# MODULI OF HYPER-KÄHLERIAN 

## ALGEBRAIC MANIFOLDS

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## Introduction

It is a well known fact that if $X$ is a compact complex simply connected Kähler manifold with $c_{1}(X)=0$, then

$$
x=\pi x_{j} \times \pi y_{i}
$$

where a) for each $j \operatorname{dim~H}\left(X_{j}, \Omega^{2}\right)=1$ and if $\varphi_{j}$ is a non-zero holomorphic two form on $X_{j}$, and at each point $x \in X_{j} \varphi_{j}$ is a non-degenerate, i.e. if $\varphi_{j \mid U}=\Sigma\left(\varphi_{j}\right)_{\alpha \beta} \quad d z{ }_{\wedge}^{\alpha} d z \cdot \beta$ then $\operatorname{det}\left(\left(\varphi_{j}\right)_{\alpha \beta}\right) \in \Gamma\left(U, 0_{U}^{*}\right)$. Such manifold we will call HyperKahlerian.
b) for each $i$ and $0<p<\operatorname{dim}_{\mathbb{C}} y_{i}=n \operatorname{dim} H^{0}\left(y_{i}, \Omega^{p}\right)=0$ and $\operatorname{dim~} H^{0}\left(y_{1}, \Omega^{n}\right)=1$ and $H^{0}\left(y_{i}, \Omega^{n}\right)$ is spanned by a holomorphic n -form which has no-zeroes and no-poles.

This fact is due to Calabi and Bogomolov. See [3]. An elegant proof based on Yau's solution of Calabi conjecture was given by M.L. Michelson. See [16].

The purpose of this article is to study the moduli space of the so called marked algebraic Hyper-Kählerian manifolds.

Definition. A tripple $\left(x, \gamma_{1}, \ldots, \gamma_{b_{2}} ; L\right)$ will be called a marked algebraic Hyper-Kahlerian manifold if $X$ is a Hyper-

Kählerian manifold, $\gamma_{1}, \ldots, \gamma_{b_{2}}$ is a basis of $H_{2}(X, z)$ and $L$ is the imaginary part as a class of cohomology of Hodge metric on $X$.

In this article we prove that the moduli space of marked algebraic Hyper-Kăhlerain manifolds exists. This is proved in § 2. More over we have an universal family of marked algebraic Hyper-Kăhlerain manifolds

$$
x_{L} \xrightarrow{\pi} M_{\left(L ; \gamma_{1}, \ldots, \gamma_{b}\right)}
$$

The construction of the moduli space follows Burns and Rapoport. See [ ].

We have the so called period map:

$$
p: M_{\left(L ; r_{1}, \ldots, r_{b 2}\right)} \rightarrow P\left(H^{2}(x, z) \oplus \mathbb{C}\right)
$$

where

$$
p(t)=\left(\ldots, \int_{\gamma_{i}} w(2,0), \ldots\right) \in \mathbb{P}\left(H^{2}(x, z) \bullet \mathbb{L}\right)
$$

where $\omega_{t}(2,0)$ is the unique up to a constant holomorphic two-form on $X_{t}=\pi^{-1}(t)$. From Bogomolov's result, that there are no oostructions to deformations and local Torelli theorem we get that the irreducible component ${ }^{M}\left(L ; \gamma_{1}, \ldots, r_{b_{p}}\right)$ is a non-singular manifold and $\operatorname{dim}_{c^{M}}\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)=b_{2}-2$, where $b_{2}=\operatorname{dim} H^{2}(X, c)$.

From Griffith's theory of Variations of Hodge structure we get that
$\mathrm{p}: \mathrm{M}_{\left(\mathrm{L} ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right) \rightarrow \mathrm{SO}_{0}\left(2, \mathrm{~b}_{2}-3\right) / \mathrm{SO}(2) \times \operatorname{SO}\left(\mathrm{b}_{2}-3\right) \subset \mathbb{P}\left(\mathrm{H}^{2}(\mathrm{X}, \mathbb{C})\right)}$
is a local isomorphism.

In § 3 we prove Theorem 3. The period map
$\mathrm{p}: \mathrm{M}_{\left(\mathrm{L} ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)} \rightarrow \mathrm{SO}_{\mathrm{g}}\left(2, \mathrm{~b}_{2}-3\right) / \mathrm{SO}(2) \times \operatorname{SO}\left(\mathrm{b}_{2}-3\right)$
is an embedding.

Theorem 3 is a positive answer to the so called Torelli problem, and is in some aspects a generalization of the theorem of Piatezki-Shapiro and Shafarevich about the K-3 surfaces. See [20].

In order to prove Theorem 3 we need to compactify partially the family $X_{L} \rightarrow M_{\left(L ; \gamma_{\eta}, \ldots, \gamma_{b}\right)}$ to a family $\left.\bar{X}_{L} \rightarrow \bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b}\right)}\right)$ by adding ${ }^{\mathbf{z}}$ singular Hyper-Kählerian algebraic manifold Zor which $L$ is a very ample line bundle. Next we prove that $\bar{M}_{\left(L, \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$ is a Hausdorf space and $p$ can be extended to a proper étale map

$$
p: M\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right) \rightarrow \operatorname{sq}\left(2, b_{2}-3\right) / S O(2) \times S O\left(b_{2}-3\right)
$$

But $S O_{0}\left(2, b_{2}-3\right) / S O(2) \times S O\left(b_{2}-3\right)$ is a siegel domain of IV type so $\mathrm{SO}_{0}\left(2, \mathrm{~b}_{2}-3\right) / \mathrm{SO}(2) \times \mathrm{SO}\left(\mathrm{b}_{2}-3\right)$ is a simply connected manifold. From this fact and since $\bar{p}$ is a proper and Etale map we get that $\bar{p}$ is a one-to-one surjective map. So we have proved both injectivity and surjectivity for algebraic Hyper-Kählerian manifolds.

So the main step of the proof of Theorem 3 is the partial compactification and this partial compactification is based on the following theorem

Theorem 1. Suppose $\pi^{*}: X^{*} \rightarrow D^{*}$ is a family of non-singular Hyper-Kahlerian manifolds such that:
a) $\pi *: X^{*} \rightarrow D$ has a trivial monodromy on $H_{2}\left(X_{t}, z\right)$


Then there exists a family $\pi: \chi \rightarrow D$ such that all its fibres are non-singular Hyper-Kahlerian manifolds and


This theorem is proved in $\$ 1$ and the proof 1 is based on the existence of Calabi-Yau metric, i.e. Ricci flat metrices on Hyper-Kahlerain manifolds. The existence of such metrics follows from the Yau's solution of Calabi's conjecture see [22]. More precisely the main point of the proof of Theorem 1 is based on the isometric deformations, which is an application of the existence of Ricci-flat metric. Theorem 1 gives an affirmative answer to a problem posed by Griffiths. He called this problem "the filling in problem". See [ || ]×[18] for counterexamples in case of surfaces of general type. 'Theorem 1 is a generalization of some results of Kulikov ([15]). See also [19]. Our proof is entirely different form that of Kulikov's since in my opinion the method of Kulikov works only for $k 3$ surfaces.

The first examples of Hyper-Kählerain manifolds of dim $\geq 4$ were constructed by Fujiki [12]. These examples were generalized by Beauville and Miyaoka. See [1].

It is not very difficult to prove by the method used in the proof of Theorem 1 the' surjectivity of the period map for all Hyper-Kählerain manifold. This will be done in another paper.

Recently 0 . Debarre constructed using the so called elementary transformations introduced by Mukai in [17] two bimeromorphic but not biholomorphic non algebraic Kählerian manioflds. So the best we can hope in case of Hyper-Kählerian non-algebraic manifolds is that the Global Torelli theorem is true for bimeromorphic HyperKählerian maniofolds, i.e. if $X$ and $X$ ' have the same periods, i.e. isometric Hodge structe on $H^{2}(X, Z)$ and $H^{2}\left(X^{\prime}, z\right)$, then $X$ and $X^{\prime}$ are bimeromorphic.

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SO. SOME DEFINITIONS AND NOTATIONS

DEFINITION 0.1 . Let $X$ be a Mahler compact manifold such that: a) $\pi_{1}(X)=0$, i.e. $X$ is a simply connected manifold
b) $\quad \operatorname{dim}_{\mathbb{c}^{x}}=2 n$
c) $\operatorname{dim}_{\mathbb{C}^{H^{\circ}}}\left(\mathrm{X}, \Omega^{2}\right)=1$ and let $0 \neq \omega_{\mathrm{X}}(2,0) \in H^{\circ}\left(\mathrm{X}, \Omega^{2}\right)$, then $\omega_{\mathrm{X}}(2,0)$ is a non-degenerate holomorphic two form on $X$, which means that for each point $x \in X$, there exists an open neighborhood $u$ of $x$ and local coordinates $z^{1}, \ldots, z^{2 n}$ such that:

$$
\left.\omega_{X}(2,0)\right|_{U}=\Sigma \omega_{\alpha \beta} \partial^{2} \wedge d \cdot z^{\beta}
$$

and get $\omega_{\alpha \beta}$ is a holomorphic function in $U$ without zeroes and poles, ie. $\operatorname{det}\left(\omega_{\alpha \beta}\right) \in \Gamma\left(U, 0_{U}^{*}\right)$.

If a manifold $X$ is a Mahler one and fulfills a), b) and c) then we will called it Hyper-Kuhlerian manifold.

Examples of such manifolds are constructed in [/2] and [1].

Some notations:
$W_{X}(k, 0)$ will be a holomorphic $k$-form on $X$
$W_{X}(0, k)=\bar{w}_{X}(k, \sigma)$, 1.e. the autiholomorphick-forms on $X$ $D-w i l l$ be the unit disk, ie. $D=\{t \in \mathbb{C}| | t \mid<1\}$
$D^{*}=D \backslash\{0\}$.
If $\pi: X \longrightarrow D$ is a family of manifolds, then $X_{s}=\pi^{-1}(s)$.

If $g$ is a Riemannian metric on $X$ by $\nabla$ we will denote the Levi-Chevita connection on T*X, where TX is the tangent bundle on $X$ and $T * X$ is the cotangent bundle. By $T^{*} X \otimes \mathbb{C}$, we will denote the complexified cotangent bundle. $\nabla$ induces a covariant derivative on $\Lambda^{P_{T}}{ }^{*}$ for any $p \in \mathbf{z}$, this covariant derivative we will denote again by $\nabla$ $\Gamma\left(X, \Lambda^{p_{T}}\right)^{*}$ will be the global sections of the bundle $\Lambda^{P_{T}}$ *

If $\varphi \in \Gamma\left(X, \Lambda^{m}\left(T^{*} X \otimes \mathbb{C}\right)\right)$, then locally:

$$
\varphi=\sum_{p+q=m} \varphi_{A}, B_{q}, d z^{A}{ }^{A} \wedge \overline{\overline{B z}^{B_{q}}}
$$

where $A_{p}=\left(\alpha_{1}, \ldots, \alpha_{p}\right) \quad B_{q}=\left(\beta_{1}, \ldots, \beta_{q}\right)$ are multindexes
 local wordinates.

If $\varphi \in \Gamma\left(X, \Lambda^{P_{T}}{ }^{*} X\right)$ and $d \varphi=0$, then by $[\varphi]$ we will denote the class of cohomology that $\varphi$ defines in $H^{p}(X, R)$.
§1. PROOF OF THEOREM 1.

Theorem 1. Let $\pi^{*}: X^{*} \longrightarrow D^{*}$ be a family of non-singular Hyper-Kählerian manifolds such that:
a) $\pi^{*}: X^{*} \longrightarrow D^{*}$ has a trivial monodromy on $H_{2}\left(X_{t}, z\right)$, i.e. if $T: H_{2}\left(X_{t}, Z\right) \rightarrow H_{2}\left(X_{t}, Z\right)$ is the monodromy operator, then $T=i d$.
b)


Then there exists a family $\pi: X \longrightarrow D$ such that:
a) $\pi^{-1}(0)$ is a non-singular Hyper-kahlerian manifold (algebraic one)
b)

§1.1. Marked, polarized Hyper-Kählerian manifolds and their Hodge structures of weight two

DEFINITION 1.1.1. The tripple $\left(x ; \gamma_{1}, \ldots, \gamma_{b_{2}} ; L\right)$ we will call a marked, polarized Hyper-Kăhlerain manifold if $X$ is a Hyper-Kählerian manifold; $\quad \gamma_{1}, \ldots, \gamma_{p_{2}}$ is a basis of $H_{2}(X, z)$ and $L$ is the cohomology class of the imaginary part of a Kahler metric on $X$, i.e. $L=\left[g_{\alpha \bar{B}}\right]$.

Remark. Notice that two marked polarized Hyper-Kahlerian manifolds $\left(X ; \gamma_{1}, \ldots, \gamma_{p_{2}} ; L\right) \&\left(Y ; \mu_{1}, \ldots, \mu_{p_{2}} ; L^{1}\right)$ are isomorphic iff there exists a bihomomorphic map $\varphi: X \xrightarrow{\sim} Y$ such that
a) $\varphi_{*}\left(\gamma_{i}\right)=\mu_{i} ; \varphi_{*}: H_{2}(X, Z) \longrightarrow H_{2}(Y, I)$
b) $\left.\left.\varphi^{*}\left(L^{1}\right)=L ; \varphi^{*}: H^{2}(Y, Z) \longrightarrow H^{2}\right) X, Z\right)$

DEFINITION 1.1.2. Suppose that $\pi: X \rightarrow S$ is a family of non-singular Hyper-Kahlerian manifolds and suppose that the monodromy operator $T$ induced by the action of $\pi_{1}(S)$ on $H_{2}\left(X_{t}, z\right)$ is the identity operator. Now it is clear that
if we fix a basis $\gamma_{1}, \ldots, \gamma_{b_{2}}$ of $H_{2}\left(X_{t}, z\right)$, then since the monodromy operator is the trivial one we get that for every $s \in S \quad \gamma_{1}, \ldots, \gamma_{b}$ will be a basis in $H_{2}\left(X_{s}, z\right)$. Now we can define the period map:

$$
p: s \rightarrow P\left(H^{2}(X, \mathbb{L})\right)
$$

in the following manner:

$$
p(s)=\left(\ldots, \int_{\gamma_{i}} \omega_{s}(2.0), \ldots .\right)
$$

Now we want to see where the image of $S$ lie in $P\left(H^{2}(X, \mathbb{L})\right)$. So for that reason we will define a scalar product in $H^{2}(X, \mathbb{C})$, where $X$ is a marked polarized HyperKählerian manifold.

DEFINITION 1.1.3. The scalar product in $\cdot H^{2}(X, \mathbb{R})<,>$ is defined as follows:

$$
\left\langle w_{1}, w_{2}\right\rangle=\int_{x} w_{1} \wedge w_{2} \wedge L^{n-2} \text {, where } w_{1}, w_{2} \in H^{2}(X, R)
$$

and $L$ is the polarization class.

PROPOSITION 1.1.3.4. The scalar product $<$, $>$ has signature $\left(3, b_{2}-3\right)$, where $b_{2}=\operatorname{dim}_{R} H^{2}(X, R)$

Proof: Note that

$$
\langle L, L\rangle=\int f^{n}=\operatorname{vol}(X)>0, \text { where vol }(X) \text { is the volume }
$$ of $X$. with respect to the metric $\left(g_{a \bar{B}}\right)$, where $\left[g_{\alpha \bar{\beta}}\right]=$ L. Next we will prove the following relations:

(1.1.4.) $\left.\quad<\omega_{X}(2,0), \omega_{X}(2,0)\right\rangle=0$
$<\omega_{x}(2,0), \overline{\omega_{x}}(2,0) \gg 0$
(1.1.6)

$$
\left\langle\omega_{X}(2,0), L\right\rangle=0
$$

Notice that (1.1.4) and (1.1.6) follow from the definition of $\langle$,$\rangle . In order to prove (1.1.5) we need the following lemma:$

Lemma. If $\eta$ is a primitive form of type $(p, q)$, then

$$
*_{n}=\frac{(\sqrt{-1})^{p-q}}{(2 n-p-q)!}(-1)^{\frac{(p+q)(p+q+1)}{2}} x^{2 n-p-q} \bar{n}
$$

where * is the Hodge star operator. (For the proof see [81) From this lemma it follows that:

$$
\left\langle\omega_{X}(2,0), \overline{\omega_{X}(2,0)}=\int_{X} \omega_{X}(2,0) \wedge * \omega_{X}(2,0)=\left\|\omega_{X}(2,0)\right\|^{2}>0\right.
$$

So (1.1.5.) is proved.

