), rewrite the expression in the square brackets as

$$
\frac{\partial}{\partial \lambda}\left(\lambda \hat{G}-\frac{1}{4 \pi} \frac{\lambda}{\lambda+1}-\frac{1}{A} \lambda I(\lambda)\right) .
$$

To finish our calculation we need several lemmas
The first one is an analog of Corollary 2.8 from [8].
Lemma 2 The following relation holds

$$
\begin{equation*}
4 \pi G_{z^{\prime} z}\left(z^{\prime}, z ; \lambda\right)=\frac{1}{\left(z^{\prime}-z\right)^{2}}-\frac{\lambda}{4} \frac{\overline{z^{\prime}-z}}{z^{\prime}-z}+\alpha\left(z^{\prime}, z\right), \tag{6.31}
\end{equation*}
$$

where $\alpha\left(z, z^{\prime}\right)$ is $O\left(\left|z^{\prime}-z\right|\right)$ as $z^{\prime} \rightarrow z$ and $\lambda$ belongs to any closed subinterval of $(0,+\infty)$.

To prove the lemma we notice that the metric $|w|^{2}$ is flat in a vicinity of a point $P \in \beta_{\alpha}$ and the geodesic local coordinates in this vicinity are given by the local parameter $z$. Therefore, as it is explained on pp. 38-39 of [8] the asymptotical behavior of $4 \pi G_{z^{\prime} z}\left(z^{\prime}, z ; \lambda\right)$ coincides with that of the second derivative with respect to $z^{\prime}$ and $z$ of the function

$$
\begin{equation*}
F\left(z^{\prime}, \bar{z}^{\prime}, z, \bar{z}\right)=\log \left|z^{\prime}-z\right|^{2}+\frac{1}{4} \lambda\left|z-z^{\prime}\right|^{2} \log \left|z^{\prime}-z\right|^{2}, \tag{6.32}
\end{equation*}
$$

(One has to put $H_{0}=1$ and $H_{1}=0$ in Fay's calculations on p. 38 of [8].) This immediately leads to (6.31).

The next two lemmas are classical (see [8], p. 25 and example 2.4 and formula (2.18) on p. 30).
Lemma 3 There is the following Laurent expansion near the pole $\lambda=0$ of the resolvent $G\left(z^{\prime}, z ; \lambda\right)$ :

$$
\begin{equation*}
G\left(z^{\prime}, z ; \lambda\right)=-\frac{1}{\lambda \operatorname{Area}(\mathcal{L})}+G\left(z^{\prime}, z\right)+O(\lambda) \tag{6.33}
\end{equation*}
$$

as $\lambda \rightarrow 0$, where $G\left(z^{\prime}, z\right)$ is the Green function.
Lemma 4 The relation holds

$$
\begin{equation*}
4 \pi G_{z^{\prime} z}\left(z^{\prime}, z\right)=\frac{1}{\left(z^{\prime}-z\right)^{2}}+\frac{1}{6} S_{B}(z)-\pi \sum_{\alpha, \beta=1}^{g}(\Im \mathbf{B})_{\alpha \beta}^{-1} v_{\alpha}(z) v_{\beta}(z)+O\left(z^{\prime}-z\right) \tag{6.34}
\end{equation*}
$$

as $z^{\prime} \rightarrow z$, where $G\left(z^{\prime}, z\right)$ is the Green function from (6.33), $S_{B}$ is the Bergman projective connection, $\left\{v_{\alpha}(z) d z\right\}_{\alpha=1}^{g}$ is the basis of normalized holomorphic differentials on $\mathcal{L}$ and $\mathbf{B}$ is the matrix of b-periods of $\mathcal{L}$.

It should be noted that the Green functions depends on the metric on $\mathcal{L}$ whereas its second derivative (6.34) is independent of the (conformal) metric.

The last lemma immediately follows from Rauch variational formula (6.7) and the obvious relation $2 i[\log \operatorname{det} \Im \mathbf{B}]^{\cdot}=\operatorname{Tr}\left\{(\Im \mathbf{B})^{-1} \dot{\mathbf{B}}\right\}$.

