

**ONE REMARK ON CONSTRUCTION OF  
SEPARATED FACTOR-SPACE**

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# ONE REMARK ON CONSTRUCTION OF SEPARATED FACTOR-SPACE

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ABSTRACT. We discuss elementary constructions of boundaries of symmetric spaces.

Let  $M$  be a compact metric space. Let  $M = \bigcup_{\alpha \in A} M_\alpha$  be a partition of  $M$  ( $M_\alpha \cap M_\beta = \emptyset$  if  $\alpha \neq \beta$ ). Then the factor-space  $A$  has canonical structure of a topological space. Recall that the set  $P \subset A$  is closed if and only if  $\bigcup_{\alpha \in P} M_\alpha$  is a closed subset in  $M$ . Let  $a_1, a_2, \dots$  be a sequence in  $A$ . Let  $a \in A$ . Then  $a_j \rightarrow a$  if there exist points  $m_j \in M_{\alpha_j}, m \in M_\alpha$  such that  $m_j \rightarrow m$  in  $M$ .

The space  $A$  is not need to be separated in Hausdorff sence. We are interested in the following question: how to construct separated analog of the factorspace  $A$  ?

## 1. PRELIMINARIES. HAUSDORFF CONVERGENCE

Let  $N \subset M$  be a closed subset. Denote by  $M_\epsilon$  the set of all points  $m \in M$  satisfying the condition: there exist  $n \in N$  such that  $\rho(m, n) < \epsilon$ . Let  $[M]$  be the space of all closed subsets in  $M$ . Hausdorff distance  $d(N, N')$  in  $[M]$  between  $N$  and  $N'$  is the infimum of  $\epsilon > 0$  such that  $N \subset N'_\epsilon$  and  $N'_\epsilon \subset N$ .

Recall that the metric space  $[M]$  is compact. Recall also two simple facts on Hausdorff convergence. Denote by  $\bar{S}$  the closure of the set  $S$ . Denote by  $B_\epsilon(m)$  the ball  $\rho(m, n) < \epsilon$ .

*Lemma 1.* Let  $N_j \in [M]$ . Let  $K_\sigma$  ( $\sigma \in \Sigma$ ) be all limit points of the sequence  $N_j$ . Then

- a)  $\overline{\bigcup_{\sigma \in \Sigma} K_\sigma}$  coincides with the set of all  $m \in M$  such that for all  $\epsilon > 0$  the set  $N_j \cap B_\epsilon(m)$  is nonempty for infinite number of  $j$ .
- b)  $\bigcap_{\sigma \in \Sigma} K_\sigma$  coincides with the set of all  $m \in M$  such that for all  $\epsilon > 0$  the set  $N_j \cap B_\epsilon(m)$  is nonempty for sufficiently large  $j$ .

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## 2. CONSTRUCTION OF SEPARATED FACTOR-SPACE

Let a partition  $M = \bigcup_{\alpha \in A} M_\alpha$  satisfies the following condition

\*) for each  $B \subset A$  the set  $\overline{\bigcup_{\alpha \in B} M_\alpha}$  is the union of elements of the partition.

Fix an open subset  $\mathcal{A} \subset A$  such that factor-topology on  $\mathcal{A}$  is separated. Denote by  $\tilde{\mathcal{A}} \subset [M]$  the set of subsets  $\overline{M_\alpha}$ ,  $\alpha \in \mathcal{A}$ . Let our data satisfy the condition

\*\* ) the map  $\alpha \leftrightarrow \overline{M_\alpha}$  is a homeomorphism of the spaces  $\mathcal{A}$  and  $\tilde{\mathcal{A}}$ .

*Definition.* The *separated factor-space*  $[[A]]$  is the closure of  $\tilde{\mathcal{A}}$  in Hausdorff metrics.

*Remark.* Of course the construction depends on the set  $\mathcal{A} \subset A$ .

## 3. DESCRIPTION OF THE SET $[[A]]$

By lemma 1 and the condition \*) the elements  $N \in [[A]]$  are unions of elements  $M_\alpha$  of the partition. Hence we associate to each  $N \in [[A]]$  subset  $S_N \subset A$  of all  $\sigma \in A$  such that  $M_\sigma \subset N$ . Denote by  $[A]$  the set of all subsets  $S_N$ . By construction we have canonical bijection  $[[A]] \leftrightarrow [A]$ .