Let $\omega_{X}(2,0)=\operatorname{Re} \omega_{X}(2,0)+i \operatorname{Im}{\underset{X}{x}}(2,0)$, then from (1.1.4.) and (1.1.5.) it follows that: <Re $w_{X}(2,0)$, Re $\left.\psi_{X}(2,0)\right\rangle=\left\langle\operatorname{Im} w_{X}(2,0)\right.$, $\left.\operatorname{Im} \omega_{X}(2,0)\right\rangle=\frac{1}{2}\left\|w_{X}(2,0)\right\|^{2}>0$ and $\left\langle\operatorname{Re} \omega_{X}(2,0), \operatorname{Im} \omega_{X}(2,0)\right\rangle=0$. So we see that $L, \operatorname{Re} w_{X}(2,0)$, Im $w_{X}(2,0)$ are three orthonormal vectors in
$H^{2}(X, \mathbb{R})$ such that:

$$
\langle L, L\rangle>0,\left\langle\operatorname{Re} \omega_{X}(2,0), \operatorname{Re} \omega_{X}(2,0)\right\rangle=\left\langle\operatorname{Im} \omega_{X}(2,0), \operatorname{Im} \omega_{X}(2,0) \gg 0\right.
$$

So we see that $<,>$ has at least signature $\left(3, b_{2}-3\right)$. Now since $H^{2}(X, \mathbb{R})=\mathbb{R} \operatorname{Re} \omega_{X}(2,0)+\mathbb{R} \operatorname{Im} \omega_{X}(2,0)+\mathbb{R} I+H^{1,1}(X, \mathbb{R})_{0}$ where $H^{1,1}(X, \mathbb{R})_{0}=\left\{\omega \in H^{1,1}(X, \mathbb{R}) \mid\langle\omega, L\rangle=0\right\}$, i.e. $H^{1,1}(X, \mathbb{R})_{0}$ are the primitive (1.1) classes in $H^{2}(X, \mathbb{R})$, we get that <,> has signature $\left(3, b_{2}-3\right)$. Indeed from the lemma used above it follows that if $\omega \in H^{1,1}(x, \mathbb{R})_{0}$ then $\langle\omega, \omega\rangle<0$. It is easy to see that $\left\langle\omega_{X}(2,0), \omega\right\rangle=0$ if $\omega \in H^{1,1}(X, \mathbb{R})_{0}$.
Q.E.D.

The scalar product (1.1.3) defines a nonsingular quadrics $Q$ in $P\left(H^{2}(X, \mathbb{C})\right)$ in the following way:
(1.1.7.) $\quad Q \stackrel{\text { def }}{\underline{E}}\left\{u \in \mathbf{P}\left(H^{2}(X, \mathbb{C})\right)|<u, u\rangle=0\right\}$

Let $\Omega$ be
(1.1.8.)

$$
\Omega \stackrel{\operatorname{de} \tilde{\mathrm{I}}}{=}\{u \in Q \mid\langle u, \bar{u} \gg 0\}
$$

$\Omega$ is an open subset in $Q$. Let

$$
\begin{equation*}
\Omega(L)=\{u \in \Omega|<u, L\rangle=0\} \tag{1.1.9.}
\end{equation*}
$$

From (1.1.4.), (1.1.5.) and (1.1.6.) and Griffith's theory [ ] we obtain that if $X \rightarrow S$ is a family of marked
polaxized Hyper-Kahlerian manifolds, then $p(S) \subset \Omega(L)$, where $p$.is the period map.

Definition 1.1 .10 . $\Omega(\mathrm{L})$ we will call the period domain of the polarized Hodge structure of weight two on HyperKählerian manifolds.
Remark 1.1.11. a) If $L \in H^{2}(X, Z)$, then $<,>$ is defined over 2.
b) It is not difficult to see that:

$$
\Omega(L) \equiv \operatorname{SO}_{0}\left(2, \mathrm{~b}_{3}-3\right) / \mathrm{U}(1) \times \mathrm{SO}_{2}\left(\mathrm{~b}_{2}^{-3)}\right.
$$

§ 1.2. Calabi-Yau metrics and isometric deformations of Hyper-Kählerian manifolds.

Definition 1.2.1. A Kahler metric $\left(g_{\alpha \bar{\beta}}\right)$ on a Hyper-Kählerian manifold will be called Calabi-Yau metric if

$$
\operatorname{Ricci}\left(g_{\alpha \bar{\beta}}\right)=\text { する } \log \operatorname{det}\left(g_{\alpha \bar{\beta}}\right) \equiv 0
$$

The existence of Calabi-Yau metric follows from the deep work of Yau [22]. Notice that in the polarization class of $L$, there exists a unique Calabi-Yau metric $g_{a \bar{\beta}}$ such that

$$
\left[g_{\alpha \bar{\beta}}\right] \equiv L
$$

Let us fix the Calabi-Yau metric $\quad g_{\alpha \bar{B}}$ in L. This metric induces covariant differenciation on $\Lambda^{2}(T * x \bullet a)$. We will denote it by $\nabla$.

Lemma 1.2.2. $\nabla \omega_{X}(2,0)=\nabla \omega_{X}(0,2) \equiv 0$

Proof: The following formula is proved in [14]:
Let $\varphi$ be a form of type ( $p, q$ )

$$
\varphi=1 / p!q!\quad \sum \varphi_{A_{p}}, \bar{B}_{q} d z^{A_{p}} \wedge \overline{\mathrm{~B}}^{\bar{B}} q
$$

$A=\left(\alpha_{1}, \ldots, \alpha_{p}\right) ; B=\left(\beta_{1}, \ldots, \beta_{q}\right)$
(1.1.2.1.) $\quad(\square \varphi)\left(A_{p}, \bar{B}_{q}\right)=-\sum_{\alpha, \beta} g^{\bar{\beta} \alpha_{\nabla_{\alpha}} \bar{\nabla}_{\beta}{ }^{\varphi}\left(A_{p}, \bar{B}_{q}\right)+}$


$$
\begin{aligned}
& \left.\bar{\beta}_{k+1}, \ldots, \bar{\beta}_{q}\right) \\
& -\sum_{k=1}^{q} \sum_{\tau} R_{\bar{\beta}^{\tau}} \bar{\tau}^{\prime} \varphi\left(A_{p}, \bar{\beta}_{1}, \ldots, \bar{\beta}_{k-1}, \bar{\tau}_{\tau}, \bar{\beta}_{k+1}, \ldots, \bar{\beta}_{q}\right)
\end{aligned}
$$

where $\quad$ is the Laplace-Beltrami operator, $R_{\bar{\alpha} \beta^{\prime}} \bar{\gamma} \sigma$ is the curvature tensor, $R_{\bar{\mu} \nu}$ is the Riccio tensor and $\left(g^{\bar{B} \alpha}\right)=\left(g_{\mu \sigma}\right)^{1}$.

$$
\text { In our case } R_{\mu \nu} \equiv 0 \text { and } \omega_{x}(0,2) \text { is an anti-holomorphic }
$$ two-form, so we obtain:

(1.2.2.2.) $\quad \square \omega_{X}(0,2)=-\sum_{\beta} \quad \beta \alpha_{\alpha} \nabla_{\beta} \omega_{X}(0,2) \equiv 0$

On the other hand it is easy to see:

$$
\begin{aligned}
0 & \left.=\int_{x} \sum_{i, j} \sum_{\beta, \alpha} g^{\bar{\beta} \alpha^{\prime}} \nabla_{\alpha} \bar{\nabla}_{\beta} \omega_{X}(0,2)\right)_{i j} \overline{\left(\omega_{X}(0,2)\right)^{i j}} \operatorname{det}\left(g_{\alpha, \beta}\right) 1 / n!= \\
& =\sum_{\beta}\left\langle\bar{\nabla}_{\beta} \omega_{X}(0,2), \bar{\nabla}_{\beta} \omega_{X}(0,2)\right\rangle, \text { where here }\left\langle\omega_{1}, \omega_{2}\right\rangle \text { means, }
\end{aligned}
$$

that $\left\langle\omega_{1}, \omega_{2}\right\rangle=\int_{x} \omega_{1} \wedge * \omega_{2}$ (* is the Hodge star operator.) So we obtain that

$$
\sum_{\beta}\left\|\bar{\nabla}_{B}\right\|_{X}(0,2) \|^{2}=0 \neq \bar{\nabla}_{B^{\omega}}(0,2) \equiv 0 .
$$

Q.E.D.

Corollary 1.2.3. If $\omega_{X}(2,0)=\operatorname{Re} \omega_{X}(2,0)+i \operatorname{Im} \omega_{X}(2,0)$, then

$$
\nabla \operatorname{Re} \omega_{X}(2,0) \equiv \nabla \operatorname{Im} \omega_{X}(2,0) \equiv 0
$$

(1.2.4) From the definition of a Kahler metric, it follows that

$$
\nabla\left(i \sum_{\alpha \bar{B}} d z^{\alpha} \wedge d \bar{z}^{B}\right)=\nabla\left(\operatorname{Im} g_{\alpha \bar{B}}\right) \equiv 0
$$

Re $\omega_{X}(2,0)$. $\operatorname{Im} \omega_{X}(2,0)$ and $\operatorname{Im}\left(g_{\alpha \sigma}\right)$ define a three dimensional subsapce $E_{X}(L)$ in $\Gamma\left(X, \Lambda^{2} T^{*} X\right)$. Notice that $E_{X}(L)$ consists of two forms parallel with the respect to the connection induced by the Calabi-Yau metric $\left(g_{\alpha \bar{\beta}}\right)$. Since Re $\omega_{X}(2,0)$, Im $\omega_{X}(2,0)$ are harmonic forms, we may consider $E_{X}(L)$ as a subspace in $H^{2}(X, R)$. We may suppose that $<R e \omega_{X}(2,0)$, $\left.\operatorname{Re} \omega_{x}(2,0)\right\rangle=\left\langle\operatorname{Im} \omega_{X}(2,0), \operatorname{Im} \omega_{X}(2,0)\right\rangle=\left\langle\operatorname{Im} g_{\alpha \vec{B}}, \operatorname{Im} g_{\alpha \bar{B}}\right\rangle=1$. On the other hand $\left\langle\operatorname{Re} \omega_{X}(2,0), \operatorname{Im} v_{X}(2,0)\right\rangle=\left\langle\operatorname{Re} \omega_{X}(2,0)\right.$, $\left.\operatorname{Im}\left(g_{a \bar{B}}\right)\right\rangle=\left\langle\operatorname{Im} \omega_{X}(2,0)\right.$, $\left.\operatorname{Im}\left(g_{\alpha \bar{B}}\right)\right\rangle=0$. So $\operatorname{Re} \omega_{X}(2,0)$, $\operatorname{Im} \omega_{X}(2,0)$ and $\operatorname{Im}\left(g_{\alpha \bar{\beta}}\right)$ is an orthonormal base in $E_{X}(L) \subset \Gamma\left(X, \Lambda^{2} T^{*}\right)$ with respect to the scalar product induced by $g_{a \bar{\beta}}$ in $\Lambda^{2} T^{*}$. Notice that this scalar product is the same as $<,>$ defined by (1.1.3).

Let $\gamma=a \operatorname{Re} \omega_{X}(2,0)+b \operatorname{Im} \omega_{X}(2,0)+c \operatorname{Im}\left(g_{\alpha \bar{B}}\right)$, where $a, b, c \in \mathbb{R}$ and $a^{2}+b^{2}+c^{2}=1$. Since $\gamma \in E_{x}(L)$, then
(*)

$$
\nabla \gamma \equiv 0
$$

Locally $\gamma$ can be written in the following way

$$
\gamma=\sum \gamma_{\mu \nu} d x^{\mu} \wedge d x^{v}
$$

If $\sum_{\tau, \nu} g_{\tau \nu} d x^{\tau} \otimes d x^{\nu}$ is the Riemannian Ricci flat metric on $X$ defined by the Calabi-Yau metric $\left(g_{\alpha \bar{\beta}}\right)$ on $X$, then we will define $J(\gamma)$ in the following manner 1.2.6. $J(\gamma) \in \Gamma(X, T * \otimes T)$, where $J(\gamma)_{\beta}^{\alpha} \operatorname{def}^{f} \sum_{\tau} g^{\alpha \tau} \gamma_{\tau \beta}$ Clearly $\quad \nabla(J(\gamma)) \equiv 0$.

Lemma 1.2.7. a) $J(\gamma)$ defines a new integrable complex structure on $X$
b) $\gamma$ is an imaginary part of a Calabi-Yau metric with respect to the new complex struture $J(\gamma)$. The Calabi-Yau metric defined by $\gamma$ and $J(\gamma)$ is equivalent as a Riemannian metric to the Calabi-Yau metric $g_{\alpha \bar{B}}$, that we started with. Proof: Since $\nabla \mathcal{J}(\gamma) \equiv 0$ if we prove that in one point $x \in X$ $J(\gamma) \circ J(\gamma)=-i d$, then $J(\gamma)$ will define an almost complex structure globally on $X$. Then we will need to show that this complex struture is an integrable one.

So first we will prove that at one point $x \in X$ $J(\gamma) \cdot J(\gamma)=-i d$. First since $\omega_{X}(2,0)$ is a parallel with
respect to the connection induced by Calabi-Yau metric, it follows that the holonomy group of the Calabi-Yau metric is $\mathrm{Sp}(\mathrm{n})$. This means that globally we can find $j \in \Gamma\left(X, T^{*} \bullet T\right)$ such that $\nabla j=0$ and we have at each point $x$

$$
\mathrm{T}^{*}{ }_{x, x}^{1,0}=\boldsymbol{H}^{n}={e^{n}}^{n}+{c^{n}}^{n}
$$

This splitting is global. On the other hand the Calabi-Yau metric on $T_{X}^{*}{ }^{1,0}=X^{n}=\mathbb{R}^{n}+\mathbb{R}^{n_{i}}+\mathbb{R}^{n_{j}}+\mathbb{R}^{n_{k}} \quad$ is induced by the standart scalar product on $H^{n}$, so from here it follows that we can find an orthonormal quaternionic base in

$$
T_{x, X}^{1,0}=a^{n}+a^{n} j
$$

$h_{1}^{1}=e_{1}^{1}+e^{1+n} j, h^{2}=e^{2+n_{j}}, \ldots . h^{n}=e^{n}+e^{2 n} j$. Then the imaginary part of Calabi-Yau metric can be written in the following way:

$$
\begin{equation*}
\left.\operatorname{Im}\left(g_{\alpha \bar{\beta}}\right)\right|_{T \times, 1,0}=i \sum_{i=1}^{2 n} e^{i} \wedge e^{i} \tag{*}
\end{equation*}
$$

(**) and $\left.\omega_{x}(2,0)\right|_{T^{*}{ }_{x, 0}, 0^{\prime}=e^{1} \wedge e^{1+n}+e^{2} \wedge e^{2+n}+\ldots+e^{u} \wedge e^{2 n}=}$

$$
\sum_{i=1}^{n} e^{i} \wedge e^{i+n}
$$

Let us denote by $I$ the original complex structure on X. Notice that $J\left(I m g_{a \bar{B}}\right)=I$. (See how we defined from $Y$ $I(\gamma))$. Let us denote by $J=J\left(\operatorname{Re} \omega_{X}(2,0)\right)$ and by $K=J\left(\operatorname{Im} \omega_{X}(2,0)\right)$. From (*) and (**) we see immediately that:
(***)

$$
I^{2}=J^{2}=K^{2}=-i d, \quad I J+J I=I K+K I=J K+K J=0
$$

So remember that $\gamma=a \operatorname{Re} \omega_{X}(2,0)+\operatorname{bIm} \omega_{X}(2,0)+c I m\left(g_{\alpha \bar{B}}\right)$, so

$$
I(\gamma)=a J+b K+c I, a^{2}+b^{2}+c^{2}=1
$$

So from (***) we get

$$
I(\gamma) \circ I(\gamma)=a^{2} J \circ J+b^{2} K \circ K+c^{2} I \circ I=-\left(a^{2}+b^{2}+c^{2}\right) i d=-1 a
$$

So we have proved that $I(\gamma)$ defines an almost complex structure on $X$. Next we must prove that the almost complex structure $J(\gamma)$ is integrable. The proof is based on the following fact:

## Andreotti-Weil remark

Let $\omega$ be a n-complex valued form in a neighborhood $U$ of a point $x \in X$, where $X$ is a $n$-dimensional real manifold. Let $\omega$ satisfies:
a) $P(\omega)=0$, where $P$ are the Plücker relation. This means that at each point $x \in X \quad{ }^{\omega} \mid x \in X^{x}=\zeta^{1} \wedge \ldots \wedge \zeta^{n}, \zeta^{i} \in T_{x, X}^{*} \otimes \mathbb{C}$, so $\omega$ defines a subspace $T_{x}^{1,0} \subset T_{X, X}^{*} \otimes \mathbb{C}$ at each point $x \in V$
b) $w \wedge \bar{w}=f\left(x_{1}, \ldots, x_{2 n}\right) d x^{1} \wedge \ldots \wedge d x^{2 n}$, where $f\left(x_{1}, \ldots, x_{-2 n}\right)>0$ in U. This means that $T_{X}^{1,0}+\bar{T}^{1,0}=T_{X, X}^{*} \otimes a$ in U.
c) $d w=0$

Notice that a) and b) means that $w$ defines an almost complex struture in $U$. The condition c) means that this complex struture is integrable.