Lemma 5 The relation holds

$$
\begin{equation*}
[\log \operatorname{det} \Im \mathbf{B}]=\frac{1}{2 i} \sum_{\gamma, \beta=1}^{g}(\Im \mathbf{B})_{\gamma \beta}^{-1} \oint_{b_{\alpha}} v_{\gamma}(z) v_{\beta}(z) d z \tag{6.35}
\end{equation*}
$$

Now using the asymtotics $I(\lambda)=O\left(\frac{1}{\lambda^{3}}\right)$ as $\lambda \rightarrow+\infty$ and the last four Lemmas, one can make the integration with respect to $\lambda$ in (6.24). This leads to the relation

$$
\left[-\zeta_{\Delta}^{\prime}(0)\right]^{\cdot}=\frac{1}{12 \pi i} \oint_{b_{\alpha}} S_{B}(z) d z+[\log \operatorname{det} \Im \mathbf{B}]^{\cdot}+[\log \mathrm{A}]^{\cdot}
$$

The latter relation is equivalent to (6.20) for $k=1, \ldots, g$. The proof of (6.20) in the case $k=$ $g+1, \ldots, 2 g$ is similar.

Consider now the variation of (6.22) with respect to $z_{m}$. From now on the dot denotes the derivative with respect to $z_{m}$. Using the equality $\dot{c}_{0}=\dot{c}_{1}=0$ and (6.10), we get

$$
\begin{equation*}
\left[-\zeta_{\Delta}^{\prime}(0)\right]^{\cdot}=-2 i \lim _{\epsilon \rightarrow 0} \int_{0}^{+\infty} d \lambda \iint_{\mathcal{L}} d A(P) \oint_{\left|z-z_{m}\right|=\epsilon} G_{z}(z, P ; \lambda) G_{z}(z, P ; \lambda) d z \tag{6.36}
\end{equation*}
$$

After passing to local parameter $x=\sqrt{z-z_{m}}$, the latter expression can be rewritten as

$$
\begin{equation*}
-2 i \lim _{\epsilon \rightarrow 0} \oint_{|x|=\sqrt{\epsilon}} \frac{d x}{2 x} \int_{0}^{+\infty} d \lambda \iint_{\mathcal{L}} G_{x}(x, P ; \lambda) G_{x}(x, P ; \lambda) d A(P) . \tag{6.37}
\end{equation*}
$$

Lemma 3.3 from [8] implies the relation

$$
\begin{equation*}
\iint_{\mathcal{L}} G_{x^{\prime}}\left(x^{\prime}, P ; \lambda\right) G_{x}(x, P ; \lambda) d A(P)=-\frac{1}{4 \pi}|x|^{2} \frac{\overline{x^{\prime}-x}}{x^{\prime}-x}+\iint_{\mathcal{L}} G_{x}(x, P ; \lambda) G_{x}(x, P ; \lambda) d A(P)+O\left(\left|x^{\prime}-x\right|\right), \tag{6.38}
\end{equation*}
$$

as $x^{\prime} \rightarrow x$. Using this relation rewrite the right hand side of (6.37) as

$$
\begin{equation*}
-\left.2 i \lim _{\epsilon \rightarrow 0} \oint_{|x|=\sqrt{\epsilon}} \frac{d x}{2 x} \int_{0}^{+\infty} d \lambda\left\{\iint_{\mathcal{L}} G_{x^{\prime}}\left(x^{\prime}, P ; \lambda\right) G_{x}(x, P ; \lambda) d A(P)+\frac{1}{4 \pi}|x|^{2} \frac{\overline{x^{\prime}-x}}{x^{\prime}-x}\right\}\right|_{x=x^{\prime}} \tag{6.39}
\end{equation*}
$$

As before, using the resolvent identity, we rewrite the expression inside the braces as a derivative with respect to $\lambda$ :

$$
\begin{equation*}
\left[-\zeta_{\Delta}^{\prime}(0)\right]^{\cdot}=-\left.2 i \lim _{\epsilon \rightarrow 0} \oint_{|x|=\sqrt{\epsilon}} \frac{d x}{2 x} \int_{0}^{+\infty} d \lambda \frac{\partial}{\partial \lambda}\left\{G_{x^{\prime} x}\left(x^{\prime}, x ; \lambda\right)-\frac{1}{4 \pi} \frac{1}{\left(x^{\prime}-x\right)^{2}}+\frac{\lambda}{4 \pi}|x|^{2} \frac{\overline{x^{\prime}-x}}{x^{\prime}-x}\right\}\right|_{x^{\prime}=x} \tag{6.40}
\end{equation*}
$$