† The following proposition is evident.

*Lemma 2.* Let  $S \subset A$ . Then the following conditions are equivalent

- a)  $S \in [A]$
- b) There exist a sequence  $a \in A$  such that each limit point of  $a_j$  is an element of  $S$  and each element  $s \in S$  is a limit of the sequence  $a_j$  in the factor-topology on  $A$ .

Elements of  $[A]$  we call *admissible subsets*.

## 4. EXAMPLE: COMPLETE COLLINEATIONS

Let  $M$  be the Grassmann manifold  $Gr_n$  of all  $n$ -dimensional subspaces in  $\mathbb{C}^n \oplus \mathbb{C}^n$ . Let  $\lambda \in \mathbb{C}^* = \mathbb{C} \setminus 0$ . Let  $V \in Gr_n$ . Define the subspace  $\lambda V$  :

$$h \oplus p \in V \Leftrightarrow h \oplus \lambda p \in \lambda V$$

where  $h \in \mathbb{C}^n \oplus 0$ ,  $p \in 0 \oplus \mathbb{C}^n$ . Consider the partition of  $Gr_n$  into  $\mathbb{C}^*$ -orbits. Let  $Op \subset Gr_n$  be the space of graphs of invertible operators. Of course the space  $Op$  coincide with the general linear group  $GL_n(\mathbb{C})$ . The factorspace  $Op/\mathbb{C}^* = GL_n(\mathbb{C})/\mathbb{C}^*$  is the group  $PGL_n(\mathbb{C})$  of invertible operators defined up to scalar multiplier.

We want to apply our construction to the space  $M = Gr_n$  and  $\mathcal{A} = PGL_n(\mathbb{C})$ . We have to describe all admissible subsets in  $Gr_n/\mathbb{C}^*$ .

*Example.* Let  $n = 2$ . Consider the sequence  $Q_n = \begin{pmatrix} 1 & 0 \\ 0 & n \end{pmatrix} \in PGL_2(\mathbb{C})$ . Then the set of limits of  $Q_n$  in  $Gr_2/\mathbb{C}^*$  consists of points  $V_1, \dots, V_5$  (= subspaces in  $\mathbb{C}^2 \oplus \mathbb{C}^2$ ) enumerated below:

$$\begin{aligned}
V_1 &: (x, y; 0, 0) \\
V_2 &: (x, y; 0, y) \\
V_3 &: (x, 0; 0, y) \\
V_4 &: (x, 0; x, y) \\
V_5 &: (0, 0; x, y)
\end{aligned}$$

where  $x, y \in V$ . The subspaces  $V_1, V_3, V_5$  are stable points of the group  $\mathbb{C}^*$ . The  $\mathbb{C}^*$ -orbits of  $V_2, V_4$  are 1-dimensional complex curves.

*Definition.* Let  $V \in Gr_n$ . Then

- a) *Kernel*  $\text{Ker } V = V \cap (\mathbb{C}^n \oplus 0)$
- b) *Image*  $\text{Im } V$  is the projection of  $V$  to  $0 \oplus \mathbb{C}^n$ .
- c) *Domain*  $\text{Dom } V$  is the projection of  $V$  to  $\mathbb{C}^n \oplus 0$ .
- d) *Indefiniteness*  $\text{Indef } V = V \cap (0 \oplus \mathbb{C}^n)$ .

*Remark.* Let  $V \in Gr_n$ . Then the subspace  $V$  induces by the obvious way the invertible operator

$$\text{Dom } V / \text{Ker } V \rightarrow \text{Im } V / \text{Indef } V$$

We denote this operator by  $\langle V \rangle$ .

*Definition.* *Hinge* in  $\mathbb{C}^n$  is a collection

$$\mathcal{P} = (Q_0, P_1, Q_1, P_2, Q_2, \dots, P_k, Q_k)$$

where  $Q_j, P_j$  are elements of  $Gr_n$  defined up to multiplier and 0.

$$\begin{aligned}
Q_j &= \text{Ker } Q_j \oplus \text{Indef } Q_j \\
P_j &\neq \text{Ker } P_j \oplus \text{Indef } P_j
\end{aligned}$$

1. For each  $j = 1, 2, \dots, k$

$$\begin{aligned}
\text{Ker } P_j &= \text{Ker } Q_j = \text{Dom } P_{j+1} \\
\text{Im } P_j &= \text{Im } Q_j = \text{Indef } P_{j+1}
\end{aligned}$$