So in order to use Andreotti-Weil remark we need to construct the form $w$, that satisfies a), b) and c). So first we will constructaglobally ciefined form ${ }^{\omega_{J}}(\gamma)(2,0)$ of type $(2,0)$ with respect ot $J(\gamma)$ and then we will prove that:

$$
{ }^{\omega_{J(\gamma)}(2 n, 0)}=\underbrace{\omega_{J i m e s}}_{\underbrace{}_{J(\gamma)}(2,0) \wedge \ldots \wedge{ }_{J(\gamma)}(2,0)}
$$

fulfills the conditions of Andreotti-Weil's remark.

## Constructions of ${ }^{\omega} J(\gamma) \xlongequal{(2.0)}$.

Let $(\alpha, \beta, \gamma)$ be an orthonormal base of $E_{X}(L) \subset \Gamma\left(X, \Lambda^{2} T * X\right)$ with respect to the scalar product induced by Calabi-Yau metric in $r\left(X, \Lambda^{2} T^{*} X\right)$. We suppose that $(\alpha, \beta, \gamma)$ define the same orientation on $E_{X}(L)$ as $\left(\operatorname{Re} u_{X}(2,0), \operatorname{Im} \omega_{X}(2,0), \operatorname{Im}\left(g_{\alpha \bar{\beta}}\right)\right)$.

$$
\begin{equation*}
\omega_{J(\gamma)}(2,0) \stackrel{\operatorname{def}}{=} \alpha+i \beta \tag{1.2.7.1}
\end{equation*}
$$

Proposition (1.2.7.2.) $\quad \omega_{J(\gamma)}(2,0)=\alpha+i \beta \quad$ is a form of type ( 2,0 ) with respect to the almost complex structure on $x$ defined by $J(\gamma)$.

Proof: Since both $\omega_{J}(\gamma)(2,0)$ and $J(\gamma)$ are paraller with respect to the connection $\nabla$ induced by Calabi-Yau metric $\left(g_{a \bar{B}}\right)$, we need to check that $\omega_{J(\gamma)}(2,0)$ is a form of type $(2,0)$ at one point $x$ with respect to $J(\gamma)$. We will define an action of $\operatorname{Sp}(1)$ on $T * X$. Remember that the holonomy group
of the Calabi-Yau metric $\left(g_{\alpha \bar{\beta}}\right)$ was $\operatorname{Sp}(n)$, so we can introduce on $T_{X, X}^{*}$ a quaternionie structure, i.e.

$$
\mathrm{T}_{\mathrm{X}, \mathrm{X}}^{*}=\mathbb{a}+\mathbb{C}^{\mathrm{n}}=\mathbf{H}^{\mathrm{n}} \quad(\mathbf{H} \quad \text { is the quaternionic field })
$$

( $g_{\alpha \bar{\beta}}$ ) is induced in $H^{n}$ by the standart quaternionic scalar product, i.e. let $h^{1}=e^{1}+e^{n+1} j, \ldots, h^{n}=e^{n}+e^{2 n} j$ is a quaternionic orthonormal basis in $\mathbf{H}^{n}$, then the restriction of Calabi-Yau's metric on $T_{X, X}^{*}$ is obtained from the following quaternionic product in $\mathbb{H}^{n}$. Let $u=\sum_{i=1} h^{i} u_{i}$ and $v=\sum_{i=1}^{n} h^{i} v_{i}$, where $v_{i} \in \mathbf{H}$, then

$$
\langle u, v\rangle=\sum u_{i} \bar{v}_{i}
$$

Now we can identify $\operatorname{Sp}(1)=\{A \in \mathbf{H} \mid M \bar{A}=1\}$. Then $\mathrm{Sp}(1)$ acts on $\mathbf{H}^{\mathrm{n}}$ in the following way:

Let $A \in S p(1)$ and let $u=\sum h^{i} u_{i}$, then

$$
A u=\left\{h^{i} u_{i} A, \text { where } \operatorname{Sp}(1)=\left\{A \in H \mid\|A\|^{2}=1\right\}\right.
$$

Clearly $\operatorname{Sp}(1) \subset S p(n)$; i.e. this action of $S p(1)$ preserves the quaternionic scalar product $\langle u, v\rangle=. \sum u_{i} \bar{u}_{i}$.

## The following remark is an easy exercise.

Remark 1. $\operatorname{Sp}(1)$ induces an action on $\Lambda^{2} T_{X, X}^{*}$ and $E_{X}(L) \subset$ $\subset \Gamma\left(X, \Lambda^{2} T * X\right)$ is invariant under this induced action of $S p(1)$. More over $\operatorname{Sp}(1)$ induces the standart $S O(3)$ action on $E_{x}(L)$ with respect to the Euclidean metric on $E_{X}(L)$ induced by the orthonormal basis $\left(\operatorname{Re} \omega_{x}(2,0), \operatorname{Im} \omega_{x}(2,0), \operatorname{Im}\left(g_{\alpha \bar{\beta}}\right)\right)$. From Remark 1
it follows immediately that there exists $A \in S p(1) \subset S p(n)$ such that:

$$
\begin{equation*}
A\left(\operatorname{Re} \omega_{x}(2,0)=\alpha, A\left(\operatorname{Im} \omega_{x}(2,0)\right)=B, A\left(\operatorname{Im}\left(g_{\alpha \bar{B}}\right)\right)=\gamma\right. \tag{**}
\end{equation*}
$$

So

$$
A\left(\omega_{x}(2,0)\right)=\omega_{J(\gamma)}(2,0)
$$

On the other hand from the definition of $J(\gamma)$ we see immediately that

$$
\begin{aligned}
(* * *) \quad J(\gamma)=A I A^{t} \quad & \left(A \text { means a matrix and } A A^{t}=E\right. \\
& \text { since } A \in \operatorname{Sp}(1) \subset \operatorname{Sp}(n) \subset S O(4 n))
\end{aligned}
$$

So from (**) and (***) we get that $\omega_{J(\gamma)}(2,0)$ is a form of type $(2,0)$ with respect to the almost complex structure $J(\gamma)$. This is so since if $\Lambda^{2,0}$ is the subspace of $(2,0)$ vectors in $\Lambda^{2}\left(T_{X, X}^{*}\right.$ © $)$ with respect to $I$ and if $J(\gamma)=A I A^{t}$, then $A\left(\Lambda^{2,0}\right)$ is the $(2,0)$ subspace of $\Lambda^{2}\left(T_{X}^{*}, X \in \mathbb{C}\right)$ with respect to $J(\gamma)=A I A^{t}$.
Q.E.D.

Now we need to show that

$$
\omega_{J(\gamma)}(2 n, 0)=\underbrace{\omega_{J \text {-times }}}_{V_{J(\gamma)}(2,0) \wedge \ldots \wedge \omega_{J(\gamma)}(2,0)}
$$

fulfills the conditions a), b) and c) of Andreotti-Weil remark. Condition al is fulfilled since $\omega_{J(\gamma)}(2 n, 0)$ is a $(2 n, 0)$ type of form with respect to the almost complex structure operator $J(Y)$ acting on $X$ and $\operatorname{dim}_{R} X=4 n$
b) It is easy to see that $\omega_{J(\gamma)}(2 n, 0) \wedge \overline{\omega_{J(\gamma)}}{ }^{(2 n, 0)}=\operatorname{vol}\left(g_{\alpha \bar{\beta}}\right)$ at each point $x \in X$.
c) From the definition of $\omega_{J(\gamma)}(2,0)$ it follows that

$$
\mathrm{d} \omega_{J}(\gamma)(2,0) \equiv 0
$$

So $\quad d \omega_{J(\gamma)}(2 n, 0) \equiv 0$.
Q.E.D.

Proof of (1.7.3.b): If $\gamma=\int \gamma_{\mu \nu} d x^{\mu} \wedge d x^{\nu}$, then $\gamma$ defines a scalar product in $\mathbb{T}_{x, X}^{*}$ in the following way: Let $u=\sum u_{\alpha} d x^{\alpha}$ and $y=\sum v_{\beta} d x^{\beta}$, then $\langle u, v\rangle_{\gamma}=\sum u_{\alpha} \gamma_{\alpha \beta} u_{\beta}$

So if we prove that for each $u \in T_{x, X}^{*}$ we have: $\left.\langle J(\gamma), u, u\rangle_{\gamma}\right\rangle 0$
then we will have that $\gamma$ is an imaginary part of a Kähler metric on $X$ with respect to $J(\gamma)$ since $d \gamma=0$. So we may suppose that at $x \in X\left(g_{\alpha \bar{\beta}}\right)=\delta_{\alpha \bar{\beta}}$, then:

$$
J(\gamma)_{\beta}^{\alpha}=\gamma_{\alpha \beta}, \gamma_{\alpha \beta}=-\gamma_{\beta \alpha} \text { and } \gamma_{\alpha \beta} \gamma_{\beta \mu}=-\delta_{\alpha \mu}
$$

Now if $u=\sum u_{\alpha} d x^{\alpha}$, then

$$
\begin{aligned}
& \left\langle J(\gamma) u_{r} u\right\rangle_{\gamma}=\sum \gamma_{\mu \alpha} u_{\alpha} \gamma_{\mu \beta}=\sum u_{\alpha}\left(-\gamma_{\alpha \mu}\right) \gamma_{\mu \beta} u_{\beta}= \\
& =\sum u_{\alpha}\left(-\delta_{\alpha \beta}\right) u_{\beta}=\sum u_{\alpha}^{2}>0
\end{aligned}
$$

The last calculation show that $\gamma$ is an imaginary part of a Kahler metric on $X$ with respect to the complex structure $J(\gamma)$ and this new Kahler metric is equivalent as Riemann
metric to the Calabi-Yau metric we started with.
Q.E.D.

Remark 1.2.8. Lemma 1.2 .8 shows that every oriented two plane $E \subset E_{X}(L) \subset \Gamma\left(X, \Lambda^{2} T * X\right)$ defines a new complex structure on $X$. So we obtain a family $x \rightarrow s^{2}$, where $s^{2}=\left\{\gamma \in E_{X}(L) \mid\langle\gamma, \gamma\rangle=1\right\}$. Every point $t \in S^{2}$ defines an oriented two plane $E_{t} \subset E_{x}(L)$ in the following manner: $E_{t}=\left\{\operatorname{Re} \omega_{t}(2,0)\right.$, In $\left.\omega_{t}(2,0)\right\}$. Notice the conjugate complex structure on $X_{t}$ defines the same $E_{t} \subset E_{x}(L)$ but with different orientation, since $\overline{\omega_{t}}(2,0)$ is the holomorphic twoform with respect to the conjugate complex structure and

$$
\overline{\omega_{t}}(2,0)=\operatorname{Re} \omega_{t}(2,0)-1 \operatorname{Im} \omega_{t}(2,0)
$$

See also [7].

## § 1.3. Hilbert scheme of Hyper-Kahlerian manifolds

Let $X$ be a projective Hyper-Kahlerian manifold embedded
in $\mathbf{P}^{\mathbf{N}}$. Fubbini-Schtudy metric on $\mathbf{P}^{\mathbf{N}}$ in a natural way defines a class of polarization $L$. on $X$. Let us denote by $\widetilde{H i l b}_{X / \mathbb{P}} N$, the component of the Hilbert scheme that contains $X$. Let $H i l b X / \mathbf{P}^{N}$ be a subscheme of $\widetilde{H i l b} \cdot X / \mathbb{P}^{N}$ such that $\mathrm{Hilb}_{\mathrm{X} / \mathrm{p}^{N}}$ parametrizes all non-singular HyperKählerian manifolds in the family $\tilde{\chi}^{\rightarrow}+\overparen{H i l b}_{\mathrm{X} / \mathbb{P}^{N}}$. Grothendieck proved in SGA, that $H i l b_{X / \mathbb{P}^{N}}$ is a quasi-projective algebraic space.

Definition 1.3.1. $\quad \Gamma_{L} \stackrel{\text { def }}{=}\left\{\gamma \in\right.$ Aut $H^{2}(X, Z) \mid\langle\gamma(u), \gamma(u)\rangle=$ $\mp\langle u, u\rangle, \gamma(L)=L\}$. Now we can define the period map $p: H i l b_{X / P^{N}} \rightarrow \Omega(L) / \Gamma_{L}$. From the general Baily-Borel compactification theory, it follows that $\Omega(L) / \Gamma_{L}$ is a quasi-projective manifold.

Lemma 1.3.2. There exists an open Zariski set $H^{\prime} b^{\prime} X / \mathbb{P}^{N} \subset$
 subset in $\Omega(L) / r_{L}$ and every point of $W$ corresponds to the algebraic Hyper-Kählerian manifold.

Proof: From the famous Hironaka's "resolution of singularity" theorem it follows that we can compactify $\operatorname{Hilb}_{X / \mathbb{P}^{N} \subset \hat{H i l b}}^{X / P^{N}}$ in such a way that:

1) $\operatorname{Hilb}_{X / \mathbb{P}^{N}}$ is a projective manifold obtained from projective manifold by successive blows up on non-singular submanifolds.
2) $\hat{H i l b}_{X / P N} \backslash \operatorname{Hilb}_{X / \mathbf{p}^{N}}=\mathrm{D}$ is a divisor with normal crossings Borel proved in [5] that the period map:

$$
\mathbf{p}: \mathrm{Hilb}_{\mathbf{X} / \mathbf{P}^{N}} \rightarrow \Omega(L) / \Gamma_{L}
$$

can be prolonged to a map:

$$
\hat{p}: \hat{\mathrm{Hilb}}_{\mathrm{X} / \mathrm{P}^{N}} \rightarrow \overline{\Omega(\mathrm{~L}) / \mathrm{I}_{\mathrm{L}}}
$$

where $\overline{\Omega(L) / \Gamma_{L}}$ is the Baily-Borel compactification of $\Omega(L) / \Gamma_{L}$. From Baily-Borel theory it follows that $\Omega(L) / \Gamma_{L}$ is a Zariski open set in $\overline{\Omega(L) / \Gamma_{L}}$, and $\overline{\Omega(L) / \Gamma_{L}}$ is a projective algebraic variety.