Again we need a few lemmas.
Lemma 6 The following relation holds

$$
\begin{equation*}
4 \pi G_{x^{\prime} x}\left(x^{\prime}, x ; \lambda\right)=\frac{1}{\left(x^{\prime}-x\right)^{2}}-\frac{1}{4 x^{2}}-\lambda|x|^{2} \frac{\overline{x^{\prime}-x}}{x^{\prime}-x}+\alpha\left(x^{\prime}, x\right) \tag{6.41}
\end{equation*}
$$

where $\alpha\left(x, x^{\prime}\right)$ is $O\left(\left|x^{\prime}-x\right|\right)$ as $x^{\prime} \rightarrow x$ and $\lambda$ belongs to any closed subinterval of $(0,+\infty)$.
To prove the lemma we notice that the metric $|w|^{2}$ is flat in a vicinity of the point $x$ and the geodesic local coordinates in this vicinity are given by the local parameter $z=z_{m}+x^{2}$. Therefore, as it is explained on pp. 38-39 of [8] the asymptotical behavior of $4 \pi G_{x^{\prime} x}\left(x^{\prime}, x ; \lambda\right)$ coincides with that of the second derivative with respect to $x^{\prime}$ and $x$ of the function

$$
\begin{equation*}
F\left(x^{\prime}, \overline{x^{\prime}}, x, \bar{x}\right)=\log \left|z^{\prime}-z\right|^{2}+\frac{1}{4} \lambda\left|z-z^{\prime}\right|^{2} \log \left|z^{\prime}-z\right|^{2} \tag{6.42}
\end{equation*}
$$

where $z^{\prime}=z_{m}+\left(x^{\prime}\right)^{2}$.
Using the Taylor expansion of $\left(x^{\prime}-x\right)^{2} F_{x^{\prime} x}\left(x^{\prime}, \bar{x}^{\prime}, x, \bar{x}\right)$ up to the terms of the second order, we arrive at (6.41).

Now notice that formulas (6.33) and (6.34) are still true being written in the local parameter $x$, moreover, one has the following analog of Lemma 5:

Lemma 7 The relation holds

$$
\begin{equation*}
[\log \operatorname{det} \Im \mathbf{B}]=\frac{1}{2 i} \sum_{\alpha, \beta=1}^{g}(\Im \mathbf{B})_{\alpha \beta}^{-1} \oint_{|x|=\sqrt{\epsilon}} \frac{v_{\alpha}(x) v_{\beta}(x) d x}{2 x} \tag{6.43}
\end{equation*}
$$

These lemmas together with (6.40) imply the relation

$$
\left[-\zeta_{\Delta}^{\prime}(0)\right]^{\cdot}=-\frac{1}{12 \pi i} \oint_{C} \frac{S_{B}(x) d x}{2 x}+[\log \operatorname{det} \Im \mathbf{B}]
$$

where $C$ is a small positively oriented circle around $P_{m}$. The latter relation is equivalent to (6.20) for $k=2 g+m, m=1, \ldots, M-1$.

### 6.1.2 An explicit formula for the determinant of the Laplacian on a flat surface with trivial holonomy

We start with recalling the properties of the prime form $E(P, Q)$ (see [7, 8], some of these properties were already used in our proof of the Troyanov theorem above).

- The prime form $E(P, Q)$ is an antisymmetric -1/2-differential with respect to both $P$ and $Q$,
- Under tracing of $Q$ along the cycle $a_{\alpha}$ the prime-form remains invariant; under the tracing along $b_{\alpha}$ it gains the factor

$$
\begin{equation*}
\exp \left(-\pi i \mathbf{B}_{\alpha \alpha}-2 \pi i \int_{P}^{Q} v_{\alpha}\right) \tag{6.44}
\end{equation*}
$$

- On the diagonal $Q \rightarrow P$ the prime-form has first order zero with the following asymptotics:

$$
\begin{gather*}
E(x(P), x(Q)) \sqrt{d x(P)} \sqrt{d x(Q)}= \\
(x(Q)-x(P))\left(1-\frac{1}{12} S_{B}(x(P))(x(Q)-x(P))^{2}+O\left((x(Q)-x(P))^{3}\right)\right. \tag{6.45}
\end{gather*}
$$

where $S_{B}$ is the Bergman projective connection and $x(P)$ is an arbitrary local parameter.
The next object we shall need is the vector of Riemann constants:

$$
\begin{equation*}
K_{\alpha}^{P}=\frac{1}{2}+\frac{1}{2} \mathbf{B}_{\alpha \alpha}-\sum_{\beta=1, \beta \neq \alpha}^{g} \oint_{a_{\beta}}\left(v_{\beta} \int_{P}^{x} v_{\alpha}\right) \tag{6.46}
\end{equation*}
$$