- 2.

$$\begin{aligned}
Q_0 &= \mathbb{C}^n \oplus 0 ; \text{Dom } P_1 = \mathbb{C}^n \\
Q_k &= 0 \oplus \mathbb{C}^n ; \text{Im } P_k = \mathbb{C}^n .
\end{aligned}$$

*Remark.* Let  $P$  be the graph of an invertible operator  $\mathbb{C}^n \rightarrow \mathbb{C}^n$ . Then

$$(\mathbb{C}^n \oplus 0, P, 0 \oplus \mathbb{C}^n)$$

is a hinge.

*Remark.* The elements  $Q_0, \dots, Q_{k+1}$  of a hinge are completely defined by the elements  $P_1, \dots, P_k$ . The subspaces  $Q_j$  are fixed points of the group  $\mathbb{C}^*$ . The  $\mathbb{C}^*$ -orbits of  $P_j$  are 1-dimensional complex curves.

**Theorem.** *The space  $[PGL_n]$  of all admissible subsets in  $Gr_n/\mathbb{C}^*$  coincides with the space of all hinges.*

The space  $[PGL_n]$  coincide with the *complete collineation* space constructed by Semple (see [2]). It is a smooth algebraic variety and the group  $PGL_n$  is an open dense subset in  $[PGL_n]$ . On equivalence of these two constructions see see [8]. Complete collineations is a partial case of complete symmetric varieties, see De Concini, Procesi [3].

## 5. EXAMPLE. FURSTENBERG-SATAKE COMPACTIFICATION OF RIEMANNIAN SYMMETRIC SPACE

We will only discuss the case  $PGL_n(\mathbb{R})/SO(n)$ . Consider the space  $\mathbb{R}^n \oplus \mathbb{R}^n$  provided by a skew-symmetric bilinear form  $\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$ . Let  $\mathcal{L}$  be the grassmannian of all Lagrangian subspaces in  $\mathbb{R}^n \oplus \mathbb{R}^n$ . Denote by  $\mathbb{R}^*$  the multiplicative group of real positive numbers. This group acts on  $\mathcal{L}$  by multiplications of linear relations on scalars.

Denote by  $R$  the open subset in  $\mathcal{L}$  consisting of graphs of operators  $S : \mathbb{R}^n \rightarrow \mathbb{R}^n$ . It is easy to see that

$$\{\text{matrix } S \text{ is symmetric}\} \Leftrightarrow \{\text{the graf of } S \text{ is an element of } \mathcal{L}\}$$

The group  $GL_n(\mathbb{R})$  acts on  $R$  by the formula  $g : S \mapsto g^t S g$ . The stabilizer of the point  $S = E$  is the orthogonal group  $O(n)$ . Hence  $GL_n(\mathbb{R})$ -orbit  $X$  of  $E$  is a homogeneous space  $GL_n(\mathbb{R})/O(n)$ . Points of  $X$  correpond to positive definite matrices  $S$ .

Now we apply the construction of the sections 2-3 to the space  $\mathcal{L}$  and to the open subset  $X = GL_n(\mathbb{R})/O(n)$ . Then the completion consists of hinges

$$P = (Q_0, P_1, Q_1, \dots, P_k, Q_k)$$

such that  $P_j \in \mathcal{L}, Q_j \in \mathcal{L}$  and the operators  $\langle P_j \rangle$  (see section 4) are positive definite.

## 6. EXAMPLE. BOUNDARY OF BRUHAT-TITS BUILDING

Let  $\mathbb{Q}_p$  be a  $p$ -adic field. Let  $M$  be the space of all  $\mathbb{Z}_p$ -submodules in  $\mathbb{Q}_p^n$ . Let  $B \subset M$  be the space of all lattices. The group  $\mathbb{Q}_p^*$  act on  $M$  in a natural way. Then the corresponding separated factor-space consists of collections

$$(R_0, T_1, R_1, \dots, T_k, R_k)$$

where  $0 = R_0 \subset T_1 \subset R_1 \subset T_2 \dots \subset R_k = \mathbb{Q}_p^n$  are elements of  $M$  defined up to multiplier,  $R_j$  are subspaces and images of  $T_j$  in  $R_j/R_{j-1}$  are lattices.

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