Proposition 1.3.2.1. The map $\hat{p}: \hat{H i l b}_{X / P N} \rightarrow \hat{\Omega(L) / \Gamma_{L}}$ is a surjective map.

Proof: First we will recall some facts about local deformation theory of Hyper-Kählerian manifolds due to Bogomolov: The Kuranishi space of any Hyper-Kahlexian manifold is a nonsingular manifold of dimension $h^{1,1}=\operatorname{dim}_{a^{H}}\left(^{1}\right)$. See [4].

For trivial reasons the local Torelli theorem is true for the period map defined in § 1.1. Beauville proved in [1] that $p(U)$ lies in the open set of the quadric $Q$ defined by (1.1.7.) and (1.1.8.). So we may suppose that $U$ is an open set in $Q$. Let $U_{L}$ be defined as follows a point $t \in U_{L}$ jiff $L$ is a class of type (1.1) in the Hyper-Kahlerian manifold $X_{t}$ that corresponds to the point $t$. So $U_{L}=U \cap H_{L}$, where $H_{L}$ is the hyperplane in $P\left(H^{2}(X, \mathbb{C})\right)$ defined by:

$$
\mathrm{B}_{\mathrm{L}}=\left\{u \in \mathbb{P}\left(\mathrm{H}^{2}(\mathrm{X}, \mathrm{C})\right) \mid\langle u, L\rangle=0\right\}
$$

So $\operatorname{dim}_{c_{L}} U_{L^{1,1}}-1=\operatorname{dim} \Omega(L) / \Gamma_{L}$. On the other hand we have a family ${\underset{U}{L}}_{X_{L}}$. Now $L_{t} \in H^{1,1}\left(X_{t}, Z\right)$ is a fix class so
from here we obtain a line bundle $L$ on $X_{L}$. Now suppose that $L_{\mid X_{t}}=L_{t}$ is a very ample line bundle, i.e. if $\varphi_{0}, \ldots, \varphi_{N} \in H^{0}\left(X_{t}, L_{t}\right)$ and $\left(\varphi_{0}, \ldots, \varphi_{N}\right)$ is a basis of $H^{0}\left(X_{t}, L_{t}\right)$, then $\varphi_{0}, \ldots, \varphi_{N}$ define an embedding

$$
x_{t} \hookrightarrow \mathbf{p}^{N}
$$

By continuity argument we will get (that may be after shrinking $U_{L}$ ):


From the universal properties of $H i l b \cdot \mathrm{X} / \mathbb{P N}$ it follows that $\mathrm{U}_{\mathrm{L}} \subset \mathrm{Hilb}_{\cdot \mathrm{X} / \mathbb{P}^{N}}$, so from here we get that

$$
\operatorname{dim}_{\mathbb{C}} \hat{p}\left(\hat{\operatorname{Hi}}^{\hat{1}} b_{\mathrm{X} / \mathbb{P}^{N}}\right)=\operatorname{dim}_{\mathbb{Q}} \overline{\Omega(L)} / \Gamma_{L} .
$$

Now since $\hat{p}$ is a projective morphism and so $\hat{p}$ is proper we get that $\hat{p}\left(H i l b_{X / p^{N}}\right)=\overline{\Omega(L)} / \Gamma_{L}$
Q.E.D.

Now since the map $: \hat{p}: \hat{H i l b} b_{X} / p N \rightarrow \overline{\Omega(L)} / L$ is a proper surjective map, then $P(D)=p\left(H i l b_{X / \mathbb{P N}} \backslash H i l b_{X / \mathbb{P}}{ }^{N}\right)=\bar{V}$ is a proper analytic subset in $\overline{\Omega(L)} / T_{L}$. Let
$\mathrm{V} \mp \overline{\mathrm{V}} \cap(\overline{\mathrm{V}} \cap(\overline{\Omega(L)} / \Gamma) \backslash(\Omega(\mathrm{L}) / \mathrm{F}))$ and let. $W=\Omega(\mathrm{L}) / \Gamma_{\mathrm{L}} \backslash \mathrm{V}$. Clearly W is a Zariski open subset in $\Omega(L) / \Gamma_{L}$. Now let


$$
p\left(H_{i l l} b^{\prime} X / \mathbf{P}^{N}\right)=W
$$

So $H^{\prime 1 b^{\prime}} \mathrm{X} / \mathrm{P}^{\mathrm{N}}$ is what we need.
Q.E.D.

It was proved by Bogomolov that $H_{i l b} x / P^{N}$ is a non-singular manifold. [4]

## § 1.4. Proof of theorem 1

Since the monodromy operator:

$$
T: H^{2}\left(X_{t}, z\right) \rightarrow H^{2}\left(X_{t}, z\right)
$$

is the identity operator, from theorem 9.5. in [13] it follows that the period map:

$$
\mathrm{P}^{*}: \mathrm{D}^{*} \rightarrow \Omega(\mathrm{~L}) \xrightarrow{\tau} \Omega(\mathrm{L}) / \mathrm{r}_{\mathrm{L}}
$$

can be prolonged to a map

$$
\mathrm{p}: \mathrm{D} \rightarrow \Omega(\mathrm{~L}) \xrightarrow{\tau} \Omega(\mathrm{L}) / \Gamma_{L}
$$

Let $p(0)=x_{0} \in \Omega(L) / \Gamma_{L_{0}}(0 \in D)$. From $§ 1.2$. we know that there exists a proper map $\hat{p}: H \hat{i} 1 b_{X / I p^{N}} \rightarrow \overline{\Omega(L) / \Gamma}{ }_{L}$, where $\overline{\Omega(L) / \Gamma_{L}}$ is the Baily-Borel compactification and $\hat{H i l b} X / P^{N}$ is obtained from the component of the Hilbert scheme Hill $x / p^{N}$ that contains $x$ by successive blows up along non-singular submanifolds contained in $\widetilde{H i l b}_{x / \mathbb{P}^{N}}>. \mathrm{Hilb}_{\mathrm{X} / \mathrm{P}^{N}} \cdot\left(\mathrm{Hilb}_{\mathrm{X} / \mathbb{P}^{N}}\right.$ is a non-singular manifold. So from Hironaka theorem it follows that we can find in this way Herl $_{x / 3 \mathrm{pl}}$ such that:
a) $\mathrm{Hilb}_{X / \not P^{N}} \mathrm{Hilb}_{\mathrm{X} / \mathrm{PN}}$ is a divisor with normal crossings
b) There exists a family $\hat{X} \rightarrow \mathrm{Hin}_{\mathrm{X}}^{\mathrm{X} / \mathrm{pN}}$ and it is defined
in the following way, let $\hat{\pi}: H \hat{i} l b_{X / \mathbb{P}}{ }^{N} \rightarrow H i l b_{X / \mathbb{P}}$ be the natural map obtained by blowing down, then $\hat{X} \rightarrow H \hat{i} 1 b_{X / \mathbb{P}}{ }^{N}$ is $\hat{\pi}^{*} \tilde{X} \rightarrow \operatorname{Hin}_{X / \mathbb{P}^{N}}$, where $\tilde{\chi}^{\chi}+\hat{H i l b}_{X / \mathbb{P}^{N}}$ is the universal family. For each $t \in p\left(D^{*}\right)$ clearly $p^{-1}(t)$ consist of the orbit of $x_{t_{i}}$ under the natural action of $\mathrm{FGL}(N)$ on Hilb $_{X_{k} / I P N}$, where $\dot{x}_{t_{i}}$ corresponds to the Hyper-Kählerian manifold $X_{t_{i}} \hookrightarrow{\underset{D}{*}}_{*}^{x^{*}}$ and $t_{i}$ are all points in $D^{*}$ such that $p\left(t_{i}\right)=t \in p\left(D^{*}\right) \subset \Omega(L) / \Gamma_{L}$. Suppose that

$$
\hat{\operatorname{Hill}_{\hat{X} / \mathbb{P}} \mathrm{N}} \quad \hookrightarrow \quad \mathbf{P}^{\mu}
$$

and $D_{1}$ is a disk in $p\left(D^{*}\right) \subset \Omega(L)$ such that $\overline{D_{1}}$ (the closure of
 there exists a plane $\mathbf{p}^{2} \subset \mathbf{p}^{\mu}$ such that it intersects the orbits of the Hyper-Kählerian manifolds corresponding to. the points in $D_{1}$ in $H_{i l b}{ }_{X / \mathbb{P}^{N}}$ under the action of $P G L(N)$ transversally and $\mathbf{P}^{2}$ intersects $\operatorname{Hilb}_{X / \mathbb{P}^{N}} \subset \mathbb{P}^{\mu}$ transversally in a point $g_{0} \in \Pi^{-1}\left(x_{0}\right)$. It is a standart fact that such $\mathbf{P}^{2}$ exists. Let now $D \subset \mathbf{P}^{2} \cap \hat{H i l b} X_{X / P^{N}}$, where $g_{0} \in D$ and ${ }^{D}\left(\theta_{0}\right)^{D^{*} \subset H i l b_{x / P^{N}}}$. From the way we define $D$. it follows that

$$
\mathrm{p}: \mathrm{D} \hookrightarrow \Omega(\mathrm{~L}) / \Gamma_{\mathrm{L}}
$$

So from now on instead of the family
we will consider the family obtained from $\pi: X \rightarrow D$ by the pull back of the natural map $D+D$ induced from the map $: \Omega(L)+\Omega(L) / \Gamma_{L}$. We will denote this new family again by $\pi: x \rightarrow D$. So we will suppose from now on that the family $\pi: X \rightarrow D$ has the following properties:

1) $X^{*} \xrightarrow{\pi^{*}} D^{*}$ has trivial mondormy and it is a family of marked non-singular Hyper-Kählerian manifolds with a polarizatzion class $L$
2) $\dot{x}^{*} \hookrightarrow x \rightarrow \mathbf{p}^{N_{x D D}}$

3) $p: D \hookrightarrow \Omega(L)$, i.e. $p$ is an embedding.

From now on instead of the map $p: H i l b_{X}^{\prime} / \mathbb{P}^{N} \rightarrow \Omega(L) / r_{L}$ we will consider the map $p: \widehat{H i l b}{ }_{X / p} \rightarrow \Omega(L)$, where $\widetilde{H i l b} \dot{X}_{\mathbf{X}} / \mathbf{P}^{N}$ is the universal convening of Hill $\frac{1}{x} / \mathbb{P}^{N}$. Since $\pi_{1}\left(\widetilde{\mathrm{Hilb}}_{\mathrm{X} / \mathrm{TPN}^{N}}\right)=0$ then if we mark one fibre in the universal family

$$
x \rightarrow \tilde{H i l b}_{X / p^{N}} \quad \text { (For definition of } H i l b_{X}^{\prime} / \mathrm{PN} \text { see 1.3.2.) }
$$

then all the fibres will be marked and so the map

$$
\mathrm{p}:{\widetilde{\mathrm{H} I I b_{X}}}_{\prime} \mathcal{P}^{N} \rightarrow \Omega(\mathrm{~L})
$$

is correctly defined.

Let $\tau: \Omega(L) \rightarrow \cap(L) / \Gamma_{L}$ be the natural map and, $V=\Omega(L) / \Gamma_{L} \backslash\left(H i l b_{X / \mathbb{P}^{N}}\right)$ then $\tau^{-1}(V)$ will be an union of countable irreducible analytic closed subspaces $V_{i}$ " $1.0,1, \ldots, n, \ldots$ in $n(L)$ (see 1..... Now wo
may suppose that $p_{D}(0) \in \tau^{-1}(V)$, where $p_{D}$ was the map obtain from the period map: $P_{D^{*}}: \begin{aligned} & X^{*} \\ & D^{*}\end{aligned}, \rightarrow \Omega(L)$. Notice that if $P_{D}(0) \& \tau^{-1}(V)$, then theorem 1 follows immediately. Let $\mathrm{P}_{\mathrm{D}}(0) \in \mathrm{V}_{0}$, where $\mathrm{V}_{0}$ is one of the components of $\tau^{-1}(\mathrm{~V})$. Let $\mathrm{U}^{0}$ be an open polycilinder in $\Omega(\mathrm{L})$ such that $U^{0}$ intersects $\tau^{-1}(V)$ only on $V_{0}$ and $U^{0} \supset D^{*}$. Let $U=U^{0}\left(U^{0} \cap V_{0}\right)$. So from the definition of $u$ we get that

$$
\mathrm{D}^{*} \subset \mathrm{U}, \operatorname{dim}_{\mathbb{C}} \mathrm{U}=\operatorname{dim}_{\mathbb{C}} \Omega(\mathrm{L})
$$

Lemma 1.4.1. There exists a family $\chi_{U} \rightarrow U$ of marked polarized Hyper-Kählerian manifolds over $U$ (defined as


Proof: 1.4.1. Follows immediately from the existence of universal family $X_{L} \rightarrow M_{L}$ of marked polarized algebraic Hyper-Kählerian manifolds and the fact that $p: M_{L} \rightarrow \Omega(L)$ is an etale map, i.e. $p$ is a local isomorphism. The existence of $X_{L} \rightarrow M_{L}$ is proved in § 2. From these two facts and the construction


Now let $\left\{U_{i}\right\}$ be a covering of $U$ by polycilinders and suppose that $U_{i} \cap D^{*} \neq \emptyset$ is a disk in $D^{*}$. It is easy to see that such a covering exists (may be after we shrink) U). Now from the fact that $B: M_{L} \rightarrow \Omega(L)$ is a local isomorphism and $p\left(M_{L}\right)=\Omega(L) \tau^{-1}(V) \quad$ (this is proved in $\left.\S 2\right)$ we obtain families of marked polarized Hyper-Kählerian manifolds:
$x_{i} \rightarrow U_{i}$. Now clearly we can glue together these families along $D^{*}$ and ajong, $U_{i} \cap U_{j}$. So we will obtain the family $\mathrm{x}_{\mathrm{U}} \xrightarrow{\pi_{\mathrm{v}}} \mathrm{U}$.
Q.E.D.

Now for every point $t \in U$ we consider the isometric deformation of $X_{t}=\pi_{U}^{-1}(t)$ with respect to the CalabiYau metric corresponding to the polarization class L. Let us denote this family of isometric deformations by:

$$
\mathbb{P}\left(X_{t}\right) \rightarrow \mathbf{P}_{t}^{1}(L) a s^{2}
$$

Now let us consider all isometric deformations with respect to Calabi-Yau metrics $\left(g_{\alpha \bar{\beta}}(t)\right)$ corresponding in $X_{t}$ for every $t \in U$ to the fixed polarization class $L$. So we will get a new family and we will denote it by:

$$
\mathbb{P}\left(x_{U}\right) \rightarrow \mathbb{P}(u)
$$

Since as $C^{\infty}$-family the family of isometric deformations is $c^{\infty}$-diffeomorphic to $\mathbf{P}_{t}^{1}(L) \times X$ for each $t \in U$, we see that the family:

$$
\mathbf{P}\left(x_{\mathrm{U}}\right) \rightarrow P(\mathrm{U})
$$

is a marked family and so the period map:

$$
\mathrm{p}: \mathbb{P}(\mathrm{U}) \rightarrow \Omega
$$

is a well defined map. For the definition of $\Omega$ see 1.1.8.