where the interior integral is taken along a path which does not intersect $\partial \widehat{\mathcal{L}}$.
In what follows the pivotal role is played by the following holomorphic multivalued $g(1-g) / 2$ differential on $\widehat{L}$

$$
\begin{equation*}
\mathcal{C}(P)=\frac{1}{\mathcal{W}\left[v_{1}, \ldots, v_{g}\right](P)} \sum_{\alpha_{1}, \ldots, \alpha_{g}=1}^{g} \frac{\partial^{g} \Theta\left(K^{P}\right)}{\partial z_{\alpha_{1}} \ldots \partial z_{\alpha_{g}}} v_{\alpha_{1}} \ldots v_{\alpha_{g}}(P), \tag{6.47}
\end{equation*}
$$

where $\Theta$ is the theta-function of the Riemann surface $\mathcal{L}$,

$$
\begin{equation*}
\mathcal{W}(P):=\operatorname{det}_{1 \leq \alpha, \beta \leq g}\left\|v_{\beta}^{(\alpha-1)}(P)\right\| \tag{6.48}
\end{equation*}
$$

is the Wronskian determinant of holomorphic differentials at the point $P$.
It is easy to see that this differential has multipliers 1 and $\exp \left\{-\pi i(g-1)^{2} \mathbf{B}_{\alpha \alpha}-2 \pi i(g-1) K_{\alpha}^{P}\right\}$ along basic cycles $a_{\alpha}$ and $b_{\alpha}$, respectively.

In what follows we shall often treat tensor objects like $E(P, Q), \mathcal{C}(P)$, etc as scalar functions of one of the arguments (or both). This makes sense after fixing the local system of coordinates, which is usually taken to be $z(Q)=\int^{Q} w$. In particular, the expression "the value of the tensor $T$ at the point $Q$ in local parameter $z(Q) "$ will mean the value of the scalar $T w^{-\alpha}$ at the point $Q$, where $\alpha$ is the tensor weight of $T(Q)$.

The following proposition was proved in [12].
Proposition 7 Consider the highest stratum $\mathcal{H}_{g}(1, \ldots, 1)$ of the space $\mathcal{H}_{g}$ containing Abelian differentials $w$ with simple zeros.

Let us choose the fundamental polygon $\hat{\mathcal{L}}$ such that $\mathcal{A}_{P}((w))+2 K^{P}=0$, where $\mathcal{A}_{P}$ is the Abel map with the initial point $P$. Consider the following expression

$$
\begin{equation*}
\tau(\mathcal{L}, w)=\mathcal{F}^{2 / 3} \prod_{m, l=1}^{2 g-2}\left[E\left(Q_{m}, Q_{l}\right)\right]^{1 / 6} \tag{6.49}
\end{equation*}
$$

where the quantity

$$
\begin{equation*}
\mathcal{F}:=[w(P)]^{\frac{g-1}{2}} \mathcal{C}(P) \prod_{m=1}^{2 g-2}\left[E\left(P, Q_{m}\right)\right]^{\frac{(1-g)}{2}} \tag{6.50}
\end{equation*}
$$

does not depend on $P$; all prime-forms are evaluated at the zeroes $Q_{m}$ of the differential $w$ in the distinguished local parameters $x_{m}(P)=\left(\int_{Q_{m}}^{P} w\right)^{1 / 2}$. Then

$$
\begin{equation*}
\frac{\partial \log \tau}{\partial \zeta_{k}}=-\frac{1}{12 \pi i} \oint_{s_{k}} \frac{S_{B}-S_{w}}{w} \tag{6.51}
\end{equation*}
$$

where $k=1, \ldots, 4 g-3$.
The following Theorem immediately follows from Propositions 6 and 7 . It can be considered as a natural generalization of Ray-Singer formula (5.1) to the higher genus case.

Theorem 3 Let a pair $(\mathcal{L}, w)$ be a point of the space $\mathcal{H}_{g}(1, \ldots, 1)$. Then the determinant of the Laplacian $\Delta^{|w|^{2}}$ is given by the following expression

$$
\begin{equation*}
\operatorname{det} \Delta^{|w|^{2}}=C \operatorname{Area}\left(\mathcal{L},|w|^{2}\right) \operatorname{det} \Im \mathbf{B}|\tau(\mathcal{L}, w)|^{2} \tag{6.52}
\end{equation*}
$$

where the constant $C$ is independent of a point of $\mathcal{H}_{g}(1, \ldots, 1)$. Here $\tau(\mathcal{L}, w)$ is given by (6.49).