Lemma 1.4.2. a) $\mathrm{p}: \mathcal{P}(\mathrm{U}) \rightarrow \Omega$ is an embedding, i.e. $\mathbf{P}(\mathrm{U}) \quad \longrightarrow \Omega$.

$$
\text { b) } \quad \operatorname{dim}_{\mathbb{C}} \mathbf{P}(U)=\operatorname{dim}_{\mathbb{C}} \Omega
$$

Proof: The proof of lemma 1.4.2. is base on the following two propositions:
1.4.3. There exists one to one map $\varphi$ between the point of $\Omega$ and all two dimensional oriented vector subspaces $\mathrm{E} \subset \mathrm{H}^{2}(\mathrm{X}, \mathrm{R})$ such that $<_{,>}>$(defined by 1.1 .3. ) when restricted to $E$ is positive, i.e. $\langle u, u \gg 0$ for $u \in E$. (The $\operatorname{map} \varphi$ is constructed in the following way; let $x \in \Omega \subset P\left(H^{2}(X, \mathbb{Z}) \otimes \mathbb{C}\right)$, then $x$ defines a line $\ell_{X} \subset H^{2}(X, x) \mathbb{C}$, let $\omega_{X}$. be a non zero vector in $\ell_{x}$ and let $\omega_{X:}=\operatorname{Re} \omega_{X}+i I m \omega_{X}$ then $\varphi(x)=E_{x}$, where $E_{X}$ is the two plane in $H^{2}(X, R)$ spanned (Re $w_{x}, \operatorname{Im} u_{x}$ ) and the orientation is defined by $\left\{\operatorname{Re} w_{x}, \operatorname{Im} u_{X}\right\}$ )

Remark: From the definition of $\Omega$ it follows that if $x \in \Omega$, then

$$
\langle x, x\rangle=0 \quad\langle x, \bar{x}\rangle\rangle 0
$$

So from here we get that $x \neq \bar{x}$ and so if $\omega_{X} \in \ell_{X}$, then $\operatorname{Re} \omega_{X} \neq 0$ and $\operatorname{Im} \omega_{X} \neq 0$, so $\varphi$ is correctly defined. Indeed from $\left\langle\omega_{X}, \omega_{X}\right\rangle=0 \quad \& \quad\left\langle\omega_{X}, \bar{\omega}_{X}\right\rangle>0 \quad \omega=$ get that $\left\langle\operatorname{Re} \omega_{X}, \operatorname{Re} \omega_{X}\right\rangle=$ $=\left\langle\operatorname{Im} \omega_{X}: \operatorname{Im} \omega_{\dot{X}}\right\rangle>0$ and $\left\langle\operatorname{Re} \omega_{X}, \operatorname{Im} \omega_{X}\right\rangle=0$ and so $\langle\rangle \mid, E_{X}$ is strictly positive.

For the proof of 1.4.3. see [21].
 defined in the following manner $p(t)=\left\{\operatorname{Re} \omega_{t}(2,0), \operatorname{Im} \omega_{t}(2,0)\right\}=E_{t}=\varphi^{-1}(p(t))$
1.4.4. Proposition. Let $E$ be a three dimensional subspace on which <, > is strictly positive, then $P(E \in \mathbb{E}) \cap Q$ will be a non-singular curve of degree two and moreover $P(E \propto \mathbb{C}) \cap Q=P(E \otimes \mathbb{C}) \cap \Omega$, where $Q=\left\{u \in \mathbf{P}\left(H^{2}(X, R) \mathbb{C}\right) \mid\langle u, u\rangle=0\right\}$ and $\Omega=\{u \in Q \mid<u, \bar{u} \gg 0\}$. For the proof of 1.4.4. see [21] or [23]
 If $E=E_{X}(L)$ we will denote by $P_{x}^{1}(L)=P(E \mathbb{C}) \cap Q=$ $=\mathbf{P}\left(E_{X}(L) \bullet \mathbb{C}\right) \cap Q=\mathbf{P}(E \in \mathbb{C}) \cap \Omega$.
b) Let $\quad X \rightarrow \mathbf{P}_{t}^{1}(L)$ be the isometric deformation of $X_{t}$ with respect to the Calabi-Yau metric defined by $L$. We need to compute the image of the isometric deformation under the period map. From the definition of the isometric deformation we have the following facts:
a) $\quad E_{t}(L)=\left\{\operatorname{Re} \omega_{t}(2,0), \operatorname{Im} \omega_{t}(2,0), \operatorname{Im} g_{\alpha \bar{B}}(t)\right\} \subset \Gamma\left(X, \Lambda^{2} T^{*}\right)$
b) $E_{t}(L)$ is spanned by harmonic forms and so $E_{t}(L) \subset H^{2}(X, R)$
c) Notice that $\langle\rangle,\left|E_{t}(L)\right\rangle 0$

We know that there is one to one map between the oriented two planes in $E_{t}(L)$ and the complex structures in the family of isometric deformation $\quad x \rightarrow \boldsymbol{p}_{t}^{1}(L)$. So from here and remark 1.4.3. It follows that there is one to one map $\varphi$ between the oriented two planes in $g_{t}(L) \subset H^{2}(X, R)$ and the points of
$\mathbf{P}\left(E_{t}(L) \otimes \mathbb{C}\right) \cap Q=\mathbf{P}\left(E_{t}(L) \otimes \mathbb{C}\right) \cap \Omega=\mathbf{P}_{t}^{1}(L) \subset \Omega$. The fact that $p(\mathbf{P}(\mathrm{U}))$ lies on $\Omega$ follows from the fact that for each $t \in U$ the scalar product $<,>$ as in 1.1.3. on $E_{t}(L) \subset \Gamma\left(X_{t},{ }^{2} T_{X_{t}}^{*}\right)$ coinside with the scalar product defined by the Calabi-Yau metric on $\Gamma\left(X, \Lambda^{2} T * X_{t}\right)$, since

$$
*_{\omega}=\omega \wedge L^{n-2} \quad \text { and so } \quad\left\langle\omega_{1}, \omega_{2}\right\rangle=\int_{x} \omega_{1} \wedge * \omega_{2}
$$

(See [ ].)
Onthe other hand * is defined by the Riemannian metrics coming from Calabi-Yau metric and so since all the complex structures are compatible with this fixed Riemannian metric we get that $p(\mathbb{P}(U)) \subset \Omega$.

Now from local Torelli theorem and the fact that $\mathrm{p}: \mathrm{U} \Leftrightarrow \Omega(L)$ and the definition of isometric deformation we get immediately that:

$$
\mathrm{p}: \mathbf{P}(\mathrm{U}) \Leftrightarrow \Omega .
$$

Proof of 1.4.2. b): This follows immediately from local Torelli and the definition of isometric deformation.
Q.E.D.

The main lemma First we need some remarks.

Let $p(0)=x \in \Omega(L),(0 \in D)$. Since $x \in \Omega(L)$, from 1.4.3. it follows that $x$ corresponds to a two dimensional subspace $E_{X} \subset H^{2}(X, T)$ such that $\left.\langle,\rangle_{\left.\right|_{X}}\right\rangle 0$. From $x \in \Omega(L) \Rightarrow\left\langle E_{X}, L\right\rangle=0$ and since $<L, L \gg 0$ it follows that the 3-dim space $E_{X}(L) \subset$ $H^{2}(X, \mathbb{R})$ spanned by $E_{X} \& L$ has the following property:

$$
\langle,\rangle\left|E_{x}(L)\right\rangle 0
$$

From 1.4.4. we obtain that $\left(P\left(E_{x}(L) Q E\right) \cap \Omega=P_{x}^{1}(L)\right.$ is a complex projective non-singular curve of degree two in $\mathbb{P}\left(E_{x}(L) \mathbb{C}\right)$.
1.4.6. Main Lemma, Let $x^{*} \rightarrow D^{*}$ is the family with the
 monodromy, let $p: D \rightarrow \Omega(L)$ be the extended period map (this extension exists by Griffith's theorem (see [13])], fet $\rho(0)=x_{0} \in \Omega(L)$; then there exists a point $z_{0} \in U$ such that

$$
\mathbf{P}_{x_{0}}^{1}(L) \cap \mathbf{P}_{z_{0}}^{1}(L) \neq \varnothing
$$


 manifolds and $\operatorname{dim}_{\mathbb{C}} \mathrm{U}=\operatorname{dim}_{\mathbb{C}} \Omega(L)$.

Proof: The proof consists of two steps: Step 1): If $g_{0} \in \boldsymbol{P}_{X_{0}}^{1}(L)$ and $x_{0} \neq g_{0} \neq \bar{x}_{0}$, then we will prove that there exists a plane quadric $\mathbf{P}_{9_{0}^{1}}^{1}(\omega) \subset \Omega$ such that:
a) $\quad P_{g_{0}}^{1}(\omega) \cap \quad U \neq \emptyset$
b) $\boldsymbol{P}_{g_{0}}^{1}(\omega)=\overline{\mathbf{P}_{g_{0}}^{1}(\omega)}$, remember that
$\Omega \subset \mathbb{P}\left(H^{2}(X, Z) \otimes \mathbb{Z}\right)$, so the conjugation operator $u \rightarrow \vec{u}$ is a well defined operator.

The plane quadric $\mathbf{p}_{g_{0}}^{1}(4)$ is defined in the following way:
Let ${ }^{E^{\prime}} g_{0}$ be the two dimensional plane that corresponds to $g_{0}$ given by 1.4.3. Let $\omega \in H^{2}(X, I R)$ such that $\langle\omega, \omega\rangle>0$
and $\left\langle\omega, E_{g_{0}}\right\rangle=0$ and let $E_{g_{0}}(\omega)$ be the three dimensional subspace in $H^{2}(X, R)$ spanned by $E_{g_{0}}$ and $\omega$, then $\mathbf{P}_{g_{0}^{1}}^{1}(\omega)$ def $\underset{\left(E_{g_{0}}(\omega) \otimes \mathbb{C}\right) \cap \Omega .}{ }$

Step 2. Let $\mathbb{P}_{g_{0}}^{1}(\omega) \cap \mathrm{U}=\mathrm{z}_{0} \cup \bar{z}_{0}$, then we will prove that $\mathbb{P}_{X_{0}}^{1}(L) \cap \mathbb{P}_{Z_{0}}^{1}(L) \neq \emptyset$, here again $\mathbb{P}_{Z_{0}}^{1}(L)=\mathbb{P}\left(E_{z_{0}}(L) \otimes \mathbb{C}\right) \cap \Omega$.

Proof of Step 1: First we will need some definitions. Let $g_{0} \in{\underset{X}{X_{0}}}_{1}^{(L)}$ and $g_{0} \notin \Omega(L)$. From 1.4.3. follows that to $g_{0}$ there corresponds an oriented two dimensional plane $E_{g_{0}} \subset H^{2}(X, \mathbb{R})$ on which we have:

$$
\left\langle,>\left.\right|_{E_{g_{0}}}>0\right.
$$

Let

$$
H_{g_{0}}^{1,1}(\mathbb{R}) \quad \operatorname{def}\left\{u \in H^{2}(X, \mathbb{R})\left|<u, E_{g_{0}}\right\rangle=0\right\}
$$

Clearly $\operatorname{dim}_{g_{0}}^{1,1}(\mathbf{R})=b_{2}-2$ and $\langle$,$\rangle has signature$ $\left(1, b_{2}-3\right)$ on $H_{g_{0}}^{1,1}(\mathbb{R})$. Let

$$
v_{g_{0}}(\mathbb{R}) \stackrel{\text { def }}{=}\left\{u \in H_{g_{0}}^{1,1}(\mathbb{R}) \quad \mid<u, u \gg 0\right\}
$$

Clearly since $\langle$,$\rangle on H_{g_{0}}^{1,1}(R)$ has a signature $\left(1, b_{2}-3\right)$, then $\mathrm{V}_{\mathrm{g}_{0}}(\mathbb{R})$ will be an open cone in $\mathrm{H}_{\mathrm{g}_{0}}^{1,1}(\mathbb{R})$ and $v_{g_{0}}(\mathrm{R})=\mathrm{V}_{\mathrm{g}_{0}}^{+} \cup \mathrm{V}_{\mathrm{g}_{0}}^{-}$. Let

$$
\begin{aligned}
& \mathrm{E}_{\mathrm{g}_{0}}(\omega) \stackrel{\text { def }}{=}\left\{\text { three dim supspace in } \mathrm{H}^{2}(\mathrm{X}, \mathrm{IR}) \mid\right. \\
& \text { spanned by } \left.\mathrm{E}_{\mathrm{g}_{0}} \text { and } \omega \in \mathrm{V}_{\mathrm{g}_{0}}(\mathrm{IR})\right\}
\end{aligned}
$$

From the definition of $E_{g_{0}}(\omega)$ it follows that

$$
\left.\rangle| E_{g_{0}}(\omega)\right|^{>0}
$$

1.4.6.1. Let $K_{g_{0}}(\mathbb{R})$ def \{union of all $\mathbb{P}_{\mathbf{g}_{0}}^{1}(u)$ in $\Omega$ | where $\left.u \in V_{g_{0}}(\mathbb{I R})\right\}$, then $K_{g_{0}}(\mathbb{R})$ is a real analytic subspace in $\Omega$. This follows from the definition of $K_{g_{0}}(\mathbb{R})$ and the interpretation of $\Omega$ as Grassmannian.
1.4.6.2. Let: $V_{g_{0}}(\mathbb{X}) \quad \operatorname{def}\left\{u \in H_{g_{0}}^{1,1}(\mathbb{R}) \quad \mathbb{a}|\langle u, \bar{u}\rangle\rangle 0\right\}$, $\left(\operatorname{dim}_{\mathbb{C}} v_{g_{0}}(\mathbb{C})=\operatorname{dim}_{\mathbb{C}} \Omega\right) \quad K_{g_{0}}(\mathbb{C})=$ \{the union of all $\quad \mathbf{P}_{g_{0}}^{1}(u)=$ $=P\left(E_{g_{0}}\right) \cap \cap$ in $\Omega$, where $E_{g_{0}}(\mathrm{u})$ is a three dimensional subspace in $H^{2}(X, \mathbb{R}) \oplus \mathbb{C}$, spanned by $E_{g_{0}}$ and $\left.u \in V_{g_{0}}(\mathbb{I})\right\}$. Since $\left\langle,>{ }^{\prime} E_{g_{0}}(v)>0\right.$ (if $u \in V_{g_{0}}(\mathbb{I})$ ), it follows that $P\left(E_{g_{0}}(v)\right) \cap Q^{0}=P\left(E_{g_{0}}(v)\right) \cap \Omega$. is a projective plane curve of degree 2.
1.4.6.3. Proposition. $K_{g_{0}}(\mathbb{L}) \cap \Omega(L)$ contains an open set $W \subset \Omega(L)$. such that $U \subset W$ in $\Omega(L)$. ( $U$ is defined on $p .24$ ).

Proof: $H_{L}$ will be the hyperplane in $I P\left(H^{2}(X, I R) \in a\right)$ defined in the following manner:

$$
H_{L}=\left\{u \in \mathbf{P}\left(H^{2}(X, R) \odot \mathbb{C}\right) \mid\langle u, L\rangle=0\right\}
$$

Clearly $H_{L} \cap \Omega=\Omega(L)$. On the other hand since $\operatorname{dim}_{C_{0}} \mathrm{~K}_{0}(\mathbb{C})=$ $=\operatorname{dim}_{\mathbb{C}} H^{2}(X, \mathbb{C})-2=b_{2}-2=\operatorname{dim}_{a} \Omega=\operatorname{dim}_{C^{H}} H^{1,1}(X, \mathbb{C})$ we get


$$
\overline{\mathbf{P}_{g_{0}}^{1}(v)}=\mathbf{P}_{g_{0}}^{1}(v) \text { in } \mathbf{P}\left(H^{2}(x, \mathbb{R})\right.
$$

and since $H_{L} \cap \mathbb{P}_{g_{0}}^{1}(V) \ni z_{0} \neq \varnothing$ (remember that $H_{L}$ is a hyperplane in $P\left(H^{2}(X, \mathbb{R}) \otimes \mathbb{X}\right)$ and $\mathbb{P}_{g_{0}}^{1}(v)$ is a curve of degree two on the plane $\left.\mathbf{P}^{2}=\mathbb{P}\left(E_{g_{0}}(v) \otimes \mathbb{U}\right) \subset \mathbb{P}\left(H^{2}(X, \mathbb{R}) \otimes \mathbb{C}\right)\right)$, so we have that $\left.H_{L} \cap \mathbb{P}_{g_{0}}^{1}(v) \neq \varnothing\right)$.

Now let $t \in \mathbf{P}_{g_{0}}^{1}(v) \cap H_{L}$, from the fact that $\overline{\mathbb{P}_{g_{0}}^{1}(v)}=\mathbf{P}_{g_{0}}^{1}(v)$ $\overline{\Omega(L)}=\Omega(L) \quad$ (since $L \in H^{2}(X, R) \mu t u \bar{t} \in \mathbf{P}_{g_{0}}^{1}(v) \cap H_{L}(t \neq \bar{E})$. So we get that if $v \in V_{g_{0}}(\mathbb{R})$, then $\mathbb{P}_{g_{0}}^{1}(v)$ intersects $\Omega(L)$ transversally, since deg $\mathbb{P}_{g_{0}}^{1}(v)=2$ and $H_{L} \cap \mathbb{P}_{g_{0}}^{1}(v)=\Omega(L) \cap \mathbb{P}_{g_{0}}^{1}(V)=z_{0} U \bar{z}_{0}$ and $z_{0} \neq \overline{' z}_{0} . K_{g_{0}}(R) \quad$ intersects $\Omega(L) \quad$ transversally and since transversality is an open condition, $\operatorname{dim}_{\mathbb{C}^{K}}(\mathbb{C})=\operatorname{dim} \Omega$ and $K_{g_{0}}(\mathbb{R}) \subset K_{g_{0}}(\mathbb{C})$ so we can find an open subset $W \subset \Omega(L)$ such that ${ }_{z_{0} \in \mathbf{P}_{g_{0}}^{1}(\mathrm{~V}) \cap \Omega(L) \subset E \subset W \subset K_{g_{0}}(\mathbb{I}) \cap \Omega(L) .}$
Q.E.D
1.4.5.4. Grass $\left(3, b_{2} ; \mathbb{R}\right)$ def $\{a l l$ oriented 3 -dimensional subspaces $E \subset H^{2}(X, \mathbb{R})$ on which $\left\langle>_{E}>0\right\}$.
1.4.6.5. Grass $\left(3, b_{2} ; \mathbb{C}\right)=\{$ all oriented 3 -dimensional subspaces $E \subset H^{2}(X, \mathbb{R}) \otimes \mathbb{c}$ such that if $u \in E$, then $\left.\langle u, \bar{u}\rangle>0\right\}$.
1.4.6.6. Let $\tau(E)=\bar{E}$, if $E \subset H^{2}(X, \mathbb{R})$. Clearly $\tau$ acts on Grass $\left(3, b_{2} ; \mathbb{C}\right)$ and $\operatorname{Grass}\left(3, b_{2} ; \mathbb{C}\right)^{T}=\operatorname{Grass}\left(3, b_{2} ; R\right)$.
1.4.6.7. Let $M=$ \{all plane projective quadrics $\mathbf{P}_{g}^{1}(u)$, that are contained in $\Omega\}$. It is obvious that there exists an one-toone map between $M$ and Grass $\left(3, b_{2} ; d\right)$.

Suppose that 1.4.6. is not true, this means that
$(1.4 .6 .10.) \quad K_{g_{0}}(R) \cap \Omega(L) \subset V_{0}$
Remember that $V_{0}$ is a proper complex analytic closed subspace in $\Omega(L)$, (For the definition of $V_{0}$ see p. 24 ), i.e. $\operatorname{dim}_{\mathbb{C}} V_{0}<\operatorname{dim}_{\mathbb{G}} \Omega(L)$. Let

$$
P\left(v_{0}\right) \quad \operatorname{def}\left\{\mathbb{P}_{g_{0}}^{1}(u) \subset k_{g_{0}}(\mathbb{C}) \mid \mathbb{P}_{g_{0}}^{1}(u) n \ldots v_{0} \neq g\right\}
$$

It is a standart fact that $\mathbf{P}\left(\mathrm{V}_{0}\right)$ is a proper closed complex analytic subset in Grass $\left(3, b_{2} ; \mathbb{C}\right)$. (Use theory of elimination and $P\left(V_{0}\right)=\{$ all three dimensional subspaces $E$ in $H^{2}(X, R) \otimes \mathbb{C}$, such that $E \cap Z \neq O$, where $Z$ is the cone over $V_{0} \subset \mathbb{P}\left(H^{2}(X, T) \otimes \mathbb{C}\right\}$ in $\left.H^{2}(X, \mathbb{Q})\right)$. The same arguments show that

$$
P\left(V_{g_{0}}(\mathbb{R})\right) \text { def }\left\{E \subset H^{2}(X, R) \mid E \text { is spanned by } E_{g_{0}}\right.
$$

and $v$, where $\left.v \in V_{g_{0}}(R)\right\}$
is a real analytic proper subspace in $M \cong \operatorname{Grass}\left(3, b_{2} ; \mathbb{C}\right)$. Indeed $P\left(V_{g_{0}}(\mathbb{R})\right)=\left\{E \in H^{2}(X, R) \mathbb{C}\right) \mid E=\bar{E}$ and $E$ contains the fixed two dimensional subspace $E_{g_{0}}$ \}. So from this de-
 subspace in Grass ( $3, \mathrm{~b}_{2} ; \mathrm{a}$ ).

Clearly that
(1.4.6.11)

$$
\begin{aligned}
\text { a) } \quad P\left(V_{g_{0}}(R)\right) & =P\left(V_{g_{0}}(\mathbb{C})\right)^{T}, \text { where } \\
P\left(V_{g_{0}}(\mathbb{L})\right) & =\left\{E \subset H^{2}(X, \mathbb{C}) \mid d i m_{\mathbb{C}} E=3,\right.
\end{aligned}
$$

$$
\left.<,>\left.\right|_{E}>0 \quad \& \quad E \supset E_{g_{0}}\right\}
$$

b) From the definition of $\mathbb{P}\left(\mathrm{V}_{\mathrm{g}_{0}}\right.$ ( $\left.\mathbb{C}\right)$ ) it follows that $\mathbb{P}\left(\mathrm{V}_{\mathrm{g}_{0}}(\mathbb{\Psi})\right)$ is a complex analytic proper subspace in Grass $\left(3, b_{2} ; \mathbb{C}\right)$, since $\mathbb{P}\left(V_{g_{0}}(\mathbb{C})\right)=\{$ all three dimensional subspaces in $\left.\left.H^{2}(X, \mathbb{R}) \mathbb{\mathbb { C }}\right) \mid \mathrm{E} \supset \mathrm{E}_{\mathrm{g}_{0}}\right\}$ 。

Now we will show that (1.4.6.11) contradicts (1.4.6.10). From the definition of $\mathbb{P}\left(\mathrm{V}_{0}\right)$ we get that $\mathbb{P}\left(\mathrm{V}_{0}\right)$ is a proper complex analytic subspace in $\mathbb{P}\left(\mathrm{V}_{\mathrm{g}_{0}}(\mathbb{C})\right)$. From (1.4.6.10.) it follows that we have:

$$
\boldsymbol{P}\left(\mathrm{V}_{\mathrm{g}_{0}}(\mathbb{C})\right)^{\tau}=\mathbb{P}\left(\mathrm { V } _ { \mathrm { g } _ { 0 } } ( \mathbb { R } ) \subset \mathbb { P } ( \mathrm { V } _ { 0 } ) \subset \mathbb { P } \left(\mathrm{V}_{\mathrm{g}_{0}}(\mathbb{C})\right.\right.
$$

Since $\mathbf{P}\left(\mathrm{V}_{0}\right)$ is a complex analytic subspace (proper one) in a complex analytic space $\mathbb{P}\left(V_{\mathrm{g}_{0}}\right.$ (C)) $\subset \operatorname{Grass}\left(3, \mathrm{~b}_{2} ; \mathbb{\mathbb { C }}\right)$ we get that locally $P\left(\mathrm{~V}_{0}\right)$ is defined by

$$
f_{1}\left(z^{1}, \ldots, z^{N}\right)=\ldots=f_{K}\left(z^{1}, \ldots, z^{N}\right)=0
$$

where $f_{1}, \ldots, f_{N}$ are complex analytic function in Grass ( $3, b_{2} ; \mathbb{d}$ ). From $\mathbb{P}\left(\mathrm{V}_{\mathrm{g}_{0}}(\mathbb{R})\right) \subset \mathbb{P}\left(\mathrm{V}_{0}\right) \subset \mathbb{P}\left(\mathrm{V}_{\mathrm{g}_{0}}(\mathbb{E})\right)$ and since

$$
\mathbb{P}\left(\mathrm{V}_{\mathrm{g}_{0}}(\mathbb{R})\right)=\mathbb{P}\left(\mathrm{V}_{g_{0}}(\mathbb{X})\right)^{\tau}
$$

## we obtain that

$$
f_{1}\left(\operatorname{Re} z^{1}, \ldots, \operatorname{Re} z^{N}\right)=\ldots=f_{K}\left(\operatorname{Re} z^{1}, \ldots, \operatorname{Re} z^{N}\right) \equiv 0
$$

on $\mathbb{P}\left(V_{g_{0}}(\mathbb{C})\right)$, so $f_{1}=f_{2}=\ldots=f_{N} \equiv 0$ on $P\left(V_{g_{0}}(\mathbb{C})\right)$. But this is a contradiction since $\mathbb{P}\left(V_{0}\right)$ is a proper subspace in $P\left(V_{g_{0}}(\mathbb{C})\right)$, i.e. $\operatorname{dim}_{c} P\left(V_{0}\right)<\operatorname{dim}_{c} P\left(V_{g_{0}}(\mathbb{C})\right)$. So Step 1 is proved.
Q.E.D.

Proof of Step 2.

$$
\begin{aligned}
& \text { From step } 1 \Rightarrow \exists v \in V_{g_{0}}(\mathbb{R}) \text { such that } \\
& { }_{\left.\mathbb{P}_{0}^{1}(v) \cap \Omega(L) \subset U \quad \text { (where } U \text { is defined on } p .24\right)}
\end{aligned}
$$

Indeed we have proved, that $K_{g_{0}}(\mathbb{I}) \cap \Omega(L)$ is a real analytic subspace and $K_{Y}(\mathbb{R}) \cap \Omega(L)$ not contained in $V_{0}$. Since $K_{g_{0}}(\operatorname{IR}) \cap \Omega(L) \in g_{0} \subset U^{0}$ open polycilinder in $\left.\Omega(L)\right)$ we get that $K_{g_{0}}(\operatorname{IR}) \cap U \neq \emptyset$, where $U$ was $U^{0} \backslash V_{0}$ (see p. 24). So let

$$
\mathbb{P}_{g_{0}}^{1}(v) \cap \Omega(L)=z_{0} \cup \overline{z_{0}}, z_{0} \neq \overline{z_{0}} \quad \text { and } \quad z_{0} \in U
$$

Let $E$ def $\left\{\right.$ four dimensional subspace in $H^{2}(X, \mathbb{R})$ spanned by $E_{x_{0}}(L)$ and $v$ \}. Since $E_{g_{0}} \subset E$ it follows that $E_{z_{0}}$ is contained in $E$. From the facts that
a) $\left.{ }^{\langle,}\right\rangle{ }^{\prime} E_{Z_{0}}$
$(L)>0,\langle\rangle \mid, E_{x_{0}}(L)>0$ and
b) $E_{L_{0}}$
(L) $\cap E_{x_{0}}(L)=$
$=E_{t_{0}} \subset E$ it follows that
i) $\quad \operatorname{dim}_{a^{E}} t_{0}=2$ since $\operatorname{dim}_{C^{\prime}} E_{x_{0}}(L)=E_{z_{0}}(L)=3$ and

$$
E_{x_{0}}(L) \text { and } E_{z_{0}}(L) \text { are contained in } E ; d i m_{\mathbb{C}} E=4
$$

ii) $<>{ }^{\mid E_{t_{0}}}<0$.

Now from 1.4.3. it follows that $E_{t_{0}}$ corresponds to same point $t_{0} \in \Omega$. From the fact that there is one-to-one correspondence between the points of $\mathbb{P}_{X_{0}}^{1}(L)$ and the oriented two planes in $E_{x_{0}}(L)$ we get that $E_{t_{0}}$ corresponds to a point $t_{0} \in \operatorname{IP}_{X_{0}}^{1}(L)$.
Q.E.D.
1.4.7. Lemma. Let $X^{*} \rightarrow D^{*}$ be a family of marked polarized Hyper-Kählerian manifolds and this family fulfills the conditions 1),2) and 3) on p. 23, then
a) $x^{*}$ as $c^{\infty}$ manifold is diffeomorphic to
$X \times D^{*}$, where $X$ is a Hyper-Kählerian manifold
b) if $\dot{x}^{*} \longrightarrow x \times D$, then $\lim _{t \rightarrow 0} \omega_{t}(2,0)=\omega_{0}(2,0)$ exists and $\omega_{0}(2,0)$ is a complex non-degenerate form on $X$.

Proof: First we see that since $<,>\mid E_{X_{0}}\left(I_{i}\right)>0$, then $\mathrm{SO}(3)$ acts on $E_{X_{0}}(L)$. From 1.4.6. it follows that there exists $z_{0} \in U$ (as on $p$. 24) such that $E_{z_{0}}(L) \cap E_{x_{0}}(L)=E_{t_{n}}$, where $\operatorname{dim} E_{t_{0}}=2$, or which is equivalent by 1.4 .3. , to the fact that $\mathbf{P}_{t_{0}}^{1}(L) \cap \mathbb{P}_{x_{0}}^{1}=t_{0} \cup \overline{t_{0}}$. Now let $A \in \operatorname{sc}(3)$ such that $A\left(E_{x_{0}}\right)=E_{t_{0}}$. Next for each $t \in D^{*}$ we will define on $X_{t}$ a new complex structure $X_{t}^{A}$ in the following way:
Let $E_{t}(L)=\left\{\operatorname{Re} \omega_{t}(2,0), \operatorname{Im} \omega_{t}(2,0), \operatorname{Im}\left(g_{\alpha \beta}(t)\right)\right\} \subset \Gamma\left(X, \Lambda^{2} T^{*}\right)$, where $g_{\alpha \bar{\beta}}(t)$ was the Calabi-Yau metric that corresponds to $L$. From § 1.2. we know that $\left\{\operatorname{Re} \omega_{t}(2,0), \operatorname{Im} \omega_{t}(2,0), \operatorname{Im}\left(g_{\alpha} \bar{\beta}(t)\right)\right\}$ 1. an orthonormal bais of $E_{t}(L)$. So an action of $S O(3)$ is defined on $E_{t}(L)$. From $§ 1.2$. we know that

$$
A E_{t} d e f\left\{A \operatorname{Re} \omega_{t}(2,0), A \operatorname{AIm} \omega_{t}(2,0)\right\} \in \operatorname{So}(3)
$$

defines a new complex structure on $X_{t}$ which we will denote by $x_{t}^{A}$, where

$$
\omega_{t}^{A}(2,0)=\operatorname{ARe} \omega_{t}(2,0)+\operatorname{iAIm} \omega_{t}(2,0)
$$

So we get a new family:

$$
x^{*^{A}} \rightarrow D_{A}^{*}
$$

From the definition of $x^{*} \rightarrow D^{*}$ it follows that we have

$$
\begin{array}{cc}
X^{* A} & \longrightarrow \\
+ & \mathbb{P}\left(X_{U}\right) \\
+ & \text { (For definition of } \mathbb{P}\left(x_{U}\right) \rightarrow \mathbb{P}(U) \\
\text { see } p .
\end{array}
$$

Now since $\mathbb{P}(U) \subset \Omega, \mathbb{P}_{t}^{1}(L) \subset \mathbb{P}(U)$ (for each $t \in D^{*}$, since $\left.D^{*} \subset U\right)$ and since $\mathbb{P}_{z_{0}}^{1}(L) \cap \mathbb{P}_{X_{0}}^{1}=t_{0}$, where $z_{0} \in U$, we get

$$
\begin{equation*}
\lim _{t \rightarrow 0} \omega_{t}^{A}(2,0)=\omega_{t_{0}}(2,0) \tag{*}
\end{equation*}
$$

Where $\omega_{t_{0}}(2,0)$ corresponds to some complex structure on $Z_{t_{0}}$, isometric to Calabi-Yau metric on $Z_{0}$ corresponding to L. (Here $z_{0}$ is the marked polarized Hyper-Kahlerian manifold corresponding to the point $\left.z_{0} \in U \subset \Omega(L)\right)$. So we proved that the family

$$
x^{\star \boldsymbol{A}} \rightarrow D_{A}^{\star}
$$

can be embedded in a family $\hat{X}^{A} \rightarrow D_{A}$, where all the fibres are non-singular hyper-Kählerian manifolds. So $X^{A} \rightarrow D_{A}$ as $C^{\infty}$ manifold is diffeomorphic to $D \times X, X$ a Hyper-Kahlerian manifold. From here we obtain, that

$$
x^{*} \cong D^{*} \times X
$$

since $x^{k^{A}} \rightarrow D_{A}^{*}$ is the same $C^{\infty}$ family as $\bar{X}^{*} \rightarrow D^{*}$. This follows from the definition of isometric deformation.
Q.E.D.