### 6.2 Determinant of the Laplacian on an arbitrary polyhedral surface of genus $g>1$

Let $b_{1}, \ldots, b_{N}$ be real numbers such that $b_{k}>-1$ and $b_{1}+\cdots+b_{N}=2 g-2$. Denote by $\mathcal{M}_{g}\left(b_{1}, \ldots, b_{N}\right)$ the moduli space of pairs $(\mathcal{L}, \mathbf{m})$, where $\mathcal{L}$ is a compact Riemann surface of genus $g>1$ and $\mathbf{m}$ is a flat conformal conical metric on $\mathcal{L}$ having $N$ conical points with conical angles $2 \pi\left(b_{1}+1\right), \ldots, 2 \pi\left(b_{N}+1\right)$. The space $\mathcal{M}_{g}\left(b_{1}, \ldots, b_{N}\right)$ is a (real) orbifold of the (real) dimension $6 g+2 N-5$. The moduli space
$\mathcal{H}_{g}$ of holomorphic differentials on Riemann surfaces of genus $g$ forms a fiber bundle over the moduli space $\mathcal{M}_{g}$.

Let $\mathcal{U} \subset \mathcal{M}_{g}$ be a path-connected set such that there exists a $C^{1}$-section $\Omega: \mathcal{L} \mapsto(\mathcal{L}, w)$ of the bundle $\left.\mathcal{H}_{g}\right|_{\mathcal{U}}$ with the property $(\mathcal{L}, w) \in H_{g}(1, \ldots, 1)$ for any $\mathcal{L} \in \mathcal{U}$.

Let $\mathcal{L} \in \mathcal{U},(\mathcal{L}, \mathbf{m})$ belong to $\mathcal{M}_{g}\left(b_{1}, \ldots, b_{N}\right)$ and let $w$ be the holomorphic differential with $2 g-2$ simple zeroes on $\mathcal{L}$ defined via the section $\Omega$. Assume also that the set of conical points of the metric $\mathbf{m}$ and the set of zeros of the differential $w$ do not intersect.

Let $P_{1}, \ldots, P_{N}$ be the conical points of $\mathbf{m}$ and let $Q_{1}, \ldots, Q_{2 g-2}$ be the zeroes of $w$. Let $x_{k}$ be a distinguished local parameter for $\mathbf{m}$ near $P_{k}$ and $y_{l}$ be a distinguished local parameter for $w$ near $Q_{l}$. Introduce the functions $f_{k}, g_{l}$ and the complex numbers $\mathbf{f}_{\mathbf{k}}, \mathbf{g}_{\mathbf{1}}$ by

$$
\begin{aligned}
& |w|^{2}=\left|f_{k}\left(x_{k}\right)\right|^{2}\left|d x_{k}\right|^{2} \text { near } \quad P_{k} ; \quad \mathbf{f}_{\mathbf{k}}:=f_{k}(0), \\
& \mathbf{m}=\left|g_{l}\left(y_{l}\right)\right|^{2}\left|d y_{l}\right|^{2} \text { near } Q_{l} ; \quad \mathbf{g}_{1}:=g_{l}(0) .
\end{aligned}
$$

Then, according to (4.9) and (6.52), we have

$$
\begin{equation*}
\operatorname{det} \Delta^{\mathbf{m}}=C \operatorname{Area}(\mathcal{L}, \mathbf{m}) \operatorname{det} \Im \mathbf{B}|\tau(\mathcal{L}, w)|^{2} \frac{\prod_{l=1}^{2 g-2}\left|\mathbf{g}_{\mathbf{1}}\right|^{1 / 6}}{\prod_{k=1}^{N}\left|\mathbf{f}_{\mathbf{k}}\right|^{b_{k} / 6}} \tag{6.53}
\end{equation*}
$$

where the constant $C$ depends only on $b_{1}, \ldots, b_{N}$ and $\tau$ is given by (6.49).

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[^1]:    ${ }^{1}$ There exist polyhedral surfaces with nontrivial holonomy whose conical angles are all integer multiples of $2 \pi$. To construct an example take a compact Riemann surface $\mathcal{L}$ of genus $g>1$ and choose $2 g-2$ points $P_{1}, \ldots, P_{2 g-2}$ on $\mathcal{L}$ in such a way that the divisor $P_{1}+\cdots+P_{2 g-2}$ is not linearly equivalent to the canonical divisor. Consider the flat conical conformal metric $\mathbf{m}$ corresponding to the divisor $P_{1}+\cdots+P_{2 g-2}$ according to the Troyanov theorem. This metric must have nontrivial holonomy and all its conical angles are equal to $4 \pi$.