Proof of 1.4.7. b) : From 1.4.6. it follows that there exists a point $t_{0} \in \mathbb{P}_{x_{0}}^{1}(L)$ such that $t_{0}=\mathbb{P}_{x_{0}}^{1}(L) \cap \cdot \mathbb{P}_{z_{0}}^{1}(L)$ where $z_{0} \in U$, and so $z_{0}$ is the image under the period map of a marked Hyper-Kählerian manifold $Z_{0}$ with a polarized class $L$. (Remember that we have the following: a family ${\underset{U}{X}}_{X_{U}}$ is map by $\left.\mathrm{p}: \mathrm{U} \hookrightarrow \Omega(L) \operatorname{dim}_{\mathbb{C}} \mathrm{U}=\operatorname{dim}_{\mathbb{C}} \Omega(L)\right)$. Let
$S_{L}=\left\{t \in \mathbb{P}_{X_{0}}^{1}(L) \mid E_{t}\right.$ contains $I, E_{t}$ is the oriented two plane that corresponds to $t$ according to 1.4.3.\}. Clearly as $c^{\infty}$ manifold $S_{L} \cong\{t \in \mathbb{C}| | t \mid=1\}$. On the other hand from $\mathbb{P}_{X_{0}}^{1}(L) \cap \mathbb{P}_{Z_{0}}^{2}(L)=t_{0} \cup \bar{t}_{0} \Rightarrow t_{0} \in S_{L}$. From the arguments in 1.4.6. it follows that there exists an open set $W_{t_{0}}$ to $t_{0}$ in $s_{L}$ such that for every $t \in W_{t_{0}}$
 Now let $t_{0}, t_{1}$ and $t_{2}$ are three points in $P_{X_{0}}^{1}(L)$ such that: $t_{0}, t_{1}$ and $t_{1} \in W_{t_{0}}$ From the way we defined $W_{t_{0}}$ it follows that $t_{0}, t_{1}$ and $t_{2}$ are respectively in $\mathbb{P}_{z_{0}}^{1}(L), \mathbb{P}_{z_{0}}^{Q_{1}}\left(L_{1}\right)$ and
$P_{z_{2}}^{1}(L)$, where $z_{0}, z_{1}, z_{2} \in \stackrel{t}{0}_{\chi_{U}}^{(S e e ~ p .24) . ~ F r o m ~ h e r e ~ a n d ~}$ from the definition of isometric deformation it follows that $t_{0}, t_{1}, t_{2}$ corresponds to the marked Hyper-Kahlerian manifold $T_{0}, T_{1}, T_{2}$ and $T_{0}, T_{1}, T_{2}$ are in the isometric families with respect to the Calabi-Yau's metrics on $Z_{0}, Z_{1}, Z_{2}$ that corresponds to $L$. It is clear that we can choose $t_{0}, t_{1}$ and $t_{2}$ in $w_{t_{0}} \subset S_{L} \subset I P{\underset{x}{0}}_{1}^{(L)}$ such that $\omega_{t_{0}}(2,0), \omega_{t_{1}}(2,0)$ and $\omega_{t_{2}}(2,0)$ are three linearly ingependent classes of cohomology in $H^{2}(X, I R)$ a. Since $\operatorname{so}(3)$ acts on $E_{X_{0}}(L)$ (Remember $\left\langle,>\left.\right|_{E_{X_{0}}}\left(I_{1}\right)>0\right.$ ) so there exist $A, B$ and $C$ such that $A E_{X_{0}}=E_{t_{0}}^{0} B_{X_{0}}=E_{t_{1}}$ and $C E_{X_{0}}=E_{t_{2}}$. Now we can define as in the proof of 1.4.7. a) the new families $\pi_{A}^{*}: x^{* A} \rightarrow D_{A}^{*}, \pi_{B}^{*}: \dot{\chi}^{B} \rightarrow D_{B}^{*}$ and $\pi_{C}^{*}: x^{*}{ }^{C} \rightarrow D_{C}^{*}$
 are $\ln \mathbb{P}(U) \subset \Omega \subset \mathbb{P}\left(H^{2}(X, C)\right)$ we get that:

$$
\begin{aligned}
& \lim _{t \rightarrow 0}\left[\omega_{t}^{A}(2,0)\right]=\left[\omega_{t_{0}}(2,0)\right], \lim _{t \rightarrow 0}\left[\omega_{t}^{B}(2,0)\right]=\left[\omega_{t_{1}}(2,0)\right] \\
& \text { and } \quad \lim _{t \rightarrow 0}\left[\omega_{t}^{C}(2,0)\right]=\left[\omega_{t_{2}}(2,0)\right]
\end{aligned}
$$

So from here we obtain that on the level of $c^{\infty}$ forms we have : $\quad \lim _{t \rightarrow 0} \omega_{t}^{A}(2,0)=\omega_{Z_{0}}(2,0), \lim _{t \rightarrow 0} \omega_{t}^{B}(2,0)=\omega_{Z_{1}}(2,0)$ and $\lim _{t \rightarrow 0} \omega_{t}^{c}(2,0)=\omega_{z_{1}}(2,0)$. Since $\omega_{t_{0}}(2,0)=\omega_{z_{0}}, \omega_{t_{1}}(2,0)=$ $=\omega_{Z_{1}}(2,0)$ and $\omega_{t_{2}}(2,0)=\omega_{z_{2}}(2,0)$ are three linearly independent forme in $E_{t_{0}}(L) \in \mathbb{C} \in \Gamma\left(X, A^{2}(T * X) \mathbb{C}\right)$ we get that

$$
\omega_{t}^{A}(2,0), \omega_{t}^{B}(2,0), \omega_{t}^{C}(2,0) \quad \text { are linearly }
$$

independent in each $E_{t}(L) \otimes \mathbb{C} \subset \Gamma\left(X, \Lambda^{2}(T * X \otimes \mathbb{C})\right) t \in D *$. So from here we have:

$$
\begin{aligned}
& \omega_{x_{t}}(2,0)=a \omega_{t}^{A}(2,0)+b \omega_{t}^{B}(2,0)+c \omega_{t}^{C}(2,0), a, b, c \in \mathbb{C} . \\
& \lim _{t \rightarrow 0} \omega_{x_{t}}(2,0)=a \lim _{t \rightarrow 0} \omega_{t}^{A}(2,0)+b \lim \omega_{t}^{B}(2,0)+e \operatorname{dim}_{t \rightarrow 0} \omega_{t}^{C}(2,0)= \\
& =a \omega_{z_{0}}(2,0)+b \omega_{z_{1}}(2,0)+c \omega_{z_{2}}(2,0)=\omega_{x}(2,0) \text { exists } \\
& \text { as } c^{\infty} \text { form and } d \omega_{x_{0}}(2,0) \equiv 0 .
\end{aligned}
$$

Since $\operatorname{det} \omega_{t}^{A}(2,0) \wedge \operatorname{det} \overline{\omega_{t}^{A}(2,0)}=\operatorname{det} \omega_{t}(2,0) \wedge \operatorname{det} \omega_{t}(0,2)$, $\lim _{t \rightarrow 0} \omega_{t}^{A}(2,0)=\omega_{t_{0}}(2,0)$ and $\operatorname{det} \omega_{t_{0}}(2,0) \wedge \operatorname{det} \omega_{t_{0}}(0,2)=$ $=\operatorname{det} \omega_{Z_{0}}(2,0) \wedge \operatorname{det} \overline{\omega_{Z_{0}}}{ }^{(2.0)} \quad$ (this is so because $t_{0} \in \mathbb{P}_{Z_{0}}^{1}$ (L) and so $T_{0}$ is obtained from $Z_{0}$ by isometric deformation). So $\lim _{t \rightarrow 0} \operatorname{det} \omega_{t}(2,0) \wedge \operatorname{det} \omega_{t}(0,2)=\operatorname{det} \omega_{Z_{0}}(2,0) \wedge \overline{\operatorname{det} \omega_{Z_{0}}(2,0)}$ $=K \operatorname{vol}\left(g_{\alpha \bar{\beta}}\left(Z_{0}\right)\right)>0$. This proves that $\omega_{X_{0}}(2,0)$ is a non-degenerate form since $\operatorname{det} \omega_{x_{0}}(2,0)=\underbrace{\omega_{x_{0}}(2,0) \wedge \ldots \wedge \omega_{x_{0}}(2,0)}_{n-t i m e s}$ Q.E.D.

In order to finish the proof of theorem 1 we need to check that det $\omega_{X_{0}}(2,0)$ fulfills a), b) and c) of AndreottiWeil remark. Clearly $d\left(\operatorname{det} \omega_{X_{0}}(2,0)\right)=0$ and $\operatorname{det} \omega_{X_{0}}(2,0) \wedge \operatorname{det} \omega_{X}(2,0)>0 \quad$ so $\left.b\right)$ and $\left.c\right)$ are fulfilled.

Let $P$ be the Plucker relation. Clearly we have $P\left(\operatorname{det} \omega_{t}(2,0)\right) \equiv 0$ so $\quad \lim _{t \rightarrow 0} P\left(\operatorname{det} \omega_{t}(2,0)\right) \equiv 0$.
So Theorem 1 is proved.

> Q.E.D.
§ II. Construction of the moduli space of marked polarized Algebraic Hyper-Kahlerian manifolds
2.1. The construction is based on the following
2.1.1. Lemma. Let $g$ be a holomorphic automorphism of $X$, and suppose that $g^{*}=i d$, where $g^{*}: H^{2}(X, x) \rightarrow H^{2}(X, Z)$, then $g$ induces the identity map on the Kuranishi space of $X$, ie. on


Proof: For the proof see [ ].

> Q.E.D.
2.1.2. The construction of the moduli space.

Let $\begin{array}{lll}x_{0} & \longrightarrow & x \\ f_{0} \\ 0 & \ni & \text { be the Kuranishi family of the marked } \\ 0\end{array}$

Algebraic polarized Hyper-Kahlerian manifold $\left(X ; \gamma_{1}, \ldots, \gamma_{b_{2}} ; L\right)$, where $Y_{1} \ldots \ldots \gamma_{b_{2}}$ is fixed basis in $H_{2}(x, m)$ and $L$ in a fixed class of cohomology in $H^{2}(X, z)$ corresponding to the
to the imaginary part of a Hodge metric on X. From local Torelli theorem it follows that we may consider the following:
where $\mathrm{p}: \mathrm{U} \rightarrow \operatorname{IP}\left(\mathrm{H}^{2}(\mathrm{X}, \mathrm{z}) \otimes \mathbb{C}\right)$ is the period map, so from § 1.1. we may consider $U$ as an open set in $\Omega$ this is just lemma 1.4.2.)

Let $H_{L}=\left\{x \in \mathbb{P}\left(H^{2}(X, z) \otimes \mathbb{C} \mid<x, L>\right\}\right.$. So from the arguments in 1.2 . we get that if we restrict the Kuranishi
 $\mathrm{U} \subset \Omega \subset \mathrm{IP}\left(\mathrm{H}^{2}(\mathrm{X}, \mathrm{X}) \otimes \mathbb{C}\right)$, we will get the local universal family of all Hyper-Kählerian manifold for which $L$ corresponds to an imaginary part of a Hodge metric on $X_{t}$, for every $t \in U_{L}$.
 identifying isomorphic marked algebraic Hyper-Kählerian manifolds with fixed polarized class $L$. In such a way we will get an universal family $\quad{ }^{\dagger}{ }_{M}\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)$ (since if $\varphi: X \rightarrow X$ is a biholomorphic map and $\varphi^{*}(L)=L$, then $\varphi$ must be an isometry with respect to Yau metric and so for generic $X$ $\varphi^{*}=1 d$ on $H^{2}(X, z)$. See $\left.[6] \&[11]\right)$ of maried polarized Hyper-Kählerian manifolds with the following properties:
a) ${ }^{M}\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)$ is a non-singular complex manifold of dimension $h^{1,1}{ }^{1}$,
b) $X_{L} \longrightarrow I^{N}{ }^{N} M\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)$. This is so since $L$

restricted to each fibre $X_{t}$ of $\stackrel{X}{t}^{X_{L}}$, corresponds to a very ample divisor $D_{t}$.

$$
M\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)
$$

From b) it follows that $p\left(M\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)\right.$ in $\Omega(L)$ is exactly equal to $\Omega(L) \backslash \tau^{-1}(V)$, where $\tau: \Omega(L) \rightarrow \Omega(L) / \Gamma_{L}\left(\Gamma_{L}\right.$ and $v \quad i$ are defined in 1.2 .1 .

$$
\Gamma_{L}=\left\{\varphi \in \text { Rut } H^{2}(X, z) \mid \varphi(L)=L \quad \text { and }\langle u, v\rangle=\langle\varphi(u), \varphi(v)\rangle\right\}
$$

$V=p(D)$, where $D=\hat{H i l b_{X / I p^{N}} \backslash H i l b_{X / T P^{N}}^{\prime}}$.
§3. Torelli Problem for Hyper-Kahlerian Algebraic Manifolds.

Theorem 3. Let $\pi_{L}: X_{L} \rightarrow M_{\left(L ; \gamma_{1}, \ldots, \gamma_{b}\right)}$ ) be the universal family of marked Hyper-Kählerian manifolds with fixed polarization class $L$ coming from the embedding:
then there exists a universal partial compactification
$\bar{\pi}_{L}: \bar{x}_{L} \rightarrow \bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b 2}\right)}$ of the universal family of marked polarized Hyper-Rählerian manifolds definds up to an isomorphism such that:
a)

$$
\begin{aligned}
& X_{L} \quad \bar{X}_{L} \quad \Leftrightarrow \quad \mathbb{P}^{N}{ }^{M}\left(L ; \quad \ldots, b_{2}\right)
\end{aligned}
$$

and every fibre of $\bar{\pi}: \bar{x}_{L^{\prime}} \bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$ is birationally isomorphic to a non-singular Hyper-Kählerlan manifold.
b) the period map $p: M_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right) \rightarrow \Omega(L) \text { can be prolonged }, ~}^{\text {b }}$ to a holomorphic isomorphism:

$$
\overline{\mathrm{p}}: \overline{\mathrm{M}}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)} \quad \sim \Omega(L)
$$

Remark $\overline{\mathrm{p}}: \overline{\mathrm{M}}\left(\mathrm{L} ; \gamma_{1}, \ldots, \gamma_{\mathrm{b}_{2}}\right)$ is defined up to a component.

Proof: First we will construct the partial compactification of

$$
\begin{aligned}
& { }^{\pi_{L} \cdot X_{L}} \rightarrow M_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)} \begin{array}{l}
\overline{X_{L}} \\
+ \\
\\
\end{array} \\
& \left.\bar{M}_{\left(L ; \gamma_{1}\right.}, \ldots, \gamma_{b_{2}}\right)
\end{aligned}
$$

In the proof of theorem 1 we used the fact that

$$
\Omega(L) \backslash p\left(M\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)\right)=v=V_{0} \cup v_{1} \cup \ldots \cup v_{K} \ldots
$$

is a countable union of analytic subsets. Now let $D$ be a disc in $\Omega(L)$ and $D^{*}=D^{*} \backslash\{0\}$, i.e. $D$ intersects $V$ in one point. From the arguments on p. 22 and 23 it follows that over $D^{*}$ we have a family of marked algebraic HyperKăhlerian manifolds with polirization class $L$ :

$$
x^{\star} \rightarrow D^{*},
$$

and this family has the properties stated on p. 23. Now we can apply Theorem 1 to $X^{*} \rightarrow D^{*}$ and we will get a family $\pi: X \rightarrow D$, where all the fibres are non-singular Hyper-Kahlerian manifolds. So from here it follows the existence of a family of non-singular Hyper-Kăhlerian marked manifolds $\tilde{x}_{L} \rightarrow \bar{M}_{\left(L, \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$ such that

b) the period map

$$
p: \bar{M}_{\left(L / \gamma_{1} \ldots, \gamma_{p_{q}}\right)} \rightarrow \Omega(L)
$$

is a surjective map and étale map.
3.1.1. Lemma. There exists meromorphic map

$$
\begin{gathered}
\left.\tilde{\varphi}: \tilde{X}_{L} \rightarrow \text { IP }^{N} \times \bar{M}_{\left(L ; \gamma_{1}\right.}, \ldots, \gamma_{b_{2}}\right) \\
\stackrel{{ }_{M}^{M}}{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}
\end{gathered}
$$

such that:
a) the restriction of $\tilde{\varphi}$ on $X_{L} \rightarrow M_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$ gives the embedding
b) for each $t \in \bar{M}\left(L ; \ldots, b_{2}\right)^{\prime M}\left(L ; \ldots, b_{1}\right)$ the map $\tilde{\varphi}$ defines a holomorphic map

$$
\varphi_{t}: x_{t} \rightarrow \frac{x}{t}_{t}
$$

where $\bar{x}_{t}$ is the closure of the fibre $X_{t}$ in $\mathbb{P}^{N}$ under the map $\quad \tilde{\varphi}_{t}$ and $\tilde{\varphi}_{t}$ is a birational map.

Proof: We know that:
a) $\left.\bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b}\right)}\right)^{M}\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)$ is a countable union of closed analytic subsets

${ }^{M}\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)$

So from a) \& b) it follows that it is enough to prove the lemma for a family $\pi: x \rightarrow D$, where $D C \bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$ and $D^{*} \hookrightarrow M_{\left(L ; \gamma_{1}, \ldots, \gamma_{b}\right)}$ ) Since $D^{*} \hookrightarrow D C \Omega(L)$, from the arguments on p. $24^{2}$ it follows that the family $\pi^{*}: \chi^{*} \rightarrow$ $\mathrm{D}^{*}$ has the following property:
(*) there exists an embedding


Now let $\left\{\varphi_{0}(t), \ldots, \varphi_{N}(t)\right\}\left(t \in D^{*}\right)$ are the section of the line bundle $L^{*}$, that gives the embedding ${\underset{D}{*}}_{\substack{*}}^{\longrightarrow} \mathbb{P}^{N} \times D^{*}$.

From the fact that we have

it follows that we can continue $\left\{\varphi_{0}(t), \ldots, \varphi_{N}(t)\right\}$ to sections in $\pi^{-1}(0)=X_{0}$, where $X_{0}$ is the zero fibre of the family of the non-singular Hyper-Kahlerian manifolds $\dot{X}_{D}$. So from here we get that there exists a birational map between

since if $\left(\varphi_{0}(t), \ldots, \varphi_{N}(t)\right)_{t \in D}$ have fixed point then these fixed point are in $X_{0}$ so the set of fixed points of the linear system $\left(\varphi_{0}(t), \ldots, \varphi_{N}(t)\right)$ can be at most a divisor in $X_{0}$, and so has codimension $\geqq 2$ in $X$. So from here we obtain that $\quad{ }_{D_{1}}^{1} \subset \rightarrow \mathbb{P}^{N} \times D$ is a birational map. Even more we will prove that there exists a holomorphic map

$$
\varphi_{0}: x_{0} \rightarrow x_{0}^{1} \hookrightarrow \mathbb{P}^{N} \quad x_{0}^{1}=\pi_{1}^{-1}(0)
$$

which is induced by the birational isomorphism between $X_{0}$ and $\mathrm{X}_{0}^{1}$

Proof: Let $H$ be the closure of the very ample divisor $H *$ that difines $L^{*}$ in $X$. Let $L=0(H)$ and let $L_{0}=L_{\mid X_{0}}$. we will prove that $L_{0}$ gives us

$$
\varphi_{0}: x_{0} \rightarrow \mathrm{x}_{0}^{1} \longrightarrow \mathrm{P}^{\mathrm{N}}
$$

Fist it is easy to see that on $X_{1} \backslash \operatorname{Sing}\left(X_{0}^{1}\right)$ there exists a Kähler metric; this is the restriction of FubliniStudy metric $+d t \otimes d \bar{t}$ on $X_{1} \backslash A, A=\operatorname{sing}\left(X_{0}^{1}\right)$. For each $t \in D^{*}$ the restriction of the imaginary part of this Kähler metric gives the Chern class of $\left.L\right|_{X_{t}}$. Notice that codim $A \geq 2$ in $X^{1}$. Let $\left\{W_{p}\right\}$ be a covering of $X$ such that

$$
i^{\prime}\left(\left(\Sigma g_{i j}^{e}-(t) \cdot d z^{j} \wedge d \bar{z}^{j}+d t \wedge d \bar{E} \| \mid\left(W_{e} \backslash\left(W_{e} \cap A\right)=i \partial \bar{\partial} u_{e}\right.\right.\right.
$$

where $u_{e}$ is a plurihsubharmonic function. From a theorem
about the continuation of plurisubharmonic functions proved in [9] it follows that we can continue $u_{e}$ in $W_{e}$ and we will have

$$
\text { i } \partial \bar{\partial} u_{e} \geq 0
$$

From this fact we get:

For every effective analytic cycle $c \subset X_{0}$ dim $c=k$ we have
(*)

$$
\int_{c} c_{1}\left(L_{0}\right) \wedge \ldots \wedge c_{1}\left(L_{0}\right) \geq 0
$$

(*) is equivalent to the following inequality
(**) $<\mathrm{H}_{0}^{2 \mathrm{n}-\mathrm{k}}, \mathrm{c}>\geq 0$
where $H_{0}=\left.H\right|_{X_{0}}$. (*,*) means that the linear system $\left|\mathrm{H}_{0}\right|$ gives a holomorphic map:

$$
\varphi_{0}: X_{0} \rightarrow \mathrm{P}^{N}
$$

This is Kleinman-Moishezon criterion [14]. So this proves lemma 3.1.1.

> Q.E.D.

Now we can define the family $\pi i{\overline{X_{L}}}_{L} \rightarrow \bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$
 of the fibres of the image of the family ${ }^{2} \tilde{X}_{L} \rightarrow \bar{M}_{(L ;}$
in $\operatorname{sP}^{N_{X}} \bar{M}\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)$

Lemma 3.1.2. Suppose that:
a) $\pi_{1}^{*}: X_{1}^{*} \rightarrow D^{*}$ and $\pi_{2}^{*}: X_{2}^{*} \rightarrow D^{*}$ are two isomorphic families of marked polarized Hyper-Kählerian algebraic manifolds with trivial monodromy.
b) Let $\pi_{1}: x_{1} \rightarrow D_{1}$ and $\pi_{2}: x_{2} \rightarrow D_{2}$ are obtained from $\pi_{1}^{*}: x_{1}^{*} \rightarrow D_{1}^{*}$ and $\pi_{2}^{*}: x_{2}^{*} \rightarrow D_{2}^{*}$ in the following way:

$$
\begin{aligned}
& D_{i}^{*} \hookrightarrow D_{i} \longrightarrow \bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}
\end{aligned}
$$

where $\overline{X_{L}} \rightarrow \bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$ is defined on $p .49$.

Then the two families $X_{1} \rightarrow D_{1}$ and $X_{2} \rightarrow D_{2}$ are biholomorphically isomorphic

$$
x_{1}^{*} \rightarrow x_{2}^{*}
$$

Proof: Let $\varphi:{ }_{D^{*}}^{+}={ }^{t}{ }^{*}$ * be a holomorphic isomorphism between those two marked polarized families of algebraic Hyper-Kahlerian manifolds. From the definition of $\varphi$ it follows that:

1) $\varphi^{*}\left(L_{2}\right)=L_{1}$, where $L_{i}$ is the polarization class on $\pi_{i}^{*}: x_{i}^{*} \rightarrow D^{*}$
2) $\varphi^{*}: H^{2}(X, x) \rightarrow H^{2}(X, z) \quad$ is the identity map.

Since $\underset{t}{X^{*}} \underset{D^{*}}{\longrightarrow} \mathbf{P}^{N} \times D^{*}$ Fubini-Study metric on that $\varphi: \begin{aligned} & \chi_{1}^{*} \rightarrow \chi_{1}^{*} \\ & D_{2}^{*}=D^{*}\end{aligned} \quad$ is induced by a biholomorphic map
 plane section. Let $\Gamma_{\Psi *}$ be the graph of the map $\Psi^{*}$ in $\left(\mathbb{P}^{N_{x D}} D^{*}\right) \times{ }_{D^{*}}\left(P^{N_{x D}}{ }^{*}\right)=P^{N_{\times}} \mathbb{P}^{N_{\times}}{ }_{D^{*}}$. Since $\Psi *$ induces the identity map $H_{*}\left(P^{N}, T\right)$, Bishop criterium and the fact that $\left(I^{N} \times D\right) \times{ }_{D}\left(I^{N} \times D\right)={I P^{N} \times I P^{N} \times D}^{N^{N}}$ is a Káhler manifold we get that $\Gamma_{\Psi *}$ can be prolonged to $\Gamma_{\Psi}$ in $I^{N} \times P^{N} \times D$. The arguments are exactly the same as Proposition 3.1. of [23]. Since $\Psi^{*}$ is given by $0_{\mathbb{I P}^{N}}(1){ }_{0_{D *}} 0_{D^{*}}$ and $\Gamma_{\Psi *}$ can be prolonged to $\Gamma_{\Psi}$ in $\mathbb{P}^{N_{x}} \mathbb{P}^{N_{\times}} D^{N}$ we get that the sections of $\Gamma\left(\mathbb{P}^{N} \times D^{*}, 0_{I P} N(1){ }_{0} 0_{D^{*}} 0_{D *}\right)$ can be prolonged to meromorphic sections of $\Gamma\left(\mathbb{P}^{N}{ }^{N}, O_{I P N}(1){ }_{U_{D}} O_{D}\right)$ can be prolonged to meromorphic section of $\quad \Gamma\left(\mathbb{P}^{N} \times{ }_{D}, 0_{I P} N(1){ }_{O_{D}} 0_{D}\right)$ so this sections can have poles along $\pi^{-1}(0)=\mathbb{P}^{N}$, where

$$
\pi: \mathbb{P}^{N} \times \quad D \rightarrow D
$$

From here we get that if we multiply each section $\varphi_{i}(t)$ by $t^{n_{i}}$ then we will get a section $t^{n_{i}} \varphi_{i} \in \Gamma\left(I^{N} \times D, O_{I P} N \quad{ }_{0}{ }_{0}{ }_{D}{ }^{O_{D}}\right)$ abd even more $t^{n_{1}} \varphi_{i} \neq 0$ on $\pi^{-1}(0)$.

So from here directly lemma 3.1.2. follows, because we can prolong $\Psi *$ to an isomorphism

## The end of the proof of Theorem 3.

From 3.1.2. it follows that $\bar{\pi}: \bar{x}_{L} \rightarrow \bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$ is a unique family up to an isomorphism and so it induces a Hausdorf topology on $\bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$. We know that the period map

$$
\overline{\left.\mathrm{p}: \overline{\mathrm{M}}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right.}\right) \longrightarrow \Omega(L), ~}
$$

is a surjective map. From local Torelli theorem and the way we constructed $\bar{X}_{L_{L}} \rightarrow \bar{M}_{\left(L_{i} ; \gamma_{1}, \ldots, \gamma_{b}\right)}$ ) we get that $\overline{\mathrm{p}}$ is an étale map. Now if we prove that $\overline{\mathrm{p}}$ is a proper map, since

$$
\Omega(L) \approx \operatorname{SO}\left(2, b_{2}-3\right) / S O(2) \times S O\left(b_{2}-3\right)
$$

and so simply connected Theorem will follow. So we need to check that $\bar{p}$ is a proper map. So we need to use the valuative criterium of Grothendieck of a properness., [S6A], so we need to prove that if

$$
x \in \Omega(L)
$$

and if $\varphi: D \rightarrow \Omega(L) \quad$ is a holomorphic map from any disc such that:
a) $\varphi(0)=x$
b) the following diagramm is commutative
(*)

then $\Psi$. can be prolonged to a map $\psi: D \rightarrow \bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$ such that the diagram is commutative:
(**)


If we prove this (which is exactly Grothendeck's criterion of properness) the map $p: \bar{M}\left(L ; \gamma_{1}, \ldots, \gamma_{b}\right) \rightarrow \Omega(L)$ will be an etale and proper. On the other hafd we know that

$$
\Omega(L) \cong S O\left(2, b_{2}-3\right) / S O(2) \quad S O\left(b_{2}-3\right)
$$

is Siegel domain of $I V$ type and so $\Omega(L)$ is a simply connected manifold. From this fact it follows that

$$
\overline{\mathrm{p}}: \overline{\mathrm{M}}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)} \rightarrow \Omega(L)
$$

is a biholomorphic map. This will prove theorem 3. So we need to prove the valuative criterium of Grothendieck, i.e. we showed that the map $\varphi^{*}: D^{*} \rightarrow M_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$ of the commutative diagram can be prolonged to a map

$$
\Psi: D \rightarrow \bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}
$$

so that the diagramm (**) must be commutative one. See [ ]. We must consider two cases:
a) Let $\Psi^{*}: D^{*} \rightarrow \stackrel{+}{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)}$. In this case we have a family $X^{*} \rightarrow D^{*}$ of marked polarized Hyper-Kählerian manifolds. The condition that the map $p: D^{*} \rightarrow \Omega(L)$ can be continued to the map $\mathrm{p}: \mathrm{D} \rightarrow \Omega(\mathrm{L})$ means that the monodromy of the family $X^{*} \rightarrow D^{*}$ is trivial. This follows from theorem 9.5. proved by Griffiths in [13]. Then Theorem 1 says that we
 fibres are non-singular Hyper-Kählerian manifolds. Now lemma 3.1.1. shows that Grothendieck's criterium is fulfilled.
b) Let $\left.\Psi^{*}\left(\Delta^{*}\right) \subset \bar{M}_{\left(L ; \gamma_{1}\right.}, \ldots, \gamma_{b_{2}}\right) \backslash{ }^{M}\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right)$. Since $\left.\bar{M}_{\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right.}\right)^{\prime M}\left(L ; \gamma_{1}, \ldots, \gamma_{b_{2}}\right) \quad$ is a union of $\underset{X^{*}}{ }$ closed complex analytic subsets and the period map $p: D \rightarrow \Omega(L)$ can be continued to a map $p: D \rightarrow \Omega(L)$ it follows that we can find a disc $D_{1}$ such that

1) $\left.D_{1}^{*} \subset M_{\left(L ; \gamma_{1}\right.}, \ldots, \gamma_{b_{2}}\right)$
2) $p: D_{1}^{*} \rightarrow \Omega(L) \quad$ can be continued to a map $p: D_{1} \rightarrow \Omega(L)$ and $\mathrm{p}\left(0_{1}\right)=\mathrm{p}(0)$, where $0_{1} \in \mathrm{D}_{1}$ and $0 \in D$.
3) $D$ and $D_{1}$ are contained in $U$, where $U=p^{-1}(U), U$ is a policynder $\operatorname{dim}_{\mathbb{C}} U=\operatorname{dim}_{\mathbb{C}} \Omega(L)$ such that $p(D) \in U$. Then everything follows from a.

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